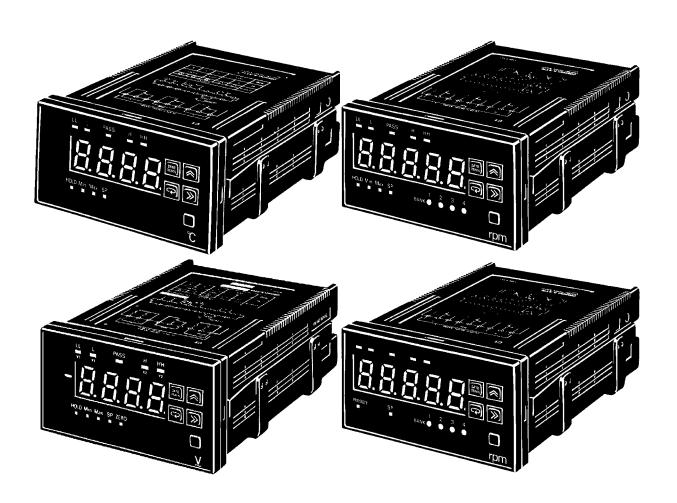
# K3TC/K3TH/K3TR/K3TX Communication Output-type Intelligent Signal Processor

# **Operation Manual**

Revised January 1997



### Notice:

OMRON products are manufactured for use according to proper procedures by a qualified operator and only for the purposes described in this manual.

The following conventions are used to indicate and classify precautions in this manual. Always heed the information provided with them. Failure to heed precautions can result in injury to people or damage to the product.

/ DANGER

Indicates information that, if not heeded, is likely to result in loss of life or serious injury.

**!** WARNING

Indicates information that, if not heeded, could possibly result in loss of life or serious injury.

Indicates information that, if not heeded, could result in relatively serious or minor injury, damage to the product, or faulty operation.

### **OMRON Product References**

All OMRON products are capitalized in this manual. The word "Unit" is also capitalized when it refers to an OMRON product, regardless of whether or not it appears in the proper name of the product.

The abbreviation "Ch," which appears in some displays and on some OMRON products, often means "word" and is abbreviated "Wd" in documentation in this sense.

The abbreviation "PC" means Programmable Controller and is not used as an abbreviation for anything else.

### Visual Aids

The following headings appear in the left column of the manual to help you locate different types of information.

**Note** Indicates information of particular interest for efficient and convenient operation of the product.

1, 2, 3... 1. Indicates lists of one sort or another, such as procedures, checklists, etc.

### © OMRON, 1991

All rights reserved. No part of this publication may be reproduced, stored in a retrieval system, or transmitted, in any form, or by any means, mechanical, electronic, photocopying, recording, or otherwise, without the prior written permission of OMRON.

No patent liability is assumed with respect to the use of the information contained herein. Moreover, because OMRON is constantly striving to improve its high-quality products, the information contained in this manual is subject to change without notice. Every precaution has been taken in the preparation of this manual. Nevertheless, OMRON assumes no responsibility for errors or omissions. Neither is any liability assumed for damages resulting from the use of the information contained in this publication.

# TABLE OF CONTENTS

SEC'	TION 1
Fron	t Panel: Nomenclature and Functions
1-1	Introduction
1-2	$K3TH-T \square 1 \square A-\square \square$ (Basic Model)
1-3	K3TH-T B- (with Set Value LED Display)
1-4	K3TR-B1DA (Basic Model)
1-5	K3TR-□B1□C (with Set Value LED Display)
1-6	K3TC-B1DA (Basic Model)
1-7	K3TX- 2 A- (4-digit Basic Model)
1-8	K3TX- 2 B- (with Set Value LED Display)
1-9	K3TX-□D3□A-□□ (41/2-digit Basic Model)
	TION 2
Kear	Panel Communications Connector/Terminals
2-1	Connector/Terminal Allocations
2-2	Connecting Communications Connectors
SFC'	TION 3
	g the RS-232C/RS-422/RS-485 Models
3-1	Interface Specifications
3-1	Before Applying Power
3-2	Key Operation
3-3 3-4	General RS-232C/RS-422/RS-485 Specifications
3-4	Communications and Error Control
3-5 3-6	Commands and Responses
3-7	Reset Control (Maximum/Minimum Value Reset)
3-8	Set Value Write (Communication/Comparative Output)
3-9	Set Value Write (K3TR/K3TC Communication/Comparative Output)
3-10	•
3-11	Set Value Read (K3TR/K3TC Communication/Comparative Output)
	Maximum/Minimum Read
	Display Value (PV Value) Read
	Model Data Read
3-15	Test
3-16	Undefined Command Error
	End Code List
	Communication Program Example
SEC'	ΓΙΟΝ 4
	g the BCD Output Model
4-1	Connecting BCD Outputs
4-1	Setting before Power Application
4-2	Operations: Front Key Section
4-3 4-4	BCD Programs
4-5	Program Example 1: Connection to a PC
4-6	Program Example 2: Connection to a PC
	endices
	CII List
B Lis	st of Optional Accessories
[nde	X
Kevi	sion History

### About this Manual:

Section 1 introduces the basic features of the K3TC Up/Down Counting Intelligent Signal Processor, K3TH Temperature Intelligent Signal Processor, K3TR Rotation/Pulse Intelligent Signal Processor, and K3TX Intelligent Signal Processor.

Section 2 gives a general description of the K3TC, K3TH, K3TR, and K3TX rear panel communications connector/terminals.

Section 3 provides the interface specifications and basic operational elements required in order to use the RS-232C/RS-422/RS-485 models.

Section 4 provides the basic operational elements required in order to use the BCD output model and gives two programming examples.

Appendix A provides an ASCII list.

Appendix B provides a list of optional accessories.



/! WARNING Failure to read and understand the information provided in this manual may result in personal injury or death, damage to the product, or product failure. Please read each section in its entirety and be sure you understand the information provided in the section and related sections before attempting any of the procedures or operations given.

# **SECTION 1**

# **Front Panel: Nomenclature and Functions**

This section gives a general description of the Intelligent Signal Processor's front panel. Two front panel models are described in this section: K3TC Up/Down Counting Intelligent Signal Processor, K3TH Temperature Intelligent Signal Processor, K3TR Rotation/Pulse Intelligent Signal Processor, and K3TX Intelligent Signal Processor. This description consists of the front panel nomenclature and a brief description of each of its functions.

1-1	Introduction	2
1-2	K3TH-T□1□A-□□ (Basic Model)	3
1-3	K3TH-T□1□B-□□ (with Set Value LED Display)	5
1-4	K3TR-□B1□A (Basic Model)	7
1-5	K3TR-□B1□C (with Set Value LED Display)	Ģ
1-6	K3TC-□B1□A (Basic Model)	11
1-7	K3TX-□□2□A-□□ (4-digit Basic Model)	13
1-8	K3TX-□□2□B-□□ (with Set Value LED Display)	15
1-9	$K3TX-\square D3\square A-\square\square$ (41/2-digit Basic Model)	17

Introduction Section 1-1

### 1-1 Introduction

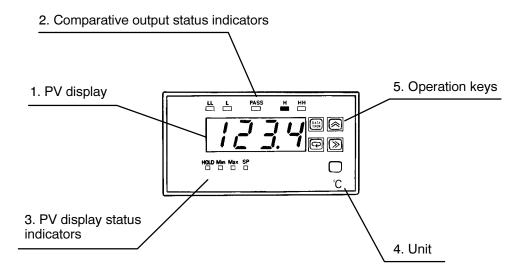
This manual provides the basic operational elements required in order to operate the Communication Output-type Intelligent Signal Processors. Four front panel models, K3TC Up/Down Counting Intelligent Signal Processor, K3TH Temperature Intelligent Signal Processor, K3TR Rotational/Pulse Intelligent Signal Processor, and K3TX Intelligent Signal Processor are described in a general fashion. Depending upon the requirements, one of several connector/terminal types can be selected for use with the Intelligent Signal Processor.

Following the front panel model descriptions, the RS-232C/RS422/RS-485 Model specifications and operation are provided in detail. Included is a communication program example written in N88 BASIC.

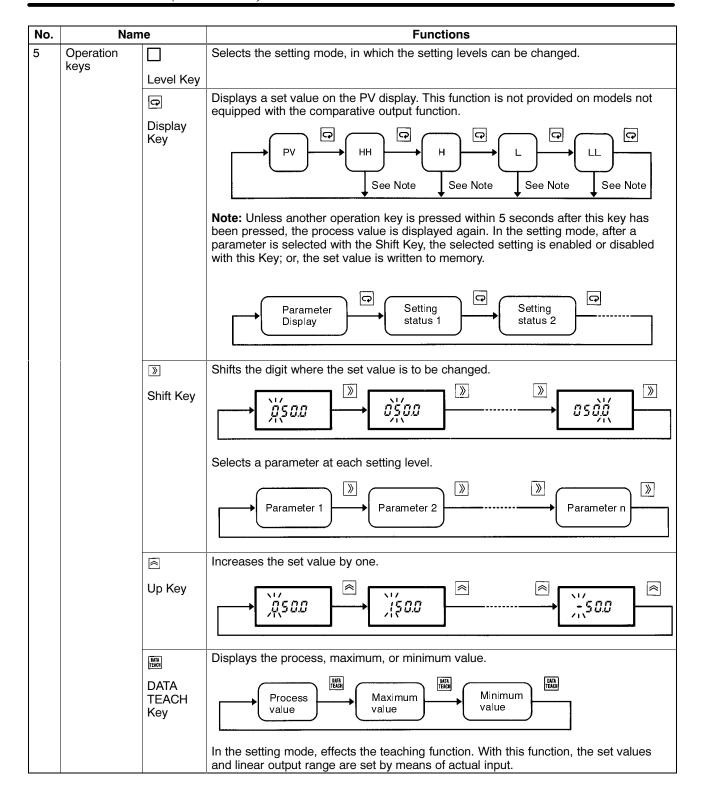
Finally, the BCD Output Model is ideal when connecting directly with a PC or a personal computer. Operational details and two program examples involving connection with a PC are provided.

# 1-2 K3TH-T□1□A-□□ (Basic Model)

The following diagram identifies the major features found on the K3TH Basic Model front panel. The table gives a brief description of the function of each front panel feature.

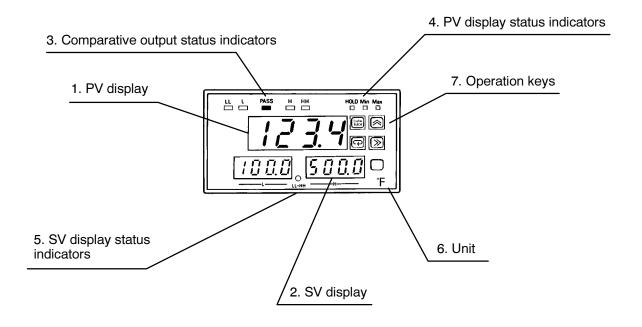


No.	Name		Functions
1.	PV (process value) display		Displays the process, maximum, and minimum values. Also displays set values while the SP indicator is lit. Displays characters indicating the set mode and set values. Displays an error message when an error occurs.
2	Comparative output status indicators	НН	Is lit when HH comparative output status is ON. HH comparative output status turns ON when the measured value exceeds the HH set value. This indicator does not light in models not provided with the comparative output function.
		Н	Is lit when H comparative output status is ON. H comparative output status turns ON when the measured value exceeds the H set value. This indicator does not light in models not provided with the comparative output function.
		L	Is lit when L comparative output status is ON. L comparative output status turns ON when the measured value falls below the L set value. This indicator does not light in models not provided with the comparative output function.
		LL	Is lit when LL comparative output status is ON. LL comparative output status turns ON when the measured value falls below the LL set value. This indicator does not light in models not provided with the comparative output function.
		PASS	Is lit when PASS comparative output status is ON. PASS comparative output status turns ON when all HH, H, L, and LL comparative output status are OFF. This indicator does not light in models not provided with the comparative output function.
3	PV display status indicators	HOLD	Is lit when HOLD input is ON. By turning ON the HOLD terminal on the rear panel, the hold function can be effected.
		Min	Indicates that the value displayed on the PV display is the minimum value. To display the minimum value, use the DATA TEACH Key.
		Max	Indicates that the value displayed on the PV display is the maximum value. To display the maximum value, use the DATA TEACH Key.
		SP	Indicates that the value displayed on the PV display is a set value. To display a set value, use the Display Key. This indicator does not light in models not provided with the comparative output function; in this case, no set value can be displayed with the Display Key.
4	Unit		Attach the appropriate label (use the labels supplied as accessories).

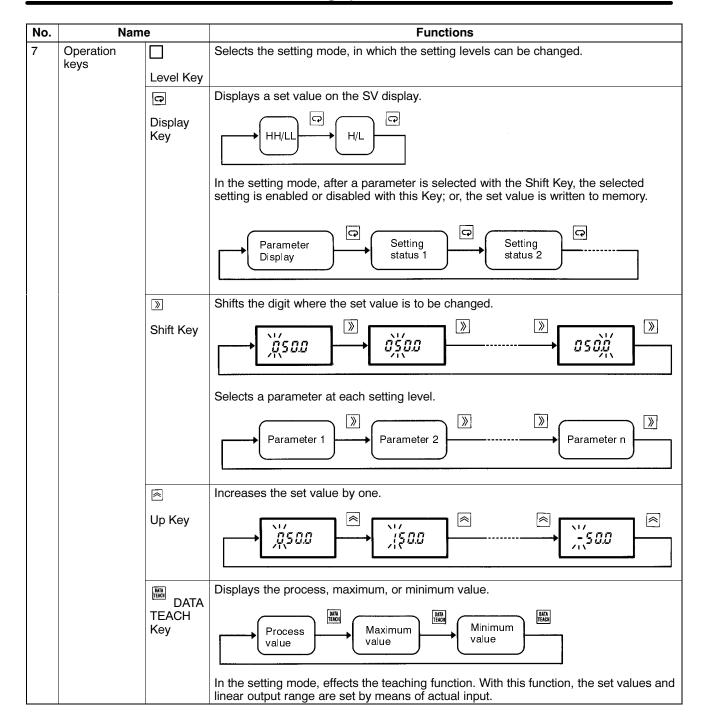


# 1-3 K3TH-T□1□B-□□ (with Set Value LED Display)

The following diagram identifies the major features found on the K3TH with Set Value LED Display front panel. The table gives a brief description of the function of each front panel feature.

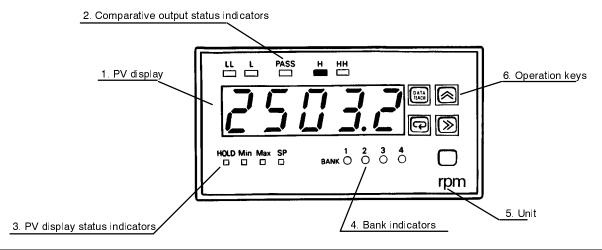


No.	Nam	ie	Functions
1	PV (process value) display		Displays the process, maximum, and minimum values. Displays characters indicating the set mode and set values. Displays an error message when an error occurs.
2	SV (set value)	display	Displays the set value of a comparative output. In setting mode, displays the set parameter.
3	Comparative output status indicators	НН	Is lit when HH comparative output status is ON. HH comparative output status turns ON when the measured value exceeds the HH set value.
		Н	Is lit when H comparative output status is ON. H comparative output status turns ON when the measured value exceeds the H set value.
		L	Is lit when L comparative output status is ON. L comparative output status turns ON when the measured value falls below the L set value.
		LL	Is lit when LL comparative output status is ON. LL comparative output status turns ON when the measured value falls below the LL set value.
		PASS	Is lit when PASS comparative output status is ON. PASS comparative output status turns ON when all HH, H, L, and LL comparative output status are OFF.
4	PV display status indicators	HOLD	Is lit when HOLD input is ON. By turning ON the HOLD terminal on the rear panel, the hold function can be effected.
		Min	Indicates that the value displayed on the PV display is the minimum value. To display the minimum value, use the DATA TEACH Key.
		Max	Indicates that the value displayed on the PV display is the maximum value. To display the maximum value, use the DATA TEACH Key.
5	SV display status indicator		Indicates whether the set values displayed on the SV display is HH and LL, or H and L.
6	Unit		Attach the appropriate label (use the labels supplied as accessories).

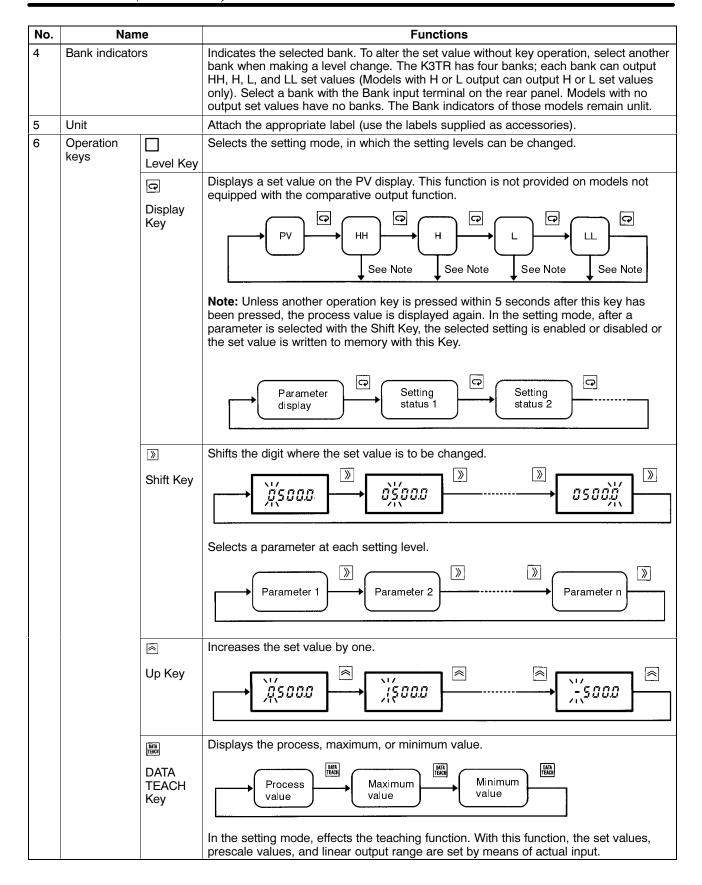


# 1-4 K3TR-□B1□A (Basic Model)

The following diagram identifies the major features found on the K3TR Basic Model front panel. The table gives a brief description of the function of each front panel feature.

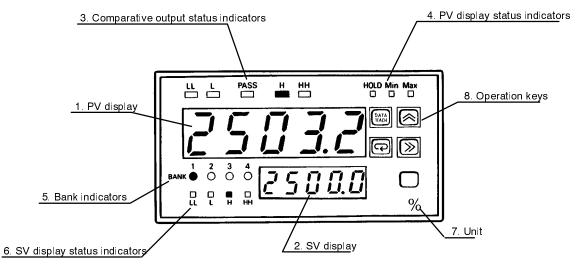


No.	Nam	ie	Functions
1.	PV (process value) display		Displays the process, maximum, and minimum values. Also displays set values while the SP indicator is lit. Displays characters indicating the set mode and set values. Displays an error message when an error occurs.
2	Comparative output status indicators	HH	Is lit when HH comparative output status is ON. HH comparative output status turns ON when the measured value exceeds the HH set value. This indicator does not light in models not provided with the comparative output function.
		Н	Is lit when H comparative output status is ON. H comparative output status turns ON when the measured value exceeds the H set value. This indicator does not light in models not provided with the comparative output function.
		L	Is lit when L comparative output status is ON. L comparative output status turns ON when the measured value falls below the L set value. The L comparative output status turns ON when the measured value exceeds the L set value only when the K3TR is in pulse counting mode (operating mode 12). This is identical to when the H comparative output status turns ON when the measured value exceeds the H set value and HH comparative output status turns ON when the measured value exceeds the HH set value. This indicator does not light in models not provided with the comparative output function.
		LL	Is lit when LL comparative output status is ON. LL comparative output status turns ON when the measured value falls below the LL set value. The LL comparative output status turns ON when the measured value exceeds the LL set value only when the K3TR is in pulse counting mode (operating mode 12). This is identical to when the H comparative output status turns ON when the measured value exceeds the H set value and HH comparative output status turns ON when the measured value exceeds the HH set value. This indicator does not light in models not provided with the comparative output function.
		PASS	Is lit when PASS comparative output status is ON. PASS comparative output status turns ON when all HH, H, L, and LL comparative output status are OFF. This indicator does not light in models not provided with the comparative output function.
3	PV display status indicators	HOLD	Is lit when HOLD input is ON. By turning ON the HOLD terminal on the rear panel, the hold function can be effected.
		Min	Indicates that the value displayed on the PV display is the minimum value. To display the minimum value, use the DATA TEACH Key.
		Max	Indicates that the value displayed on the PV display is the maximum value. To display the maximum value, use the DATA TEACH Key.
		SP	Indicates that the value displayed on the PV display is a set value. To display a set value, use the Display Key. This indicator does not light in models not provided with the comparative output function; in this case, no set value can be displayed with the Display Key.

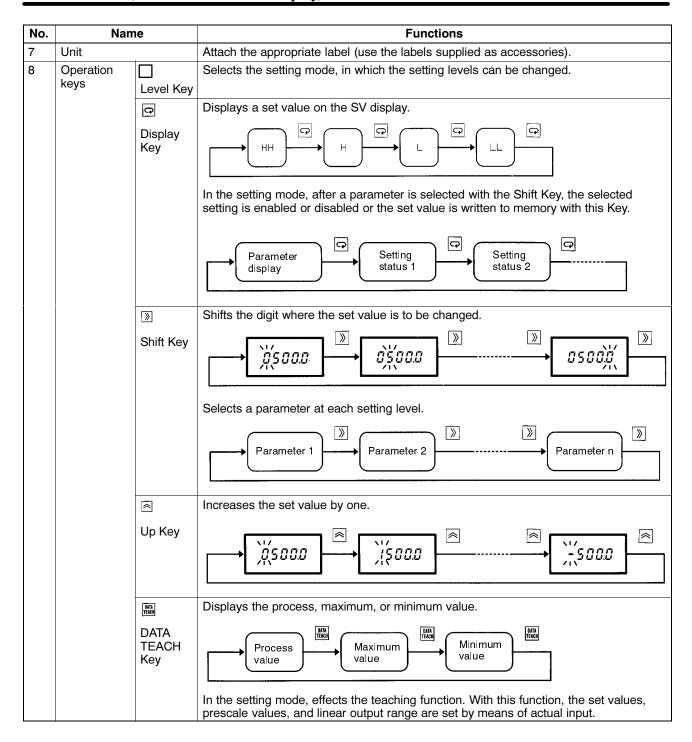


# 1-5 K3TR-□B1□C (with Set Value LED Display)

The following diagram identifies the major features found on the K3TR with Set Value LED Display front panel. The table gives a brief description of the function of each front panel feature.

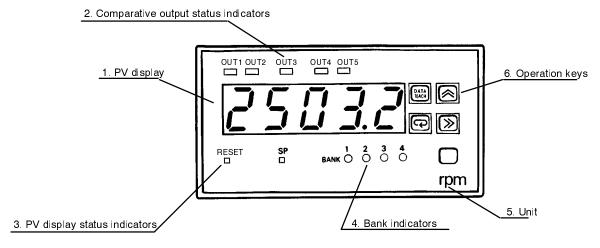


No.	Name		Functions
1	PV (process value) display		Displays the process, maximum, and minimum values. Displays characters indicating the set mode and set values. Displays an error message when an error occurs.
2	SV (set value)	) display	Displays the set value of a comparative output. In setting mode, displays the set parameter.
3	Comparative output status indicators	HH	Is lit when HH comparative output status is ON. HH comparative output status turns ON when the measured value exceeds the HH set value.
		Н	Is lit when H comparative output status is ON. H comparative output status turns ON when the measured value exceeds the H set value.
		L	Is lit when L comparative output status is ON. L comparative output status turns ON when the measured value falls below the L set value. The L comparative output status turns ON when the measured value exceeds the L set value only when the K3TR is in pulse counting mode (operating mode 12). This is identical to when the H comparative output status turns ON when the measured value exceeds the H set value and HH comparative output status turns ON when the measured value exceeds the HH set value.
		LL	Is lit when LL comparative output status is ON. LL comparative output status turns ON when the measured value falls below the LL set value. The LL comparative output status turns ON when the measured value exceeds the LL set value only when the K3TR is in pulse counting mode (operating mode 12). This is identical to when the H comparative output status turns ON when the measured value exceeds the H set value and HH comparative output status turns ON when the measured value exceeds the HH set value.
		PASS	Is lit when PASS comparative output status is ON. PASS comparative output status turns ON when all HH, H, L, and LL comparative output status are OFF.
4	PV display status indicators	HOLD	Is lit when HOLD input is ON. By turning ON the HOLD terminal on the rear panel, the hold function can be effected.
		Min	Indicates that the value displayed on the PV display is the minimum value. To display the minimum value, use the DATA TEACH Key.
		Max	Indicates that the value displayed on the PV display is the maximum value. To display the maximum value, use the DATA TEACH Key.
5	Bank indicator	rs	To alter the set value without key operation, select another bank when making a level change. The K3TR has four banks; each bank can output HH, H, L, and LL set values (Models that have H or L output can output H or L set values only).
6	SV display status indicators		Indicates whether the displayed set value on the SV display is HH, H, L, or LL.

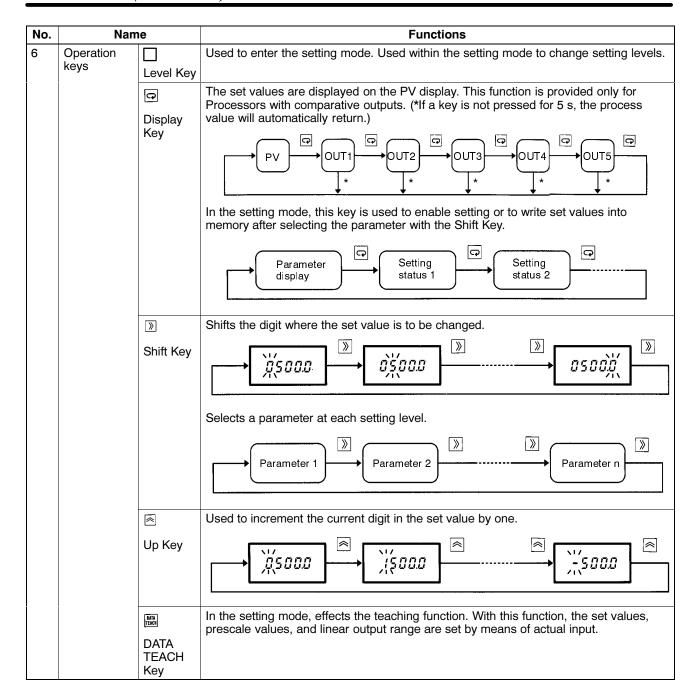


# 1-6 K3TC-□B1□A (Basic Model)

The following diagram identifies the major features found on the K3TC Basic Model front panel. The table gives a brief description of the function of each front panel feature.

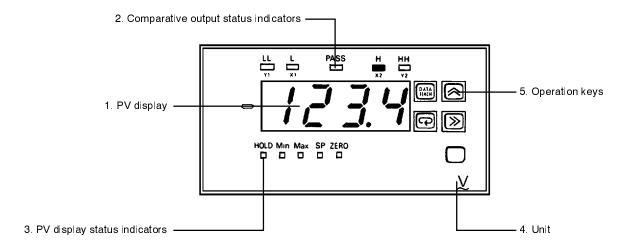


No.	Name	Functions
1.	PV (process value) display	In RUN mode, the PV display indicates the measured value unless the "SP" indicator is lit. When the "SP" indicator is lit in RUN mode, the PV display indicates the comparative set values. In setting mode, the PV display indicates the setting item or set value. If the set value is being displayed, the digit being changed will be flashing. When an error has occurred, the PV display indicates the error message.
2	Comparative output status indicators	These indicators are lit when the corresponding output (1 through 5) is ON. By means of a setting level 3 output parameter setting, it can be selected whether outputs are to be executed when the measured value exceeds the set value or when it is less than the set value.
3	PV display status indicators	The "RESET" indicator is lit when the reset signal is ON. The "SP" indicator is lit when the PV display shows the comparative set value.
4	Bank indicators	The bank indicators, which show which bank number (1 through 4) has been selected, will be lit in the following situations: (1) When there is an Output Board mounted. (2) When the setting level 1 prescale bank parameter is set to ON. (3) When the external control input bank signal is ON.
5	Unit	Attach the appropriate label (use the labels supplied as accessories).

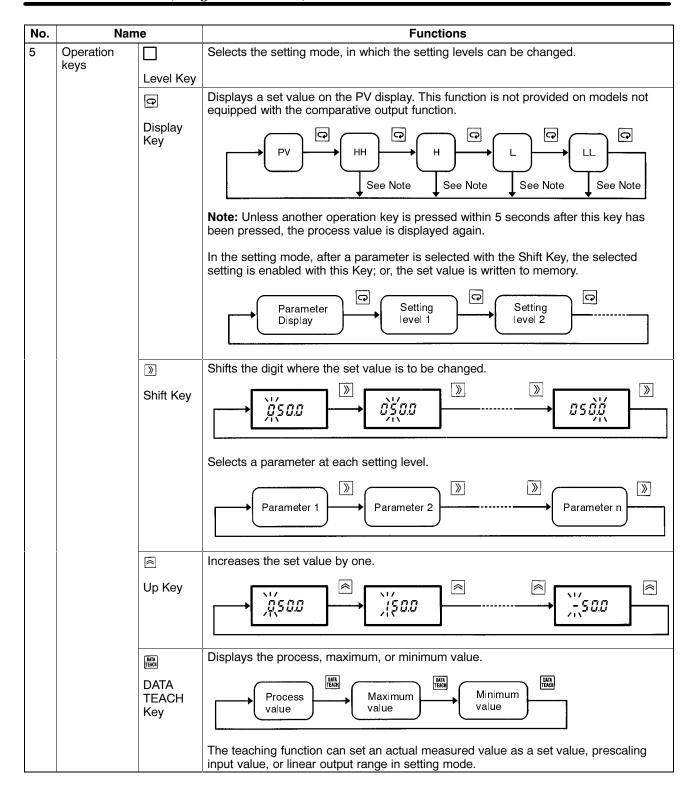


# 1-7 K3TX- 2 A- (4-digit Basic Model)

The following diagram identifies the major features found on the K3TX 4-digit Basic Model front panel. The table gives a brief description of the function of each front panel feature.

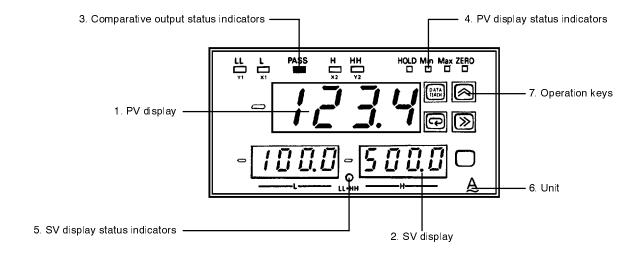


No.	Name		Functions
1.	PV (process v display	alue)	Displays the process, maximum, and minimum values. Also displays set values while the SP indicator is lit. Displays characters indicating the setting mode and set values. Displays an error message when an error occurs.
2	Comparative output status indicators	НН	Is lit when HH comparative output status is ON. HH comparative output status turns ON when the measured value exceeds the HH set value. This indicator does not light in models not provided with the comparative output function.
		Н	Is lit when H comparative output status is ON. H comparative output status turns ON when the measured value exceeds the H set value. This indicator does not light in models not provided with the comparative output function.
		L	Is lit when L comparative output status is ON. L comparative output status turns ON when the measured value falls below the L set value. This indicator does not light in models not provided with the comparative output function.
		LL	Is lit when LL comparative output status is ON. LL comparative output status turns ON when the measured value falls below the LL set value. This indicator does not light in models not provided with the comparative output function.
		PASS	Is lit when PASS comparative output status is ON. PASS comparative output status turns ON when all HH, H, L, and LL comparative output status are OFF. This indicator does not light in models not provided with the comparative output function.
3	PV display status indicators	HOLD	Is lit when HOLD input is ON. By turning ON the HOLD terminal on the rear panel, the hold function can be effected.
		Min	Indicates that the value displayed on the PV display is the minimum value. To display the minimum value, use the DATA TEACH Key.
		Max	Indicates that the value displayed on the PV display is the maximum value. To display the maximum value, use the DATA TEACH Key.
		SP	Indicates that the value displayed on the PV display is a set value. To display a set value, use the Display Key. This indicator does not light in models not provided with the comparative output function; in this case, no set value can be displayed with the Display Key.
		ZERO	Is lit when the forced zero input signal is ON. By turning ON the ZERO terminal on the rear panel, the ZERO shift function can be effected.
4	Unit		Attach the appropriate label (use the labels supplied as accessories).

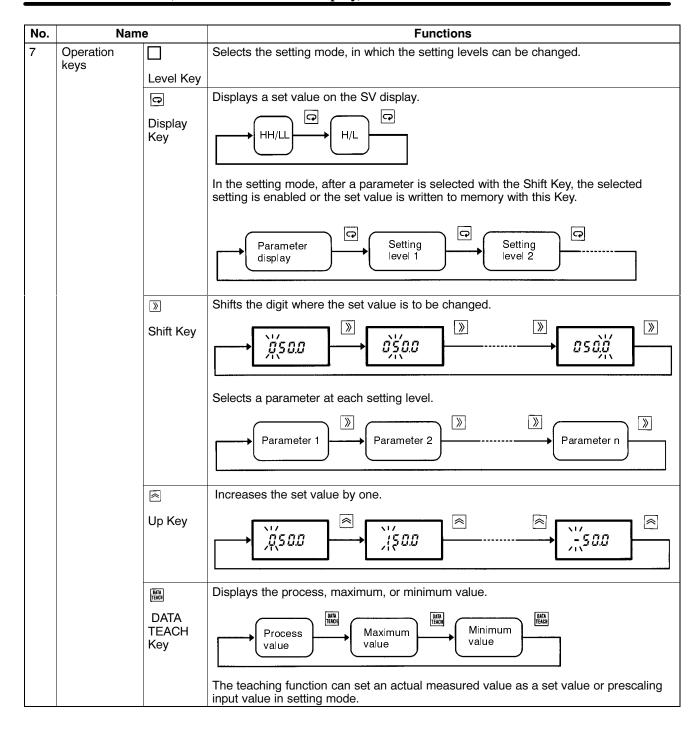


# 1-8 K3TX-□□2□B-□□ (with Set Value LED Display)

The following diagram identifies the major features found on the K3TX with Set Value LED Display front panel. The table gives a brief description of the function of each front panel feature.

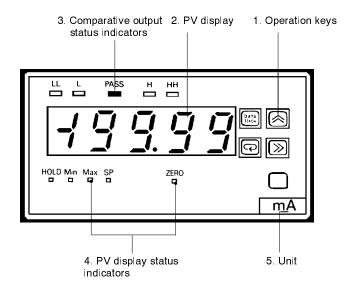


No.	Name		Functions
1	PV (process value) display		Displays the process, maximum, and minimum values. Displays characters indicating the setting mode and set values. Displays an error message when an error occurs.
2	SV (set value)	display	Displays the set value of a comparative output. In setting mode, displays the set parameter.
3	Comparative output status indicators	НН	Is lit when HH comparative output status is ON. HH comparative output status turns ON when the measured value exceeds the HH set value.
		Н	Is lit when H comparative output status is ON. H comparative output status turns ON when the measured value exceeds the H set value.
		L	Is lit when L comparative output status is ON. L comparative output status turns ON when the measured value falls below the L set value.
		LL	Is lit when LL comparative output status is ON. LL comparative output status turns ON when the measured value falls below the LL set value.
		PASS	Is lit when PASS comparative output status is ON. PASS comparative output status turns ON when all HH, H, L, and LL comparative output status are OFF.
4	PV display status indicators	HOLD	Is lit when HOLD input is ON. By turning ON the HOLD terminal on the rear panel, the hold function can be effected.
		Min	Indicates that the value displayed on the PV display is the minimum value. To display the minimum value, use the DATA TEACH Key.
		Max	Indicates that the value displayed on the PV display is the maximum value. To display the maximum value, use the DATA TEACH Key.
		ZERO	Is lit when the forced zero input signal is ON. By turning ON the ZERO terminal on the rear panel, the ZERO shift function can be effected.
5	SV display status indicators		Indicates whether the displayed set value on the SV display is HH and LL or H and L. The SV display is lit when the set values are HH and LL and not lit when the set values are H and L.
6	Unit		Attach the appropriate label (use the labels supplied as accessories).

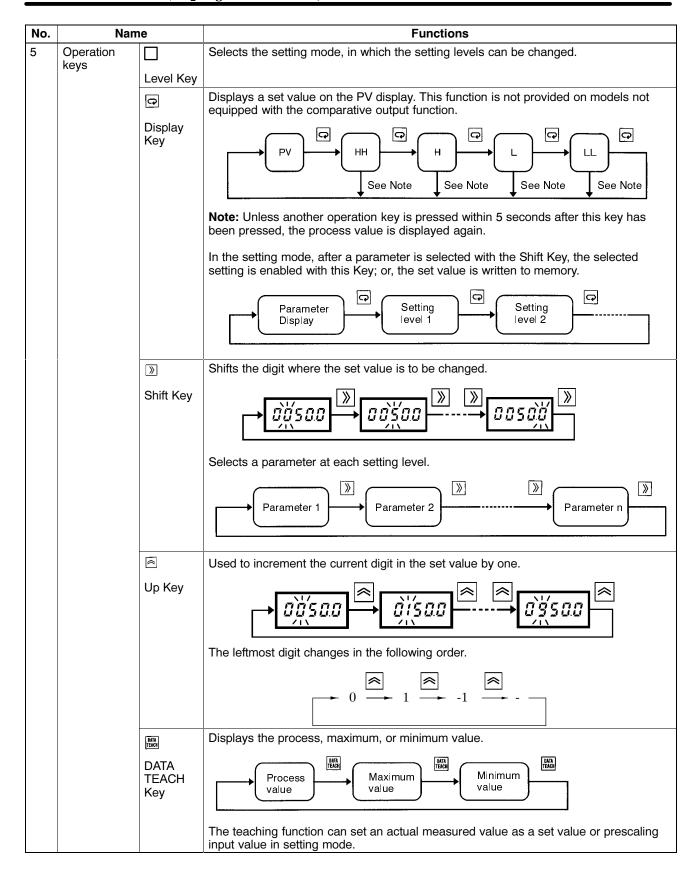


# 1-9 K3TX-□D3□A-□□ (4<sup>1</sup>/<sub>2</sub>-digit Basic Model)

The following diagram identifies the major features found on the K3TX with  $4^{1}/_{2}$ -digit display front panel. The table gives a brief description of the function of each front panel feature.



No.	Name		Functions
1.	PV (process v display	alue)	Displays the process, maximum, and minimum values. Also displays set values while the SP indicator is lit. Displays characters indicating the setting mode and set values. Displays an error message when an error occurs.
2	Comparative output status indicators	HH	Is lit when HH comparative output status is ON. HH comparative output status turns ON when the measured value exceeds the HH set value. This indicator does not light in models not provided with the comparative output function.
		Н	Is lit when H comparative output status is ON. H comparative output status turns ON when the measured value exceeds the H set value. This indicator does not light in models not provided with the comparative output function.
		L	Is lit when L comparative output status is ON. L comparative output status turns ON when the measured value falls below the L set value. This indicator does not light in models not provided with the comparative output function.
		LL	Is lit when LL comparative output status is ON. LL comparative output status turns ON when the measured value falls below the LL set value. This indicator does not light in models not provided with the comparative output function.
		PASS	Is lit when PASS comparative output status is ON. PASS comparative output status turns ON when all HH, H, L, and LL comparative output status are OFF. This indicator does not light in models not provided with the comparative output function.
3	PV display status indicators	HOLD	Is lit when HOLD input is ON. By turning ON the HOLD terminal on the rear panel, the hold function can be effected.
		Min	Indicates that the value displayed on the PV display is the minimum value. To display the minimum value, use the DATA TEACH Key.
		Max	Indicates that the value displayed on the PV display is the maximum value. To display the maximum value, use the DATA TEACH Key.
		SP	Indicates that the value displayed on the PV display is a set value. To display a set value, use the Display Key. This indicator does not light in models not provided with the comparative output function; in this case, no set value can be displayed with the Display Key.
		ZERO	Is lit when the forced zero input signal is ON. By turning ON the ZERO terminal on the rear panel, the ZERO shift function can be effected.
4	Unit		Attach the appropriate label (use the labels supplied as accessories).



# **SECTION 2**

# **Rear Panel Communications Connector/Terminals**

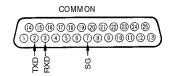
This section gives a general description of the K3TC, K3TH, K3TR, and K3TX rear panel communications connector/terminals.

2-1	Connector/Terminal Allocations	20
2-2	Connecting Communications Connectors	21

## 2-1 Connector/Terminal Allocations

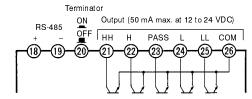
Depending upon the requirements of the host system or peripheral device, the Intelligent Signal Processors can use one of the following outputs:

K31-S1: RS-232C



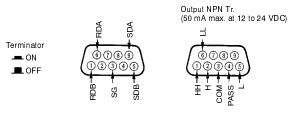
### K31-S2, K31-S5: RS-485

(Terminals 21 to 26 are provided only on the K31-S5.)



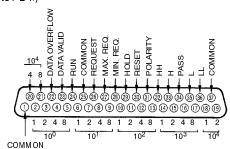
### K31-S3, K31-S6: RS-422

(The right connector is provided only on the K31-S6.)



### K31-B2, K31-B4: BCD (NPN Open Collector)

(Terminals 32 to 36 are provided only on the K31-B4.)



### Note For the K3TC:

HH, H, PASS, L, and LL are replaced by OUT5, OUT4, OUT3, OUT2, and OUT1 respectively.

HOLD is replaced by COMPENSATION.

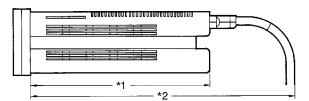
MAX. REQ. and MIN. REQ. are not available.

# 2-2 Connecting Communications Connectors

Connect a host system or peripheral device to the appropriate communication connector; confirm that the system or device conforms to that connector's communication specifications. Before mounting this device, be sure to consider the added depth required by connected cables.

The BCD output type is supplied with a connector.

Plug: XM2A-3701 Hood: XM2S-3711



\*1: Depth of main body from panel (when mounted): 130 mm

\*2: Depth of main body plus D-sub connector (OMRON XM2 or XM4) from panel (when mounted): 200 mm minimum (25/37-pin connector);

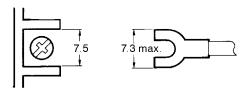
190 mm minimum (9-pin connector)

The following OMRON D-sub connectors are recommended:

25 pin: XM2A-2501 (plug) + XM2S-2511 (hood) 9 pin: XM2A-0901 (plug) + XM2S-0911 (hood)

If using an equivalent connector, make sure that the connector fastening screw is the following metric size:  $M2.6 \times 0.45$ .

When connecting to the terminal-block-type unit, use crimp-style terminals of the appropriate size for M3.5 screws. Securely insert the communication connector from the external system into the communication connector on the body of the Unit. After connection, tighten the screws on either side of the communication connector with a screwdriver. For the appropriate cable length, refer to the respective communication specifications.



# SECTION 3 Using the RS-232C/RS-422/RS-485 Models

This section provides the interface specifications and basic elements required in order to use the RS-232C/RS-422/RS-485 Models. Included in this section is a communication program example written in N88 BASIC.

3-1	Interface Specifications					
	3-1-1	RS-232C	24			
	3-1-2	RS-422	26			
	3-1-3	RS-485	28			
3-2	Before	Applying Power	29			
3-3	Key Op	peration	29			
	3-3-1	Communications Unit Number	30			
	3-3-2	Baud Rate	32			
3-4	General	RS-232C/RS-422/RS-485 Specifications	34			
3-5	Commu	nnications and Error Control	34			
	3-5-1	Communications Control Procedures	34			
	3-5-2	Block Format	34			
	3-5-3	Error Control	35			
3-6	Commands and Responses					
	3-6-1	Command/Response Format Data	36			
	3-6-2	Command List	36			
3-7	Reset C	Control (Maximum/Minimum Value Reset)	37			
3-8	Set Valu	ue Write (Communication/Comparative Output)	37			
3-9	Set Valu	ue Write (K3TR/K3TC Communication/Comparative Output)	38			
3-10	Set Valu	ue Read (Communication/Comparative Output)	39			
3-11		ue Read (K3TR/K3TC Communication/Comparative Output)	40			
3-12	Maxim	um/Minimum Read	41			
3-13	Display	Value (PV Value) Read	42			
3-14	Model 1	Data Read	44			
3-15	Test		46			
3-16	Undefin	ned Command Error	46			
3-17	End Co	de List	46			
3-18	Commu	inication Program Example	47			
	3-18-1	Program Example of RS-232C/RS-422/RS-485 Communication	47			
	3-18-2	Operation Example	51			

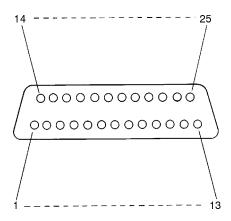
# 3-1 Interface Specifications

# 3-1-1 RS-232C

Electrical characteristics: Conforms to EIA RS-232C

### **Communications Signals**

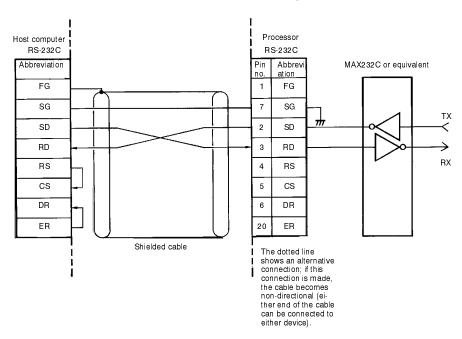
The following information identifies the key input/output signals of the interface.



Signal	Abbreviation	Signal direction	Pin no.
Frame Ground (safety ground)	FG		1
Signal Ground or common return	SG		7
Send Data	SD	Output	2
Receive Data	RD	Input	3
Request To Send	RS	Output	4
Can Send	CS	Input	5
Data Set Ready	DR	Input	6
Data Terminal Ready	ER	Output	20

### **Connection Diagram**

The following example provides information on how the RS-232C Intelligent Signal Processor is to be connected to the host computer.



Synchronization clock: Internal clock

Cable length: 15 m maximum. If increasing the cable length, use

OMRON's RS-232C optical interface (Z3RN).

Applicable connectors: Plug: XM2A-2501 (OMRON) or equivalent

XM4A-2521 (OMRON) or equivalent

Hood: XM2S-2511 (OMRON) or equivalent

Connection method (RS-232C direct connection): 1:1 connection only

The RS-232C Intelligent Signal Processor is configured as DTE (Data Terminal Equipment), therefore no host-side CD (Carrier Detect) can be supported. If the host computer requires a CD signal, support this signal by pulling up from the host side.

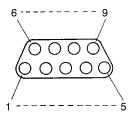
When using this connection, short-circuit RS with CS and DR with ER at the host computer side.

### 3-1-2 RS-422

Electrical characteristics: Conforms to EIA RS-422

### **Communications Signals**

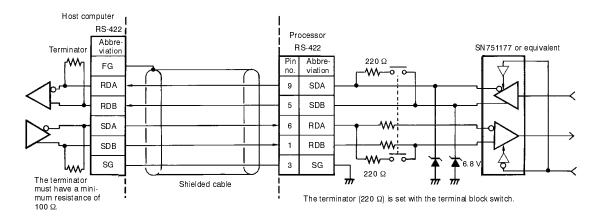
The following information identifies the key input/output signals of the interface.



Signal	Abbreviation	Signal direction	Pin no.	Terminal No.
Send Data A	SDA	Output	9	21
Send Data B	SDB	Output	5	20
Receive Data A	RDA	Input	6	23
Receive Data B	RDB	Input	1	24
Signal Ground	SG		3	22
Frame Ground (safety ground)	FG		7	

### **Connection Diagram**

The following example provides information on how the RS-422 Intelligent Signal Processor is to be connected to the host computer.



Synchronization clock: Internal clock

Total line length: 500 m maximum

Recommended cable: CO-HC-ESV-3P x 7/0.2 (Hirakawa Densen)

Applicable connectors: Plug: XM2A-0901 (OMRON) or equivalent

Hood: XM2S-0911 (OMRON) or equivalent

Connection method (RS-422 connection): Maximum 1:32 connection

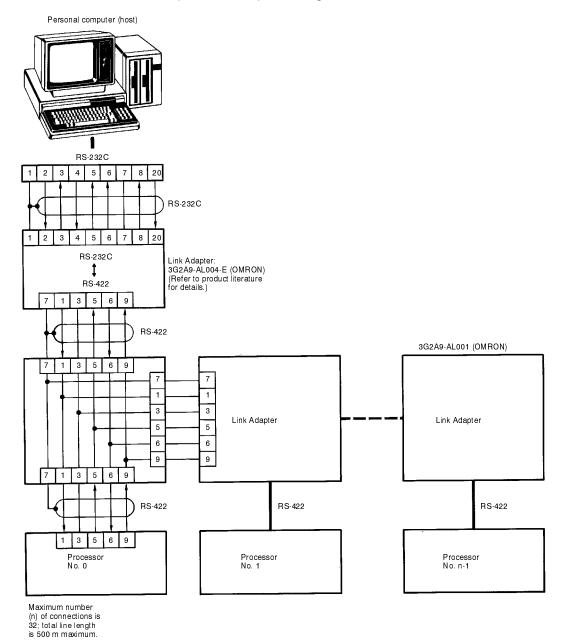
When using this connection:

Turn ON the terminal block switch at the end station.

Turn OFF all other terminal block switches.

### **RS-422 System Example**

The following example shows several Intelligent Signal Processors connected to a personal computer using the RS-422 connection method.

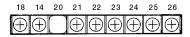


### 3-1-3 RS-485

Electrical characteristics: Conforms to EIA RS-485

### **Communications Signals**

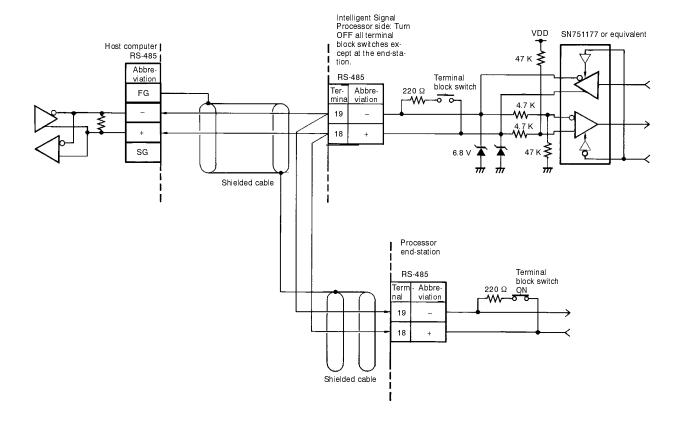
The following information identifies the key input/output signals of the interface.



Signal	Abbreviation	Signal direction	Terminal No.
Inverted output	Negative (-) side	Input/output	19
Non-inverted output	Positive (+) side	Input/output	18

### **Connection Diagram**

The following example provides information on how the RS-485 Intelligent Signal Processor is to be connected to the host computer.



Synchronization clock: Internal clock

Total line length: 500 m maximum

Recommended cable: CO-HC-ESV-3P x 7/0.2 (Hirakawa Densen)

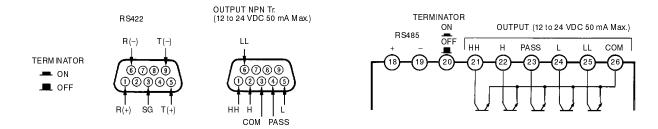
Connection method (RS-485 connection): Maximum 1:32 connection

In this case, the SYSMAC BUS wire type cannot be connected.

# 3-2 Before Applying Power

### **Terminator Designation**

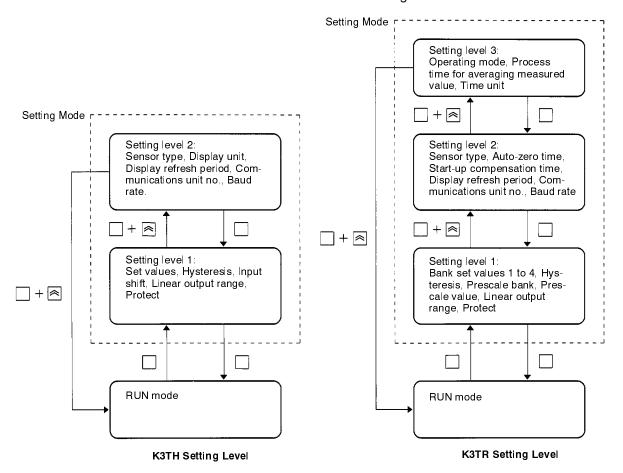
For the RS-422 and RS-485 Models, designate the Intelligent Signal Processor (Processor) located at the right end of the transmission line as an end station by setting the terminator switch of that unit to ON. (End-station designation is not required for the RS-232C Model.)

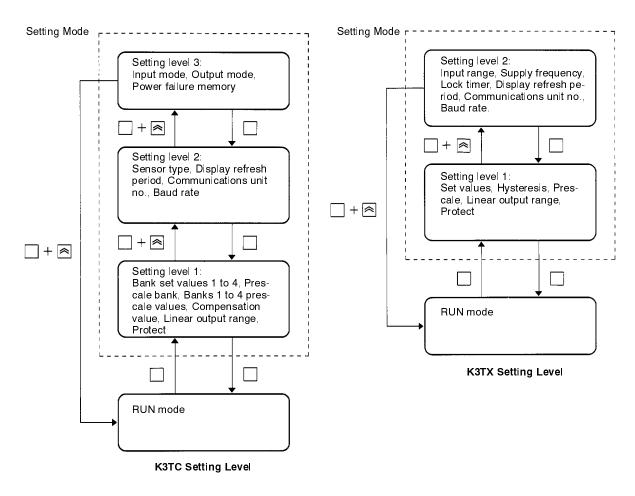


# 3-3 Key Operation

Before attempting communication when using the RS-232C, RS-422, and RS-485 Models, set the baud rate (communication speed) and unit number according to the following procedures; use the keys on the front of the Unit to make the settings. For operation procedures other than the following, refer to the operation manual or instruction manual supplied with the Unit.

This device has two modes: RUN mode, for normal operation; and Setting mode, for initial setting. The Setting mode is further categorized in two levels (three levels for the K3TR/K3TC) according to the frequency of use. Set the baud rate and unit number with Setting level 2.



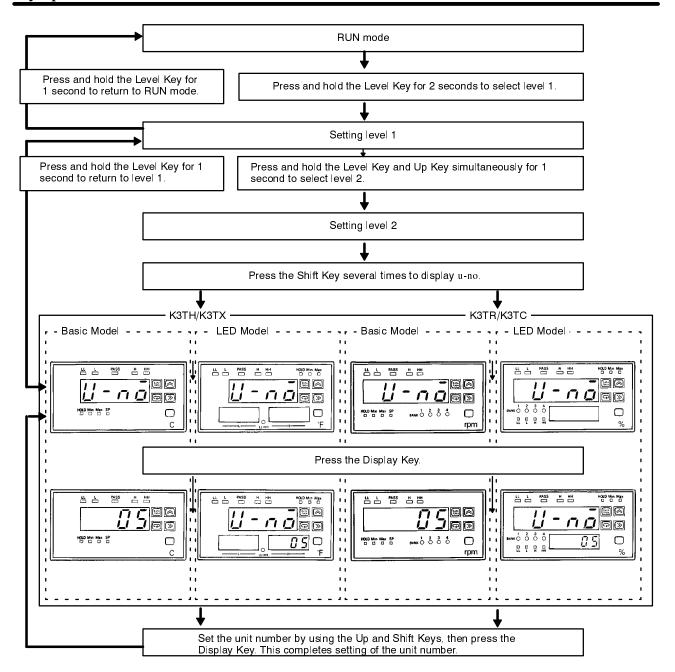


### 3-3-1 Communications Unit Number

The communications unit number is an identification number by which the host computer to which the Intelligent Signal Processor is connected identifies the Intelligent Signal Processor. The Thumbwheel Switches Models are not provided with the communication output function; therefore, communications unit number setting is not required.

In order to set the communications unit number, follow the instructions outlined on the flow diagram (after the table) and set within the following range:

Setting range		
00 to 99		

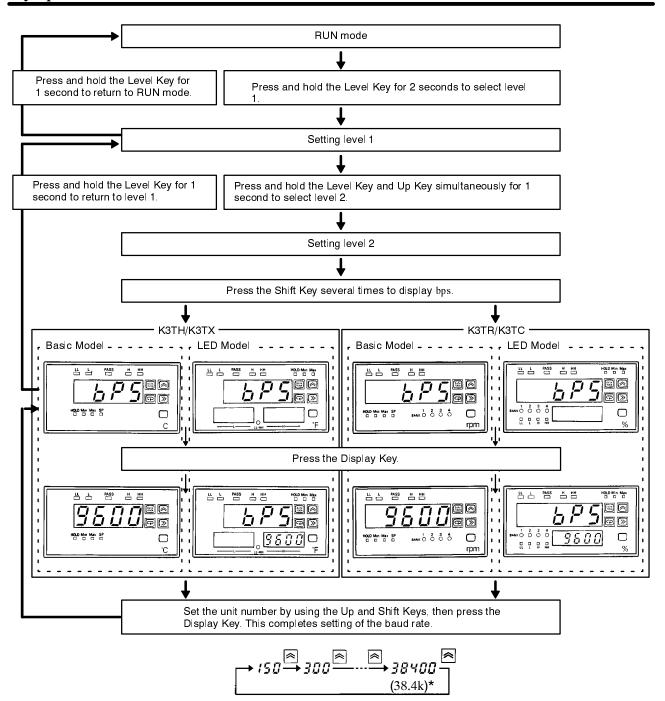


### **Baud Rate** 3-3-2

In order to set the baud rate, follow the instructions outlined in the flow diagram (after the table) and set within the following range:

Setting range			
Display	Meaning		
150	150 bps		
300	300 bps		
600	600 bps		
1200	1,200 bps		
2400	2,400 bps		
4800	4,800 bps		
9600	9,600 bps		
19200 (19.2k) (see Note 1)	19.2k bps		
38400 (38.4k) (see Note 1)	38.4k bps (see Note 2)		

- Note 1. Values in parentheses apply to K3TH and K3TX.
  - 2. Not available with the K3TC.



**Note** Values in parentheses apply to the K3TH and K3TX. Not available with the K3TC.

## 3-4 General RS-232C/RS-422/RS-485 Specifications

Transmission line connection: Multiple point

Communication system: RS-232C/RS-422 (4-wire, half-duplex),

RS-485 (2-wire, half-duplex)

Synchronization system: Start-stop synchronization (2 stop bits)

Communication speed: 150/300/1,200/2,400/4,800/9,600/19,200/

38,400 bps (key-selectable)

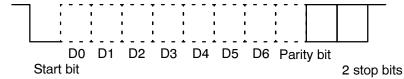
Communication code: ASCII (7 bits)

Error detection: Vertical parity (even) and FCS (frame check

sequence)

Interface: RS-232C/RS-422/RS-485

Start-stop synchronization data configuration:

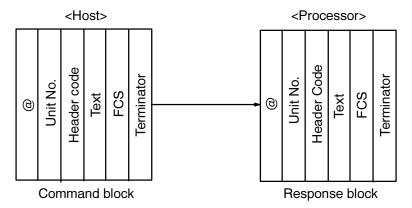


When a personal computer is used as the host system, do not select either 19,200 bps or 38,400 bps as the communication speed.

### 3-5 Communications and Error Control

#### 3-5-1 Communications Control Procedures

The host link procedure for the Intelligent Signal Processor series is conversational, based on PC host link procedures. The prior data transmission right belongs to the host computer, and the data transmission right is shifted with every one block of data transmitted. When a command block is transmitted, a response block is always returned.

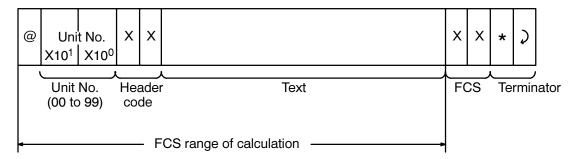


Unit numbers correspond to device numbers in a PC system. When assigning unit numbers for several units, be sure to avoid duplication of the settings.

#### 3-5-2 Block Format

The block transmitted from the host computer is referred to as a command block. The block transmitted from the Processor is referred to as a response block.

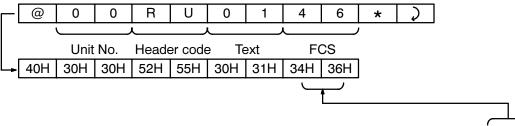
One block begins with the start character "@" and communication address, and ends with the FCS and terminator.



Data characters are in ASCII.

The FCS (frame check sequence) is formed by converting the 8-bit data obtained by converting the exclusive logical sum of @ to the last text character into two ASCII characters. Be sure to attach the FCS to the end of the text.

FCS calculation example:



FCS = 40H  $\oplus$  30H  $\oplus$  30H  $\oplus$  52H  $\oplus$  55H  $\oplus$  30H  $\oplus$  31H = 46H ((Converted into ASCII 34H + 36H) 34H + 36H)

#### 3-5-3 Error Control

With the Processor, responsibility for error recovery rests with the host computer. The host computer controls the following error recovery procedures:

- When execution is impossible (end code) because of an undefined command error (header code) or setting, communication is terminated.
- If an error other than as described in 1 above occurs, a retry operation (retransmission of the same command block) is executed.
- If no response block is returned within 5 seconds from the command block retransmission, an error is assumed and a retry operation is executed.
- If an error occurs after three retry operations, communication is terminated.
- Note that when a Processor is connected to a system currently in use, the host computer of that system executes an error recovery operation.

The following error detection is performed at the Processor:

- 1, 2, 3... 1. Character check (check of every character)
  - Vertical parity check (even parity). Exclusive logical sum (EOR) check for each character.
  - Frame check. If a "0" is detected at the stop bit position, it is assumed that an error has occurred during communication.
  - Overrun check. Overrun occurs when the next character is received while the current character is being processed.
  - 2. Block check (check of each block)
  - Format check. Command format construction is checked.
  - Registration data check. Check of numerical range of numbers such as unit number and bank number.

• FCS check. Exclusive logical sumcheck of @ to the last text character.

If the above checks detect that an error has occurred during communication, error recovery control is requested at the host computer by the response block end code. Note, however, that when it is determined that the communication address is different through the registration data check, no response block is transmitted.

## 3-6 Commands and Responses

## 3-6-1 Command/Response Format Data

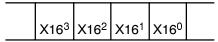
The hexadecimal data and decimal data relevant to command format and response format must be converted into ASCII.

(Example)

Hexadecimal data: \$F -> \$46 Decimal data: 8 -> \$38

Hereafter, hexadecimal data and decimal data in command/response format are expressed as follows:

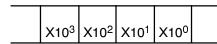
#### Hexadecimal Data



X16<sup>3</sup> through X16<sup>0</sup> mean hexadecimal data.

Therefore, the numbers to be processed are \$0(0000) through \$F(1111).

#### Decimal Data



X10<sup>3</sup> through X10<sup>0</sup> mean hexadecimal data.

Therefore, the numbers to be processed are \$0(0000) through \$9(1001).

#### 3-6-2 Command List

Header code	RU	JN mode	Test mode	Setting mode	Name
	RUN During change of setting				
KR	Yes	Yes	Yes		Reset control (maximum/minimum value resetting)
W%	Yes				Set value write (See Note 1)
W#	Yes				Set value write (only with bank) (See Note 2)
R%	Yes		Yes		Set value read (See Note 1)
R#	Yes		Yes		Set value read (only with bank) (See Note 2)
RH	Yes	Yes			Hold data read (See Note 3)
RX	Yes	Yes	Yes		Display value (PV) read
RU	Yes	Yes	Yes		Model data read
TS	Yes	Yes	Yes	Yes	Test
IC					Undefined command error

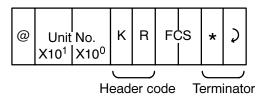
- **Note** 1. Effective only in communication plus comparative output type (special model).
  - 2. Effective only in K3TR and K3TC communication plus comparative output type (special model).
  - 3. Not effective in K3TC.

## 3-7 Reset Control (Maximum/Minimum Value Reset)

The same operation resulting from input to the reset terminal is executed through communication.

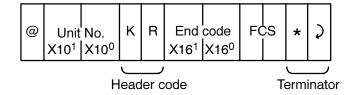
The reset control for the K3TC functions as a reset for the measured values.

#### **Command Format**



#### **Response Format**

Response at normal end. End code: "00"

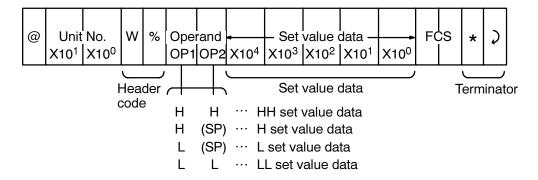


When this command ends normally, a reset is performed.

## 3-8 Set Value Write (Communication/Comparative Output)

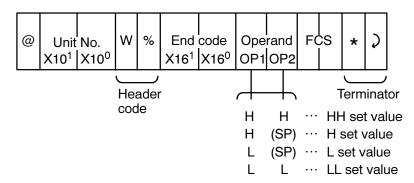
This set value write is effective only in special models with communication and comparative output. The set values (HH, H, L, and LL) are written individually.

#### **Command Format**



#### **Response Format**

Response at normal end. End code: "00"



End code when error occurs:

- In non-comparative output type: End code is "16" (without corresponding command).
- In comparative output type without corresponding set value: End code is "22" (without corresponding memory).
- When set value is changed in RUN mode: End code is "0D" (not executable due to change of setting in RUN mode).

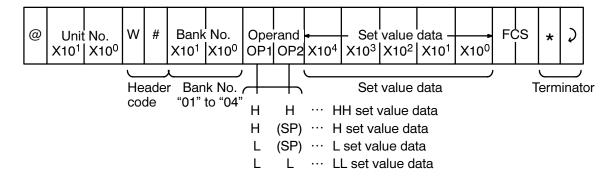
**Note** Set value is expressed in five figures of ASCII. Negative sign is represented by "F" at the position of the X10<sup>4</sup> digit.

# 3-9 Set Value Write (K3TR/K3TC Communication/Comparative Output)

This set value write is effective only in special models with K3TR communication and comparative output. The set values (HH, H, L, and LL) of the banks not in use are written individually. Other set values (HH, H, L, and LL) are written individually.

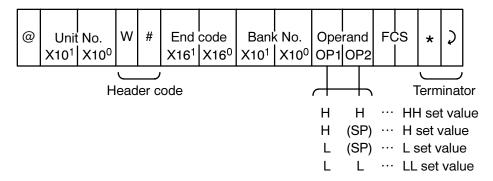
Refer to the following Note 2 for K3TC operands.

#### **Command Format**



#### **Response Format**

Response at normal end. End code: "00"

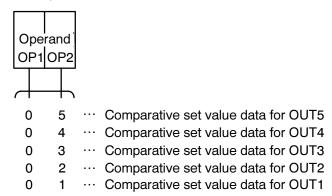


End code when error occurs:

- In non-comparative output type: End code is "16" (without corresponding command).
- In comparative output type without corresponding set value: End code is "22" (without corresponding memory).
- When set value is changed in RUN mode: End code is "0D" (not executable due to change of setting in RUN mode).
- 1. Set value is expressed in five figures of ASCII. Negative sign is represented by "F" at the position of the X10<sup>4</sup> digit.

Note

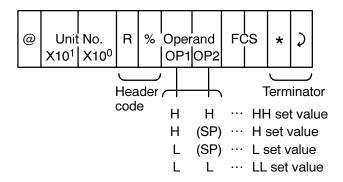
2. Comparative operands for the K3TC are as follows:



## 3-10 Set Value Read (Communication/Comparative Output)

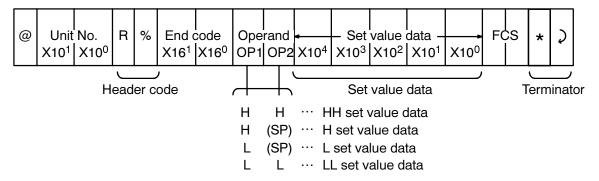
This set value read is effective only in special models with communication and comparative output. The set values (HH, H, L, and LL) are read individually.

#### **Command Format**

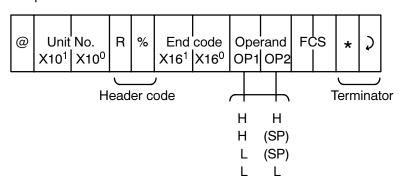


#### **Response Format**

Response at normal end. End code: "00"



Response format when an error occurs:



End code when error occurs:

- In non-comparative output type: End code is "16" (without corresponding command).
- In comparative output type without corresponding set value: End code is "22" (without corresponding memory).
- When set value is changed in RUN mode: End code is "0D" (not executable due to change of setting in RUN mode).

Note

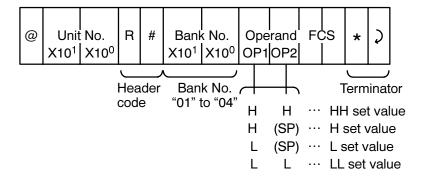
Set value is expressed in five figures of ASCII. Negative sign is represented by "F" at the position of the X10<sup>4</sup> digit.

# 3-11 Set Value Read (K3TR/K3TC Communication/Comparative Output)

This set value read is effective only in models with RS-422/485 capability,  $T_R$  comparative output, and bank function, and special models with K3TR communication and comparative output. The set values (HH, H, L, and LL) of the banks not in use are read individually.

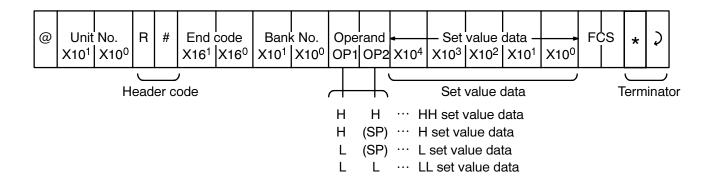
Refer to the following Note 2 for K3TC operands.

#### **Command Format**

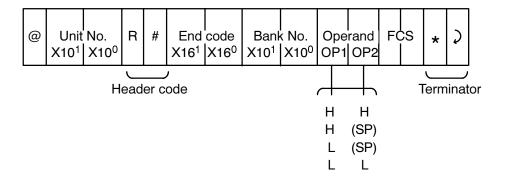


#### **Response Format**

Response at normal end. End code: "00"

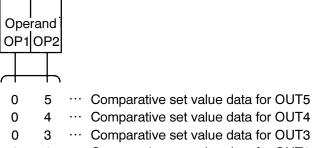


Response format when an error occurs:



End code when error occurs:

- In non-comparative output type: End code is "16" (without corresponding command).
- In comparative output type without corresponding set value: End code is "22" (without corresponding memory).
- When set value is changed in RUN mode: End code is "0D" (not executable due to change of setting in RUN mode).
- 1. Set value is expressed in five figures of ASCII. Negative sign is represented by "F" at the position of the X10<sup>4</sup> digit.
- 2. The comparative operands for the K3TC are as follows:



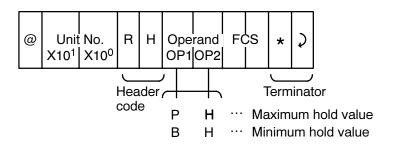
0 3 ··· Comparative set value data for OUT3
0 2 ··· Comparative set value data for OUT2
0 1 ··· Comparative set value data for OUT1

## 3-12 Maximum/Minimum Read

Reads maximum/minimum hold data (maximum/minimum values).

This command is not effective in the K3TC.

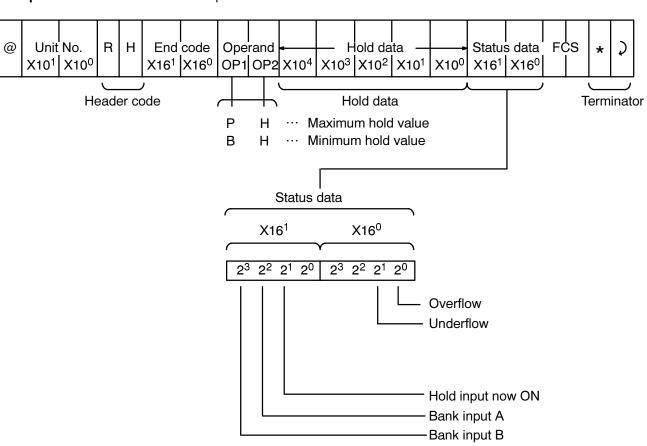
#### **Command Format**



Note

#### **Response Format**

Response at normal end. End code: "00"

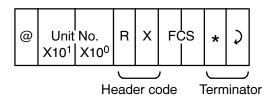


Hold data is expressed in five figures of ASCII. Negative value is indicated by "F" at the position of the  $\rm X10^4$  digit.

# 3-13 Display Value (PV Value) Read

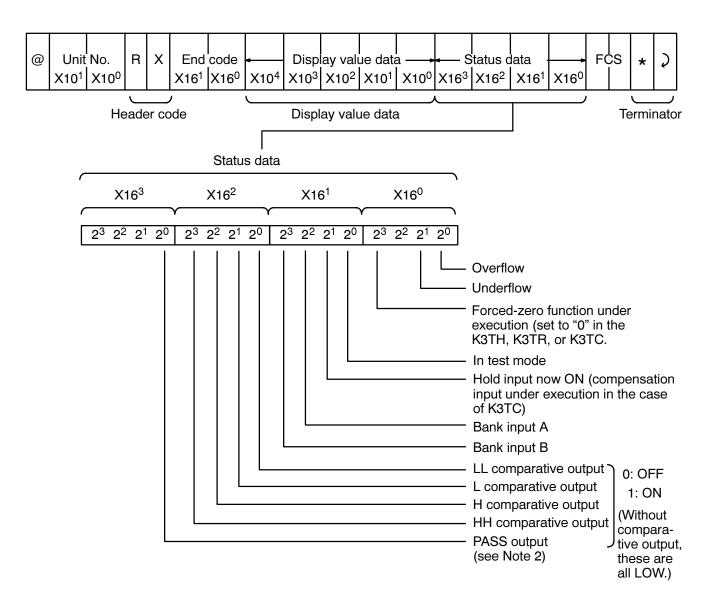
Reads display value (PV value).

#### **Command Format**



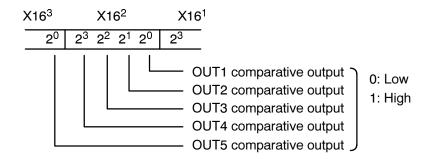
#### **Response Format**

Response at normal end. End code: "00"



Note

- 1. Display value is expressed in five figures of ASCII. Negative sign is represented by "F" at the position of the X10<sup>4</sup> digit.
- 2. The comparative outputs of K3TC status data are as follows:

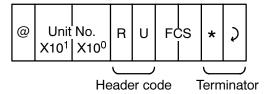


Specifications Section 3-14

# 3-14 Model Data Read

Reads model data.

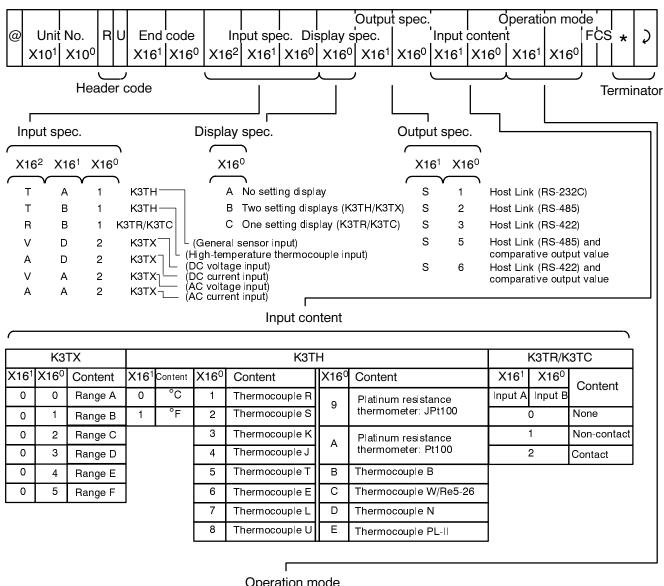
#### **Command Format**



Section 3-14 **Specifications** 

#### **Response Format**

Response at normal end. End code: "00"



Operation mode

/	K3TH/K3TX K3TR K3TC												
K31H	/K31X					K3TF	(					K3T	C
X16 <sup>1</sup>	X16 <sup>0</sup>	X16 <sup>1</sup>	X16 <sup>0</sup>	Content	X16 <sup>1</sup>	X16 <sup>0</sup>	Content	X16 <sup>1</sup>	X16 <sup>0</sup>	Content	X16 <sup>1</sup>	X16 <sup>0</sup>	Content
0	0	0	1	Rotational/ circ. speed	0	5	Flow rate ratio	0	9	Elapsed time	U	В	Individual inputs
		0	2	Absolute ratio	0	6	Linear speed	1	0	Length mea- surement	U	С	Phase differ- ence inputs
		0	3	Error ratio	0	7	Cycle	1	1	Interval			
		0	4	Rotational difference	0	8	Time dif- ference	1	2	Pulse counting			
								1	3	Passing time			

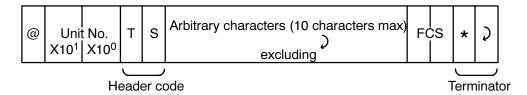
The command content is expressed in ASCII.

End Code List Section 3-17

## 3-15 Test

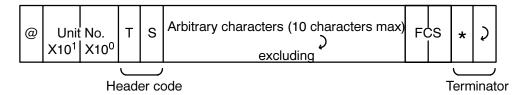
One block of data (with FCS) sent from the host computer is returned without altering anything.

#### **Command Format**



#### **Response Format**

Response at normal end. End code: "00"

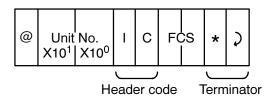


## 3-16 Undefined Command Error

The following response is returned when a command header code cannot be decoded.

#### **Response Format**

Response at normal end. End code: "00"



## 3-17 End Code List

End code		Contents					
x 16 <sup>1</sup>	x 16 <sup>0</sup>						
0	0	Normal end					
0	4	Address over (data overflow)					
0	В	Not executable because of setting mode					
0	С	Not executable because of test mode					
0	D	Not executable because of setting change in RUN mode					
1	0	Parity error					
1	1	Framing error					
1	2	Overrun error					
1	3	FCS error					
1	4	Format error (parameter length error, parameter error, data code error, data length error)					
1	6	No corresponding command					
2	0	Not executable due to sensor failure					
2	1	Not executable due to Processor failure					
2	2	No corresponding memory					

Priority of the errors is as follows:

Unit No. incorrect -> Header code undefined -> New Processor failure -> New Processor mode -> Sensor failure -> Parity error -> Framing error -> Overrun error -> FCS error -> Format error

## 3-18 Communication Program Example

### 3-18-1 Program Example of RS-232C/RS-422/RS-485 Communication

In this program, when inputting transmission data in command format from a computer keyboard, data returned from the Processor that conforms to the response format is displayed on the computer screen. Input the data to be transmitted from the start character "@" to the last piece of text data. After data input, FCS is calculated and transmitted with a terminator. If this program is not executed correctly, there will be an error in the transmission section; check the connection of communication cables, etc.

(This program is written in N88 BASIC. An NEC PC-9801 personal computer is used as the host system.)

```
1000 '*************************
1010 '*
                  : Processor TUSHIN for PC-9801 *
        PROGRAM
1020 '*
        VERSION
                  : 1.12
                            191.1.24
1030 '*
        Copyright (C) 1991 OMRON Corporation
1040 /**********************
1050 '*****************************
1060 '*
        <Main processing>
1070 '************************
1080 *MATN
1090 GOSUB *INIT
                                <Initial setting>
1100 GOSUB *MDAT
                                <Transmission data formation>
                                <Communication execution>
1110 GOSUB *COMM
1120 GOSUB *DISP
                                <Display processing>
1130 GOSUB *QUIT
                                <End processing>
1140 IF FRG=0 THEN GOTO 1170
                                End judgment
1150 CLS
                                Clear screen
1160 GOTO 1100
                                Repeat jump
1170 END
1180 *****************************
        <Initial setting>
1200 /***********************
1210 *INIT
1220 CLS
                                Clear screen
1230 TIM=1000
                                Data reception wait time setting
1240 LMT=10
                                Retry frequency setting
1250 DIM NGM$(LMT-1)
                                NG data storage in memory
1260 PRE$="@00RU"
                                Default command
```

```
1270 TRM$="*"+CHR$(13)
                                  Terminator definition
1280 NG1$="NO RESPONSE"
                                  NG data definition
1290 NG2$="END CODE:"
1300 NG3$="FCS ERROR "
1310 RETURN
1320 /*****************************
1330 '* <Transmission data formation>
1340 '************************
1350 *MDAT
1360 SEND$=""
                                  Default transmission data
1370 LOCATE 0,0
                                  Display allocation
1380 PRINT "SEND DATA: ";
                                  Transmission data input display
1390 IN$=INKEY$
                                  Transmission command input
1400 PRINT IN$;
                                  Transmission command display
1410 IF IN$=CHR$(13) GOTO 1440
                                  Transmission command determination
1420 SEND$=SEND$+IN$
                                  Transmission command formation
1430 GOTO 1390
1440 IF SEND$="" THEN SEND$=PRE$
                                  Transmission data determination
1450 DUMY$=SEND$
1460 GOSUB *FCS
                                  FCS calculation
1470 SEND$=SEND$+FCS$+TRM$
                                  <Transmission data formation>
1480 LOCATE 0,0
                                  Display allocation
1490 PRINT "SEND DATA: "; SEND$"
                                  Transmission data display
1500 RETURN
1510 '***************************
1520 '* <Communication execution>
1530 *******************************
1540 *COMM
1550 NG=0
                                  Clear retry counter
1560 *RETRY
1570 CNT=0
                                  Clear reception wait time
1580 REC=0
                                  Clear reception end flag
1590 RESP$=""
                                  Clear reception data
                                  Transmission port setting
1600 OPEN "COM:E73"AS #1
1610 PRINT #1, SEND$;
                                  Data transmission
1620 WHILE (CNT<TIM AND REC=0)
                                  (Waiting for reception)
1630 IF LOC(1)=0 THEN *SKIP
                                  Received data presence/absence judgment
1640 DUMY$=INPUT$(LOC(1),#1)
                                  Received data acceptance
1650 RESP$=RESP$+DUMY$
                                  Terminator check
1660 CHK$=RIGHT$(RESP$,2)
1670 IF CHK$=TRM$ THEN REC=1
```

```
1680 *SKIP
1690 CNT=CNT+1
                              Reception wait time progression
1700 WEND
1710 CLOSE #1
                              Close transmission port
1720 GOSUB *RESP.CHK
                              Response check
1730 IF CHK<>0 THEN RETRY
                              Retry execution
1740 RETURN
1750 /***************************
1760 '* <Display processing>
1780 *DISP
1790 LOCATE 0,1
                              Display allocation
1800 PRINT "RESPONSE : "; RESP$
                              Received data display
1810 IF NG=0 THEN *DISP.END
                              NG data display
1820 FOR I=1 TO NG
1830 PRINT "TRY"; I; "=> "; NGM$(I-1) '
1840 NEXT
1850 *DISP.END
1860 RETURN
1870 '***************************
1880 '* <End processing>
1890 ****************************
1900 *QUIT
1910 FRG=0
                              Flag clearing
1920 LOCATE 25,3
                              Display allocation
1930 PRINT "To repeat, press RETURN."
1940 CHNG$=INKEY$
                              RETURN Key input
1950 IF CHNG$=CHR$(13) THEN FRG=1
                              Return judgment
1960 IF CHNG$="" THEN GOTO 1940
1970 RETURN
1980 *****************************
1990 '* Display allocation
2000 '************************
2010 *FCS
2020 FCS=0
                              FCS clearing
2030 FOR I=1 TO LEN(DUMY$)
2040 FCS=FCS XOR ASC(MID$(DUMY$,I,1) '
2050 NEXT
2060 FCS$=RIGHT$("0"+HEX$(FCS),2) FCS HEX conversion
2070 RETURN
```

2090 '* Response check	*
2100 '*************	******
2110 *RESP.CHK	
2120 CHK=1	When no response occurs
2130 IF REC=0 THEN *RESP.ER	CHK = 1
2140 CDE\$=MID\$(RESP\$,6,2)	,
2150 CHK=2	When no normal end occurs
2160 CDF\$=MID\$(RESP\$,4,2)	CHK = 2
2170 IF CDF\$="TS" THEN GOTO 21	90 Test command check
2180 IF CDE\$<>"00" THEN *RESP.	ER '
2190 CHK=0	,
2200 GOSUB *FCS.CHK	FCS check
2210 IF CHK=0 THEN *CHK.END	Normal end
2220 *RESP.ER	,
2230 IF CHK=1 THEN NGM\$(NG)=NG	1\$ NG data storage
2240 IF CHK=2 THEN NGM\$(NG)=NG	2\$+CDE\$ '
2250 IF CHK=3 THEN NGM\$(NG)=NG	3\$ '
2260 NG=NG+1	NG frequency progression
2270 IF NG=LMT THEN CHK=0	Retry end
2280 *CHK.END	,
2290 RETURN	
2300 '************	******
2310 '* FCS check	*
2320 /*************	******
2330 *FCS.CHK	
2340 LENGTH=LEN(RESP\$)-4	Obtain range of calculation
2350 DUMY\$=LEFT\$(RESP\$,LENGTH)	,
2360 GOSUB *FCS	FCS calculation
2370 RECFCS\$=MID\$(RESP\$,LENGTH	+1,2) When FCS error occurs
2380 IF FCS\$<>RECFCS\$ THEN CHK	=3 CHK = 3
2390 RETURN	

## 3-18-2 Operation Example

The following is an execution example of the previous program:

Bold characters represents operation and the carriage return symbol represents the RETURN Key. This program cannot execute transmission normally unless the initial transmission settings of the personal computer are: even parity, 7 bits, 2 stop bits, and the same baud rate as the Processor. If the connectors are not properly connected, the program may stop halfway.

```
RUN )
SEND DATA: )
RESPONSE: @00RU00TA1BS10500 FCS *
(If only the RETURN Key is pressed when inputting data, the RU command is transmitted for unit no. 00.)
```

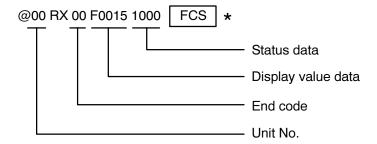
### RUN 🕽

```
SEND DATA: @00RX )

RESPONSE: @00RX00F00151000 FCS *

(Unit no. 00 display value is read.)
```

Response is as follows:



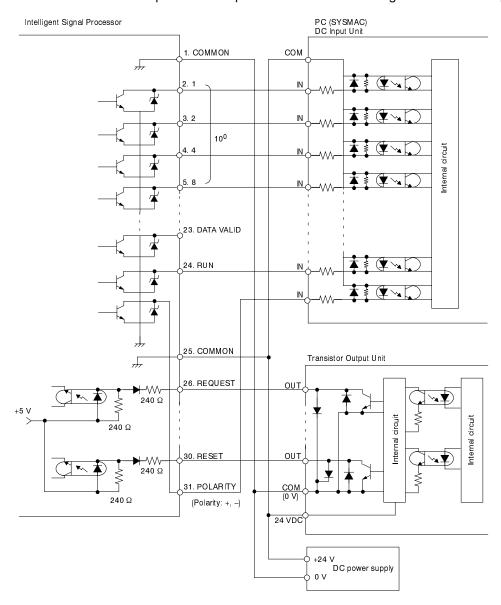
# SECTION 4 Using the BCD Output Model

This section provides the basic operational elements required in order to use the BCD output model. Included in this section is a PC connection example. Two program examples are also given.

4-1	Connec	cting BCD Outputs	54						
4-2	Setting before Power Application								
4-3	Operations: Front Key Section								
4-4	BCD P	rograms	58						
4-5	Program	m Example 1: Connection to a PC	59						
	4-5-1	Explanation of Operation	59						
	4-5-2	I/O Allocation in Use	59						
	4-5-3	DM (Data Memory) Area	60						
	4-5-4	Ladder Program	61						
	4-5-5	Timing Chart	62						
4-6	Prograi	m Example 2: Connection to a PC	63						
	4-6-1	Explanation of Operation	63						
	4-6-2	I/O Allocation in Use	63						
	4-6-3	DM (Data Memory) Area	65						
	4-6-4	Ladder Program	66						
	4-6-5	Timing Chart	68						

# 4-1 Connecting BCD Outputs

The BCD output type Processor is convenient when connecting directly with a PC or personal computer. Refer to the following connection example.



#### **Operation**

When a REQ signal is input to the Processor from a PC, the data is confirmed after an interval of 30 ms, and a DATA VALID (D.V.) signal is output from the Processor. Read the data when the DATA VALID signal is ON.

Connection between PC and Processor should be performed with a rear panel transmission connector.

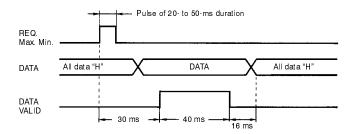
When one PC Unit is connected with several Processor Units, it is possible to achieve a wired OR connection between the DATA (including POL OVER) and DATA VALID signals.

Data cannot be written from a PC to a Processor.

#### **Timing Charts**

# Sampling Data Output (at Each Sample)

Data is confirmed after 30 ms from the REQ signal rising time, and DATA VALID signal is output. Read data while DATA VALID signal ON. The DATA VALID signal is turned OFF after an interval of 40 ms, then data is turned OFF after an interval of 16 ms.

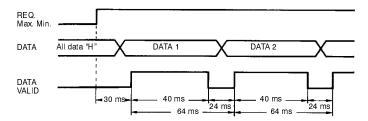


Note The above Max. and Min. are not effective in the K3TC.

#### **Continuous Data Output**

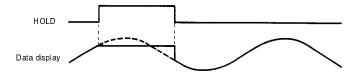
When the REQ signal remains ON, measurement data is output at intervals of 64 ms. When a hold operation or another operation is performed during the change from DATA 1 to DATA 2, the BCD data output is either DATA 1 or DATA 2 at the hold signal timing. Read maximum or minimum data when DATA VALID signal turns ON, after a 30 ms interval from maximum or minimum signal ON time to confirm measurement data.

The RUN signal is ON during RUN mode or TEST mode. (Note that the RUN signal is turned OFF when an error other than overflow or underflow occurs.)

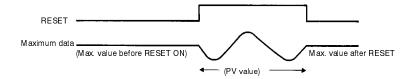


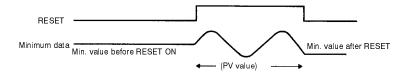
Note The above Max. and Min. are not effective in the K3TC.

When a HOLD signal is input, the Processor stops accepting input and the data received just before the HOLD signal is retained and displayed. The same function is available in (5)-(7) terminal ON.



When RESET signal is input (ON), the maximum or minimum value becomes the current PV value.

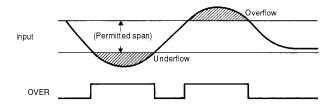




POL output becomes L at positive (+) pole or H at negative (-) pole.



OVER output is formed when BCD output data becomes overflow or underflow data.



In comparative mode or scaling mode, no BCD output is formed (all outputs become "H"). In TEST mode, the test PV value currently input is output in both REQ maximum and REQ minimum signals. When two or more input signals are input simultaneously, or when a signal is input during another input, all the output data is turned OFF. Do not turn ON two or more input signals at the same time (except for the HOLD signal).

### K3TH/K3TR/K3TX I/O Ratings

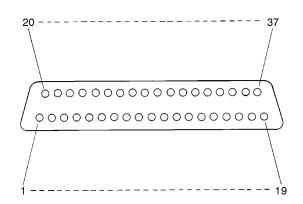
I/O sig	nal name	lt	Rating	
Input REQ HOLD		Input voltage	No-voltage contact input	
	Max. Min.	Input current		10 mA (max.)
	RESET	Signal level voltage	High (When OFF)	3 V min.
	1.252.		Low (When ON)	1.5 V max.
Output DATA POL		Rated load voltage		12 to 24 VDC <sup>+10</sup> / <sub>-15</sub> %
	OVER DATA VALID	Maximum load current		10 mA
	RUN	Leakage current		100 μΑ

## K3TC I/O Ratings

I/O sign	al name	Ite	Rating	
Input	REQUEST COMPENSATION	Input voltage		No-voltage contact input
	RESET	Input current		10 mA
	Operating voltage		OFF	3 V min.
			ON	1.5 V max.
Output	DATA POLARITY	Rated load voltage		12 to 24 VDC <sup>+10</sup> / <sub>-15</sub> %
	OVERFLOW DATA VALID	Maximum load current		10 mA
	RUN	Leakage current		100 μA max.

Note Logic method: negative logic

## **Terminal Numbers**



Terminal no.	Signal name	Signal direction	Description	
1	COM		GND: VO (See Note 1)	
2	DATA	Output	1 Read data: 10 <sup>0</sup> digit	
3		Output	2 Read data: 10 <sup>0</sup> digit	
4		Output	4 Read data: 10 <sup>0</sup> digit	
5		Output	8 Read data: 10 <sup>0</sup> digit	
6		Output	1 Read data: 10 <sup>1</sup> digit	
7		Output	2 Read data: 10 <sup>1</sup> digit	
8		Output	4 Read data: 10 <sup>1</sup> digit	
9		Output	8 Read data: 10 <sup>1</sup> digit	
10		Output	1 Read data: 10 <sup>2</sup> digit	
11		Output	2 Read data: 10 <sup>2</sup> digit	
12		Output	4 Read data: 10 <sup>2</sup> digit	
13		Output	8 Read data: 10 <sup>2</sup> digit	
14		Output	1 Read data: 10 <sup>3</sup> digit	
15		Output	2 Read data: 10 <sup>3</sup> digit	
16		Output	4 Read data: 10 <sup>3</sup> digit	
17		Output	8 Read data: 10 <sup>3</sup> digit	
18		Output	1 Read data: 10 <sup>4</sup> digit	
19		Output	2 Read data: 10 <sup>4</sup> digit	
20		Output	4 Read data: 10 <sup>4</sup> digit	
21		Output	8 Read data: 10 <sup>4</sup> digit	
22	OVER	Output	Output when input value exceeds display range	
23	DATA VALID	Output	Data confirmation signal	
24	RUN	Output	Operation signal	

BCD Programs Section 4-4

Terminal no.	Signal name	Signal direction	Description
25	COM		GND: VO (See Note 1)
26	REQ	Input	PV output request
27	Max.	Input	Maximum value output request (See Note 2)
28	Min.	Input	Minimum value output request (See Note 2)
29	HOLD/COM- PENSATION	Input	Hold input/Compensation input (See Note 3)
30	RESET	Input	Reset input
31	POL	Output	Positive/negative polarity signal
32	HH/OUT5	Output	HH comparative output (See Note 4)
33	H/OUT4	Output	H comparative output (See Note 4)
34	PASS/OUT3	Output	PASS comparative output (See Note 4)
35	L/OUT2	Output	L comparative output (See Note 4)
36	LL/OUT1	Output	LL comparative output (See Note 4)
37	COM	Output	GND: GO (See Note 1)

Note: 1. Terminals No. 1, 25, and, 37 have the same COM.

- 2. The above Max. and Min. are not effective in the K3TC.
- 3. HOLD is effective only in the K3TH, K3TR, and K3TX, and is not effective in the K3TC. COMPENSATION is effective only in the K3TC.
- 4. OUT1 to OUT5 are effective only in the K3TC.

**Applicable Connectors** 

Plug: XM2A-3701 (OMRON) or equivalent Hood: XM2S-3711 (OMRON) or equivalent

## 4-2 Setting before Power Application

No specification setting before power application is required for the BCD output type.

## 4-3 Operations: Front Key Section

No setting with front keys is required for the BCD output type.

## 4-4 BCD Programs

With the BCD output type, only the PV value (display value), maximum value, and minimum value can be read. The K3TH provides read data in four figures, while the K3TR/K3TC provides read data in five figures. The marks (+) and (–) correspond respectively to L polarity and H polarity. Read the read data after the DATA VALID signal rises.

Data cannot be written from the PC to the Processor.

# 4-5 Program Example 1: Connection to a PC

The following program example 1 shows a single Processor connected to the SYSMAC C500 PC (OMRON).

## 4-5-1 Explanation of Operation

In this program, by turning ON PC 0013, the PV (process value) of the Processor is read into the PC to be stored in data memory. Without regard to 0013 ON time, only one data sample is read.

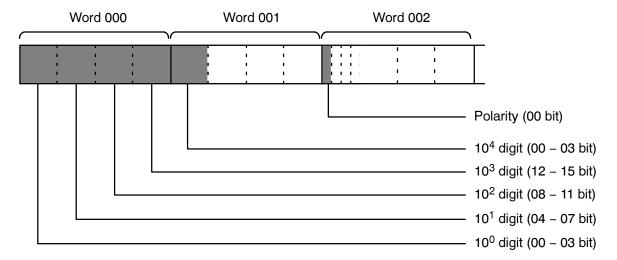
## 4-5-2 I/O Allocation in Use

Terminal no.	Signal name	Signal direction	Description	I/O allocation
1	COM		GND: GO	
2	RD1-0	Output	1 Read data: 10 <sup>0</sup> digit	Input unit 0000
3	RD1-1	Output	2 Read data: 10 <sup>0</sup> digit	Input unit 0001
4	RD1-2	Output	4 Read data: 10 <sup>0</sup> digit	Input unit 0002
5	RD1-3	Output	8 Read data: 10 <sup>0</sup> digit	Input unit 0003
6	RD2-0	Output	1 Read data: 10 <sup>1</sup> digit	Input unit 0004
7	RD2-1	Output	2 Read data: 10 <sup>1</sup> digit	Input unit 0005
8	RD2-2	Output	4 Read data: 10 <sup>1</sup> digit	Input unit 0006
9	RD2-3	Output	8 Read data: 10 <sup>1</sup> digit	Input unit 0007
10	RD3-0	Output	1 Read data: 10 <sup>2</sup> digit	Input unit 0008
11	RD3-1	Output	2 Read data: 10 <sup>2</sup> digit	Input unit 0009
12	RD3-2	Output	4 Read data: 10 <sup>2</sup> digit	Input unit 0010
13	RD3-3	Output	8 Read data: 10 <sup>2</sup> digit	Input unit 0011
14	RD4-0	Output	1 Read data: 10 <sup>3</sup> digit	Input unit 0012
15	RD4-1	Output	2 Read data: 10 <sup>3</sup> digit	Input unit 0013
16	RD4-2	Output	4 Read data: 10 <sup>3</sup> digit	Input unit 0014
17	RD4-3	Output	8 Read data: 10 <sup>3</sup> digit	Input unit 0015
18	RD5-0	Output	1 Read data: 10 <sup>4</sup> digit	Input unit 0100
19	RD5-1	Output	2 Read data: 10 <sup>4</sup> digit	Input unit 0101
20	RD5-2	Output	4 Read data: 10 <sup>4</sup> digit	Input unit 0102
21	RD5-3	Output	8 Read data: 10 <sup>4</sup> digit	Input unit 0103
22	OVER	Output	Output when input value exceeds display range	Input unit 0104* (See Note)
23	DATA VALID	Output	Data confirmation signal	Input unit 0105
24	RUN	Output	Operation signal	Input unit 0106
25	COM		GND: GO	
26	REQ	Input	PV output request	Output unit 0200
27	Max.	Input	Maximum value output request	Output unit 0201* (See Note)
28	Min.	Input	Minimum value output request	Output unit 0202* (See Note)
29	HOLD	Input	Hold input	Output unit 0203* (See Note)
30	RESET	Input	Reset input	Output unit 0204* (See Note)
31	POL	Output	Positive/negative polarity signal	Input unit 0107

**Note:** I/O marked with an asterisk is not used in this program.

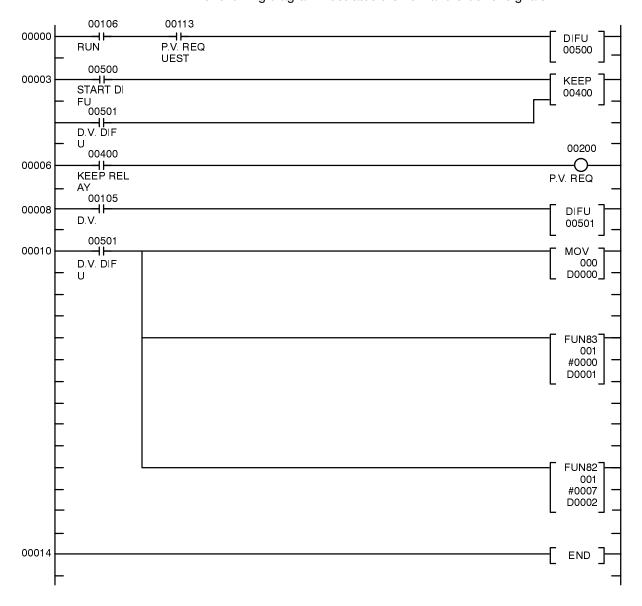
# 4-5-3 DM (Data Memory) Area

Read data is stored in the memory below.



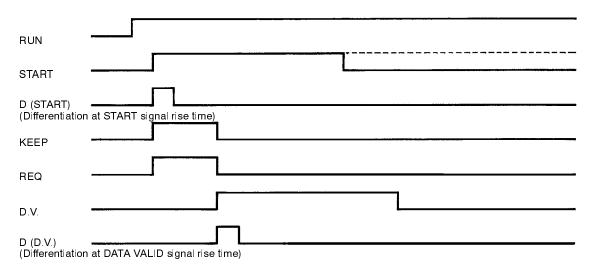
## 4-5-4 Ladder Program

The following diagram illustrates the flow and order of signals.



# 4-5-5 Timing Chart

The following example illustrates the relative timing and duration of each input/output signal.



## 4-6 Program Example 2: Connection to a PC

The following program example 2 shows 3 Processors (designated as ISP-A, ISP-B, and ISP-C Units) connected to the SYSMAC C500 PC (OMRON).

## 4-6-1 Explanation of Operation

In this program, by turning ON PC 0013, PV (process values) of three Processors (A, B, and C) are successively read into the PC, to be stored into data memory. Without regard to 0013 ON time, only one data sample is read from each Processor.

#### 4-6-2 I/O Allocation in Use

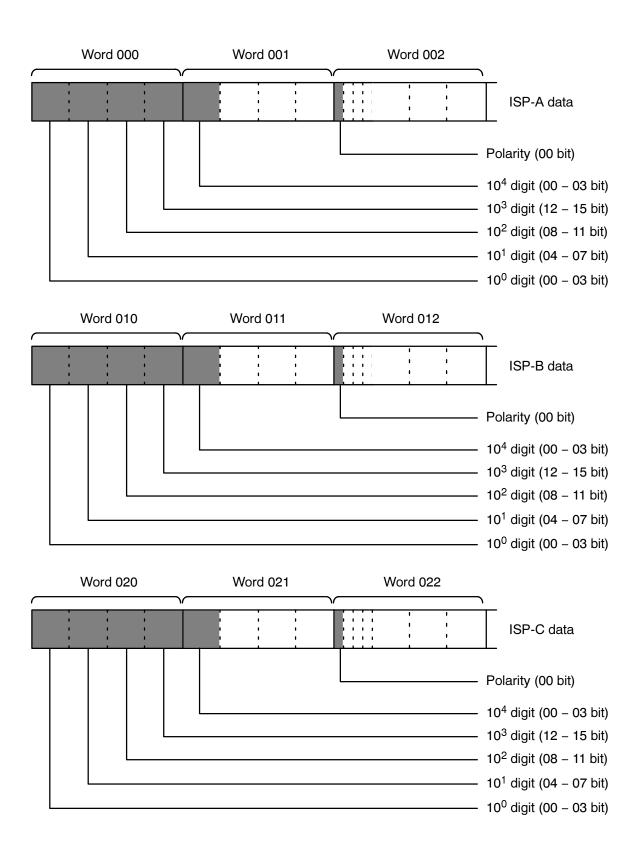
Terminal no.		Signal name	Signal direction	Description	I/O allocation	
ISP-A	ISP-B	ISP-C				
1	1	1	COM		GND: VO	
2	2	2	RD1-0	Output	1 Read data: 10 <sup>0</sup> digit	Input unit 0000
3	3	3	RD1-1	Output	2 Read data: 10 <sup>0</sup> digit	Input unit 0001
4	4	4	RD1-2	Output	4 Read data: 10 <sup>0</sup> digit	Input unit 0002
5	5	5	RD1-3	Output	8 Read data: 10 <sup>0</sup> digit	Input unit 0003
6	6	6	RD2-0	Output	1 Read data: 10 <sup>1</sup> digit	Input unit 0004
7	7	7	RD2-1	Output	2 Read data: 10 <sup>1</sup> digit	Input unit 0005
8	8	8	RD2-2	Output	4 Read data: 10 <sup>1</sup> digit	Input unit 0006
9	9	9	RD2-3	Output	8 Read data: 10 <sup>1</sup> digit	Input unit 0007
10	10	10	RD3-0	Output	1 Read data: 10 <sup>2</sup> digit	Input unit 0008
11	11	11	RD3-1	Output	2 Read data: 10 <sup>2</sup> digit	Input unit 0009
12	12	12	RD3-2	Output	4 Read data: 10 <sup>2</sup> digit	Input unit 0010
13	13	13	RD3-3	Output	8 Read data: 10 <sup>2</sup> digit	Input unit 0011
14	14	14	RD4-0	Output	1 Read data: 10 <sup>3</sup> digit	Input unit 0012
15	15	15	RD4-1	Output	2 Read data: 10 <sup>3</sup> digit	Input unit 0013
16	16	16	RD4-2	Output	4 Read data: 10 <sup>3</sup> digit	Input unit 0014
17	17	17	RD4-3	Output	8 Read data: 10 <sup>3</sup> digit	Input unit 0015
18	18	18	RD5-0	Output	1 Read data: 10 <sup>4</sup> digit	Input unit 0100
19	19	19	RD5-1	Output	2 Read data: 10 <sup>4</sup> digit	Input unit 0101
20	20	20	RD5-2	Output	4 Read data: 10 <sup>4</sup> digit	Input unit 0102
21	21	21	RD5-3	Output	8 Read data: 10 <sup>4</sup> digit	Input unit 0103
22	22	22	OVER	Output	Output when input value exceeds display range	Input unit 0104* (See Note)
23			DATA VALID	Output	Data confirmation signal-A	Input unit 0105
24			RUN	Output	Operation signal-A	Input unit 0106
	23		DATA VALID	Output	Data confirmation signal-B	Input unit 0109
	24		RUN	Output	Operation signal-B	Input unit 0110
		23	DATA VALID	Output	Data confirmation signal-C	Input unit 0111
		24	RUN	Output	Operation signal-C	Input unit 0112
25	25	25	COM		GND: VO	
26			REQ	Input	PV output request-A	Output unit 0200
	26		REQ	Input	PV output request-B	Output unit 0201
		26	REQ	Input	PV output request-C	Output unit 0202
27			Max.	Input	Maximum value output request-A	Output unit 0203* (See Note)

7	Terminal no.		ıl no. Signal S name dir		Description	I/O allocation
ISP-A	ISP-B	ISP-C				
	27		Max.	Input	Maximum value output request-B	Output unit 0204* (See Note)
		27	Max.	Input	Maximum value output request-C	Output unit 0205* (See Note)
28			Min.	Input	Minimum value output request-A	Output unit 0206* (See Note)
	28		Min.	Input	Minimum value output request-B	Output unit 0207* (See Note)
		28	Min.	Input	Minimum value output request-C	Output unit 0208* (See Note)
29			HOLD	Input	Hold input-A	Output unit 0209* (See Note)
	29		HOLD	Input	Hold input-B	Output unit 0210* (See Note)
		29	HOLD	Input	Hold input-C	Output unit 0211* (See Note)
30			RESET	Input	Reset input-A	Output unit 0212* (See Note)
	30		RESET	Input	Reset input-B	Output unit 0213* (See Note)
		30	RESET	Input	Reset input-C	Output unit 0214* (See Note)
31	31	31	POL	Output	Positive/negative polarity signal	Input unit 0107

Note: I/O marked with an asterisk is not used in this program.

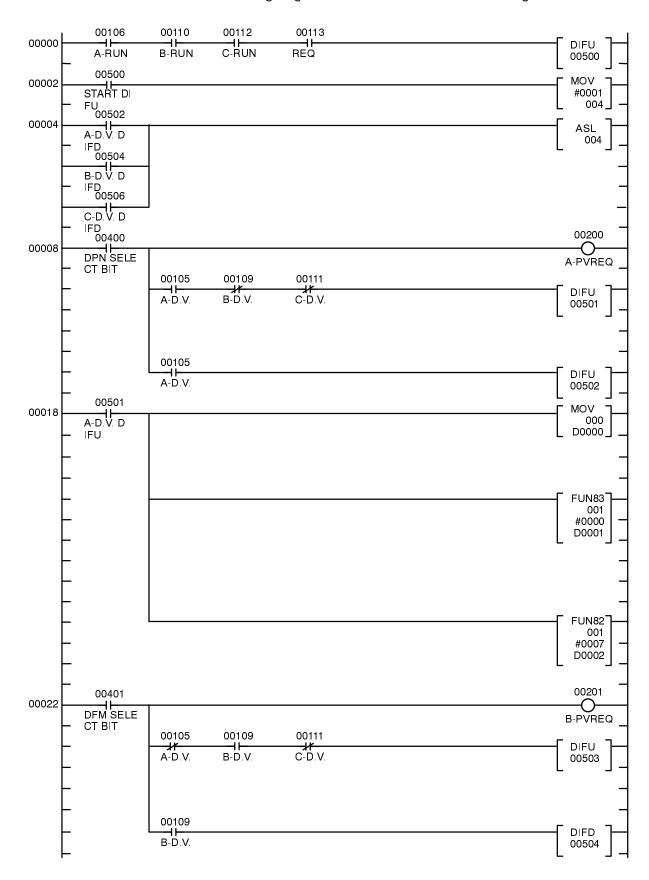
## 4-6-3 DM (Data Memory) Area

Read data is stored in the memory below.

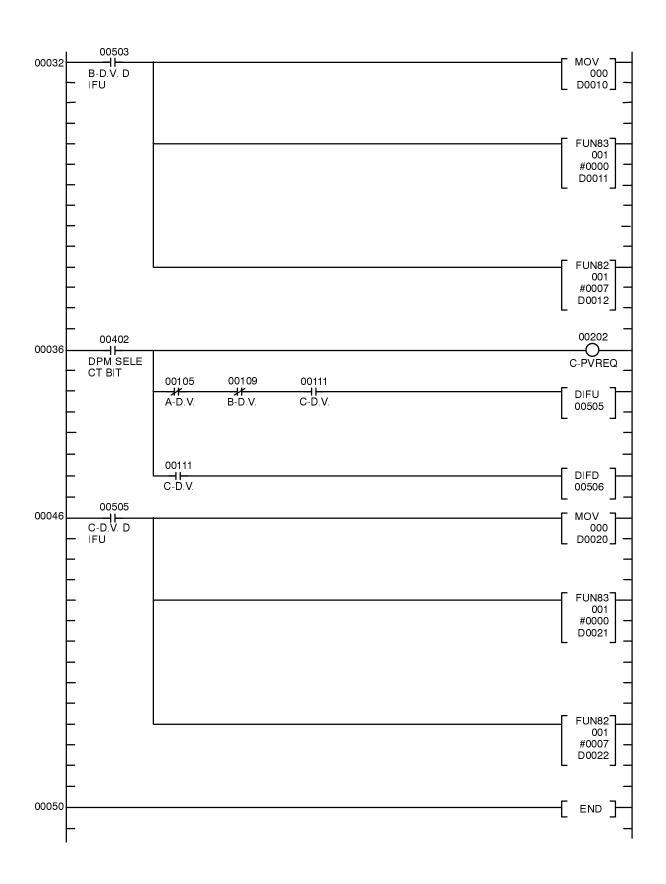


## 4-6-4 Ladder Program

The following diagram illustrates the flow and order of signals.

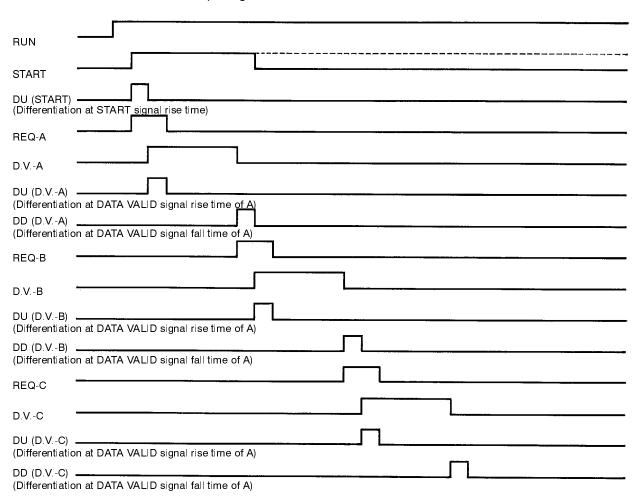


(This diagram is a continuation from the previous page)

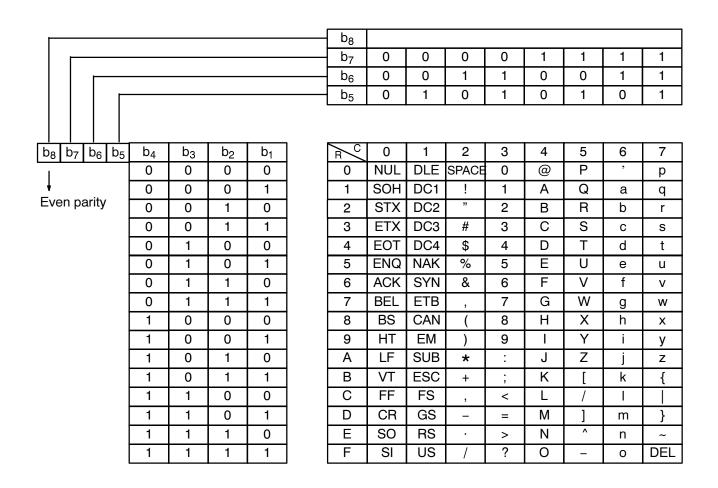


## 4-6-5 Timing Chart

The following example illustrates the relative timing and duration of each input/output signal.



# Appendix A ASCII List

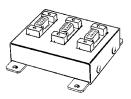


# Appendix B List of Optional Accessories

# **Link Adapters**

B500-AL001

Three RS-422 adapters for RS-422 line distribution.



B500-AL004

One RS-232C adapter and two RS-422 adapters for RS-232C and RS-422.



## **Connectors**

XM2A-0901, XM2A-2501, XM2A-3701 (Plug)

D-sub connector. Use in combination with XM2S.



XM2S-0911, XM2S-2511, XM2S-3711 (Hood)



# **Optical Link Adapter**

Z3RN

To extend RS-232C line.



# Index

A-B	connection to a PC program example 1 (1 Processor), 59 program example 2 (3 Processors), 63
accessories, optional, 71	SYSMAC 500 (OMRON), 59, 63
ASCII list, 69	connector/terminal allocations, 20
Bank indicators K3TC (Basic Model), 11 K3TR (Basic Model), 8 K3TR (with Set Value LED Display), 9	D-E
baud rate, 32	DATA TEACH Key K3TC (Basic Model), 12
BCD output, connecting, 54	K3TH (Basic Model), 4 K3TH (with Set Value LED Display), 6
BCD output connector connection to a PC, 59, 63 explanation of operation, 55 input/output ratings K3TC, 57	K3TR (Basic Model), 8 K3TR (with Set Value LED Display), 10 K3TX 4 1/2-digit Basic Model, 18 K3TX 4-digit Basic Model, 14 K3TX with Set Value LED Display, 16
K3TH/K3TR/K3TX, 56 operations: front key section, 58 programs, 58 setting before power application, 58 timing charts, 55 BCD output connectors, terminal numbers, 57	Display Key K3TH (Basic Model), 4 K3TH (with Set Value LED Display), 6 K3TR (Basic Model), 8 K3TR (with Set Value LED Display), 10 K3TX 4 1/2-digit Basic Model, 18
block format	K3TX 4-digit Basic Model, 14 K3TX with Set Value LED Display, 16
command, 34	display value read, 42
response, 34	end code list, 46
	error control, 35
C	${f F}$
command error, undefined, 46	_
commands, list, 36	FCS, 35
communication program example operation example, 51 RS-232C/RS-422/RS-485 Communication, 47	format data command, 36 response, 36
•	frame check sequence, 35
communications control procedures, 34 RS-232C specifications, 34 RS-422 specifications, 34 RS-485 specifications, 34	front panel nomenclature and functions K3TC (Basic Model), 11 K3TH (Basic Model), 3 K3TH (with Set Value LED Display), 5 K3TR (Basic Model), 7
communications unit number, 30	K3TR (with Set Value LED Display), 9
comparative output status indicators K3TC (Basic Model), 11 K3TH (Basic Model), 3 K3TH (with Set Value LED Display), 5	K3TX 4 1/2-digit Basic Model, 17 K3TX 4-digit Basic Model, 13 K3TX with Set Value LED Display, 15
K3TR (Basic Model), 7 K3TR (with Set Value LED Display), 9 K3TX 4 1/2-digit Basic Model, 17	I
K3TX 4-digit Basic Model, 13 K3TX with Set Value LED Display, 15	interface specifications, 24 RS-232C, 24 RS-422, 26
connecting communications connectors, 21	RS-485, 28

K-O	PV display  K3TC (Basic Model), 11
key operation, 29	K3TH (Basic Model), 3 K3TH (with Set Value LED Display), 5
Level Key K3TC (Basic Model), 12 K3TH (Basic Model), 4 K3TH (with Set Value LED Display), 6	K3TR (Basic Model), 7 K3TR (with Set Value LED Display), 9 K3TX 4 1/2-digit Basic Model, 17 K3TX 4-digit Basic Model, 13 K3TX with Set Value LED Display, 15
K3TR (Basic Model), 8 K3TR (with Set Value LED Display), 10 K3TX 4 1/2-digit Basic Model, 18 K3TX 4-digit Basic Model, 14 K3TX with Set Value LED Display, 16 maximum/minimum read, 41 model data read, 44	PV display status indicators K3TC (Basic Model), 11 K3TH (Basic Model), 3 K3TH (with Set Value LED Display), 5 K3TR (Basic Model), 7 K3TR (with Set Value LED Display), 9 K3TX 4 1/2-digit Basic Model, 17 K3TX 4-digit Basic Model, 13 K3TX with Set Value LED Display, 15
operation keys  DATA TEACH Key, 4, 6, 8, 10, 12, 14, 16, 18  Display Key, 4, 6, 8, 10, 14, 16, 18  K3TC (Basic Model), 12	PV value read, 42
K3TC (Basic Model), 12 K3TH (with Process Value Display), 4 K3TH (with Set Value LED Display), 6 K3TR (Basic Model), 8 K3TR (with Set Value LED Display), 10 K3TX 4 1/2 digit Basic Model, 18	R rear panel communications connector/terminals connecting, 21 connector/terminal allocations, 20
K3TX 4 1/2-digit Basic Model, 18 K3TX 4-digit Basic Model, 14	reset control, minimum/maximum value, 37
K3TX with Set Value LED Display, 16 Level Key, 4, 6, 8, 10, 12, 14, 16, 18	RS-232C communications signals, 24
Shift Key, 4, 6, 8, 10, 12, 14, 16, 18 Up Key, 4, 6, 8, 10, 12, 14, 16, 18	connections, 25
P	RS-422 communications signals, 26 connections, 26 system example, 27
1	RS-485
power, before application of, 29	communications signals, 28 connections, 28
process value display K3TC (Basic Model), 11 K3TH (Basic Model), 3 K3TH (with Set Value LED Display), 5 K3TR (Basic Model), 7 K3TP (with Set Value LED Display), 0	S set value display K3TH (with Set Value LED Display), 5
K3TR (with Set Value LED Display), 9 K3TX 4 1/2-digit Basic Model, 17 K3TX 4-digit Basic Model, 13	K3TR (with Set Value LED Display), 9 K3TX with Set Value LED Display, 15 set value read
K3TX with Set Value LED Display, 15 process value read, 42	communication output, 39 comparative output, 39
program example 1 (1 Processor)  DM (Data Memory) area, 60  I/O allocation in use, 59 ladder program, 61	K3TR communication output, 40 K3TR comparative output, 40 with bank function, 40 with RS-422/485, 40 with Tr communication output, 40
operation, 59 timing chart, 62	set value write
program example 2 (3 Processors)  DM (Data Memory) area, 65  I/O allocation in use, 63 ladder program, 66	communication output, 37 comparative output, 37 K3TR communication output, 38 K3TR comparative output, 38 setting
operation, 63 timing chart, 68	baud rate, 32 communications unit number, 30

#### **Index**

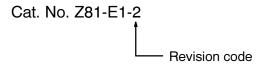
Shift Key
K3TC (Basic Model), 12
K3TH (Basic Model), 4
K3TH (with Set Value LED Display), 6
K3TR (Basic Model), 8
K3TR (with Set Value LED Display), 10
K3TX 4 1/2-digit Basic Model, 18
K3TX 4-digit Basic Model, 14
K3TX with Set Value LED Display, 16
SV display
K3TH (with Set Value LED Display), 5
K3TR (with Set Value LED Display), 9
K3TX with Set Value LED Display, 15
SV display status indicator
K3TH (with Set Value LED Display), 5
K3TR (with Set Value LED Display), 9
K3TX with Set Value LED Display, 15

## T-U

test, 46 timing charts continuous data output, 55 sampling data output, 55 unit K3TC (Basic Model), 11 K3TH (Basic Model), 3 K3TH (with Set Value LED Display), 5 K3TR (Basic Model), 8 K3TR (with Set Value LED Display), 10 K3TX 4 1/2-digit Basic Model, 17 K3TX 4-digit Basic Model, 13 K3TX with Set Value LED Display, 15 Up Key K3TC (Basic Model), 12 K3TH (Basic Model), 4 K3TH (with Set Value LED Display), 6 K3TR (Basic Model), 8 K3TR (with Set Value LED Display), 10 K3TX 4 1/2-digit Basic Model, 18 K3TX 4-digit Basic Model, 14 K3TX with Set Value LED Display, 16

# **Revision History**

A manual revision code appears as a suffix to the catalog number on the front cover of the manual.



The following table outlines the changes made to the manual during each revision. Page numbers refer to previous version.

Revision code	Date	Revised content
1	October 1991	Original production
2 January 1997	January 1997	References to the K3TC Up/Down Counting Intelligent Signal Processor added throughout the manual.
		Pages 1, 2, 46: Reference to K3TC added.
		Pages 3 to 8: Updated with new models.
		Page 10: Model numbers updated. Note added for the K3TC.
		Pages 11, 59: D-sub connector models changed.
		<b>Page 15:</b> Connection diagram corrected. Plug model added. OMRON Factory Computer reference removed. Short-circuit information corrected accordingly.
		Page 16: Plug model removed.
		<b>Page 18:</b> RS-485 terminal numbers on the Processor side corrected in the diagram.
		<b>Pages 19</b> , <b>20</b> : K3TR and K3TX information corrected and K3TC added to <i>3-3 Key Operation</i> .
		Pages 21 to 23: K3TC information added.
		Page 26: K3TC added in Note 2. Note 3 added.
		<b>Page 27:</b> K3TC information added to <i>3-7 Reset Control (Maximum/Minimum Value Reset)</i> .
		Page 28: Notes added to the bottom of the page.
		<b>Page 31:</b> Notes added to the top of the page. K3TC information added to <i>3-12 Maximum/Minimum Read</i> .
		<b>Page 32:</b> Response format corrected for <i>3-13 Display Value (PV Value) Read</i> . Notes added to the bottom of the page.
	Page 34: Response format corrected and K3TC added for 3-14 Model Data Read.	
		Page 42: Connection example corrected.
		Page 43: First two timing charts corrected. K3TC information added.
		Page 44: K3TC I/O ratings table added.
	Pages 45, 46: K3TC information added to the signal names and descriptions of the terminal numbers. Notes added.	
		Pages 48, 53: "ch" corrected to "word."
		Page 57: ASCII list corrected.