

Sysmac: A fully integrated platform

One connection - One software - One machine controller

FACTORY AUTOMATION

HMI · Programming · DB connection · IT systems



MACHINE CONTROL

Servo · Inverter · I/O · Safety · Vision · Robotics · Sensing



Omron provides tailored solutions

Flexible and integrated production business models

In today's globalized manufacturing environment, diverse and complex challenges arise and need to be overcome. The global market rapidly changes, and manufacturing companies are under increasing pressure to supply products in a timely manner that satisfy a wide variety of consumer needs. Omron industrial automation makes efficient, flexible and cost effective manufacturing possible.



Innovation

- New technology for smart manufacturing
- Collaboration between humans and machines
- Environmentally safe products



Productivity

- Integrated systems for optimized manufacturing
- Production data available in real-time
- In-line quality inspection: zero defects



Flexibility

- Quick product changeovers
- · Openness and third party connectivity
- Scalable systems for optimum solutions



Reliability

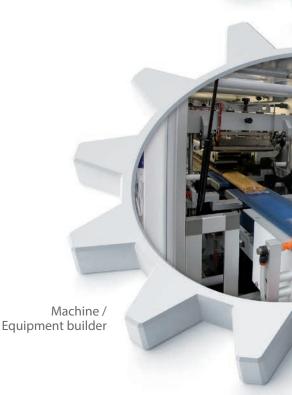
- Non-stop processes, 24/7 operation
- Extended product lifecycle



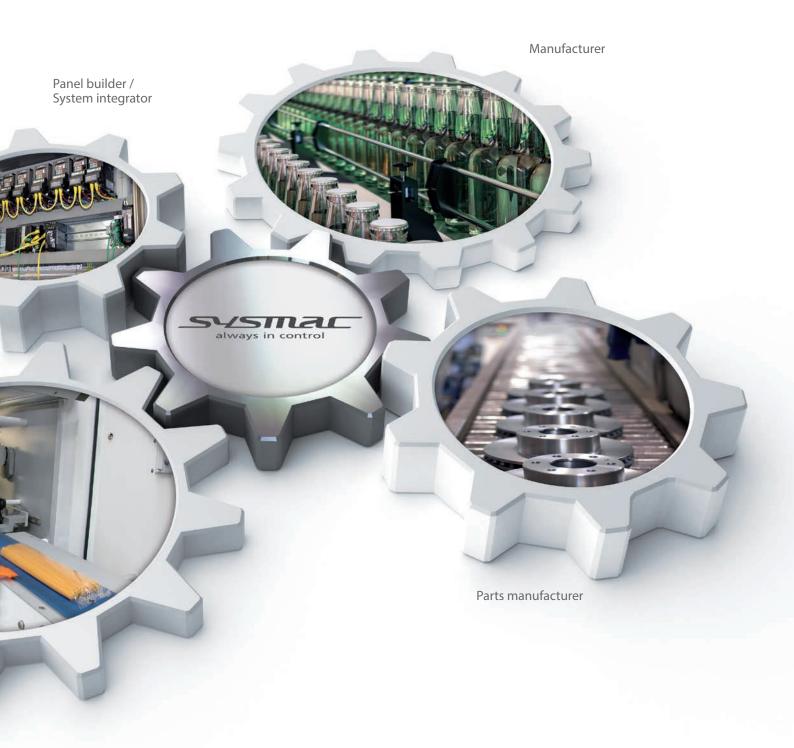
Globalization

- Products meet global standards
- Local support for training, repairs and spare-parts supply
- Engineering environment compliance with global standards

✓ Through automation, Omron supports the advancement of manufacturing and contributes to a sustainable society by providing environmentally safe products



The Sysmac technology platform ensures a flexible and integrated production business model



Sysmac: A fully integrated platform

Integration and Functionality

Sysmac is an integrated automation platform dedicated to providing complete control and management of your automation plant. At the core of this platform, the Machine Controller series offers synchronous control of all machine devices and advanced functionality such as motion, robotics and database connectivity. This multidisciplinary concept allows you to simplify solution architecture, reduce programming and optimize productivity.

One Machine Controller

Complete integration of motion and logic sequence



FACTORY AUTOMATION

MACHINE CONTROL

Machine Automation Controller / Industrial PC with Sysmac Machine Control



Motion



- Motion Control: Integrated within the IDE, and operating in real-time
- Standard PLCopen Function Blocks plus Omron generated motion FB's
- Direct Synchronous control for Position, Speed and Torque

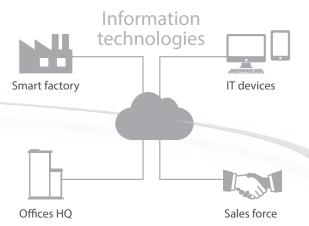




- All safety related data is synchronized with the whole network
- The PLCopen® FBD simplifies and accelerates the development process through structuring safety circuits and enhancing reuse.

 One Integrated Development Environment software for Configuration, Programming, Simulation and Monitoring





Information



- Sysmac communicates in real-time with Databases such as SQL
- Secure Data: In the event of a server going down or losing communications, data is automatically stored in internal memory
- Sysmac operates with Databases at high speed [1000 table element/ 100 ms] ensuring realistic Big Data Processing to improve productivity and aid predictive maintenance etc.

✓ Integrated Automation Control:

The Sysmac platform is scalable and provides the performance and functionality for a wide range of solutions from simple machines through to manufacturing cells

Vision



- Higher resolution images available without increasing the vision processing time
- Shape search technology: Provides more stable and accurate object detection for Pick & Place projects





 Function Blocks in Adept Robot Control Library enable robot control from the NJ/NX/NY Controller using Ladder and Structured Text

Sensing

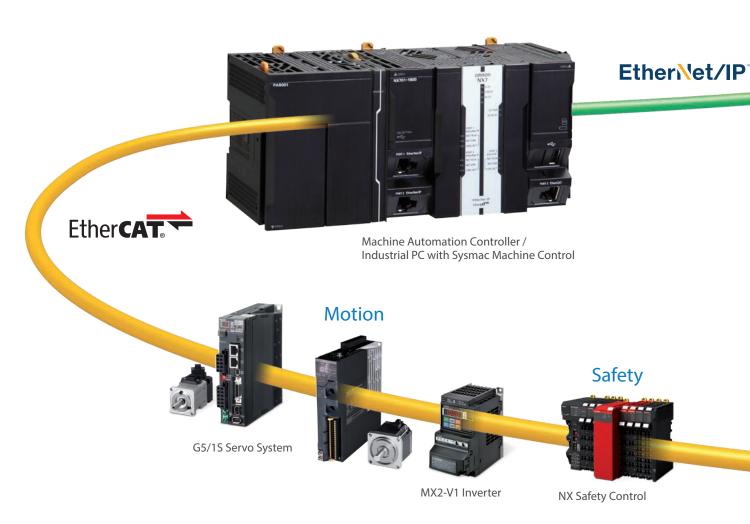


- Full control of the process parameter setting and predictive maintenance functions
- High precision detection and positioning data synchronized on the network

One Connection

Seamless machine control and factory automation

One machine control through one connection and one software is how we define the Sysmac automation platform. The Machine Automation Controller integrates logic, motion, safety, robotics, vision, information, visualization and networking under one software: Sysmac Studio. This one software provides a true Integrated Development Environment (IDE) that also includes a custom 3D motion simulation tool. The machine controller comes standard with built-in EtherCAT and EtherNet/IP. The two networks with one connection purpose is the perfect match between fast real time machine control and data plant management.



EtherCAT - Machine Control

- · Fast and precise: Fastest cycle time of 125 μs, synchronization with 1 μs jitter
- 512 slaves
- Embedded in Omron servo drive, inverter, I/O, Safety, Vision and Sensing
- · Uses standard STP Ethernet cable with RJ45 connectors
- · One connection using Safety over EtherCAT (FSoE) protocol





Database

EtheriNet/IP*



SCADA/MES/ERP



Robot



Parallel/SCARA/ Articulated Robot

HMI



NA Programmable Terminal

Software













Ethernet - Factory Automation

- · Peer-to-Peer controller communication
- · Interface with Sysmac Studio , NA HMI or SCADA software
- Database connection for Microsoft SQL Server, Oracle, IBM DB2, MySQL and Firebird
- FTP server

Vision FH FQ-M

Sensing



ZW-8000/7000/5000 Confocal Fiber Displacement Sensor



N-Smart Fiber/Laser/Contact Sensor IoT Status Monitoring Amplifier



NX I/O O IO-Link

IO-Link Sensor

One Software

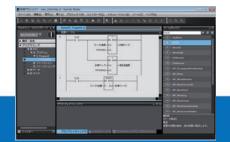
One Integrated Development Environment Software

Created to give you complete control over your automation system, Sysmac Studio integrates configuration, programming and monitoring. Graphics-oriented configuration allows quick set-up of the controller, field devices and networks while machine and motion programming based on IEC standard and PLCopen Function Blocks for Motion Control cuts programming time. Smart Editor with On-line debugging helps quick and error free programming. Advanced simulation of sequence and motion control, and data trace reduce machine tuning and set-up.

Design

Reusable programs

Programming with variables



One Integrated Development
Environment software Sysmac Studio is
fully compliant with the open standard
IEC 61131-3. Programming with
variables eliminates the need to learn
the internal memory map of the PLC
and allows the programs to be reused.



*This function can be used by applying the Team Development Option to Sysmac Studio version 1.20 or higher. Project version control function is supported by CPU Unit version 1.16 or later.

Maintenance

Highly efficient maintenance

Troubleshooting



Troubleshooting in the Sysmac Studio and NA Programmable Terminal can manage errors across the entire system including the controller. You can check details of errors and solutions without reading manuals.



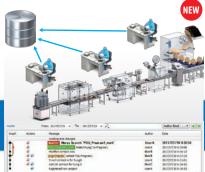
Collection of software functional components Sysmac Library

Packed with Omron's rich technical know-how, the Function Blocks in the Sysmac Library for advanced applications and motion control cut programming time.

Development by multiple developers

For advanced machine control

| Project version control function *



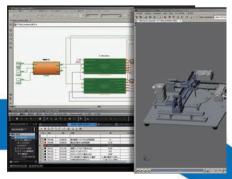
When you develop a project at the same time as your colleagues, the Sysmac Studio combined with the version control system (Git™) merges changes automatically and resolves conflicting changes. This makes merging easier and faster. You can even revert to the previous revision after graphically comparing the current project with a previous one.

| Motion programming



Advanced motion control applications can be created quickly just by combining PLCopen® Function Blocks for Motion Control.

| Model-Based design



Complex feedback control that is designed with MATLAB®/ Simulink® can be imported into programs.



Verifification

Fast system debugging

Virtual mechanical debugging



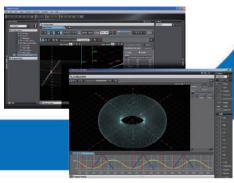
Movement of the machine connected online can be displayed on the CAD in real time, and movement can also be reproduced from the trace data. Maintenance and troubleshooting can be performed in remote locations.



Before the mechanical prototype is completed, motion can be checked and the program can be debugged. This cuts design time.



3D simulation



Motion trajectories in 3D can be pre-tested with advanced simulation of sequence and motion control. Simulation of single Function Blocks, POU's (Program Organization Unit) or the entire program can be performed. In addition all standard features such as Break & Step are available. Easy tuning and debugging reduce the set-up times of machines and production lines.

One Machine Controller

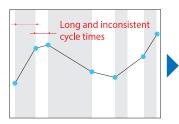
NJ/NX/NY Machine Automation Controller

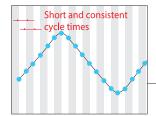
Powerful, yet easy to configure

The NJ/NX/NY Controller is at the heart of the Sysmac platform. One integrated controller is designed to meet extreme requirements in terms of logic sequence and motion control speed and accuracy. Standard programming and open networks make it easy to build your automation system.

High-speed, high-precision control*1

Architecture based on Intel® Core™ i7 processor significantly speeds up the execution of instructions (basic instructions 0.37 ns, math instructions for Long Real Data 3.2 ns). Command values to send to servomotors and stepper motors can be updated as fast as every 125 µs. This enables smooth cam motion and high-precision interpolation and phase adjustment between axes.





Basic instructions 0.37 ns Industry's fastest Motion control 125 μs/8 axes Industry's fastest

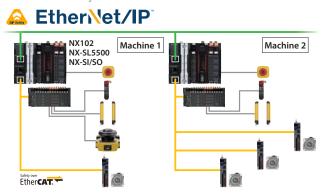
Complete integration of motion and logic

One controller integrates logic, motion, vision and information for complete control and management of machines. Position, displacement, and tension information collected from sensors can be quickly and easily fed back to the motion control.



Integrated safety into machine control*3

The controller integrates safety control into machine control in lines that require fast cycle times. It also integrates two different open networks: EtherNet/IP for safety control in production lines and EtherCAT for safety control in machines.





- * 1. Performance of NX701-1□00
- * 2. Based on Omron investigation in February 2015.
- * 3. Performance of NX102- \square \square and NX-SL5 \square 00
- * 4. Database connection CPU unit: NX102- \(\pri \) 20/N I \(\pri \) 01- \(\pri \) 20
- * 5. Performance of NX102-□□□□/NJ501-1□00

Fast machine data storage in database *4

The controller connects directly to a database without the need for a gateway. The special instructions allow easy access to the database. Real-time data collection enables productivity improvement, predictive maintenance, and quality traceability.

Secure host connection*5

OPC UA is an IEC communication protocol which is listed as a recommendation for Industrie 4.0 and PackML. The NX1 comes equipped with an OPC UA server interface and provides a secure connection to IT systems such as MES and ERP. CERTIFIED



Standard programming

- Fully conforms with IEC 61131-3 standards
- PLCopen Function Blocks for Motion Control





Global standard networks





Standard Factory Network

Collection of software functional components Sysmac Library

- FB library option for advanced applications (vibration suppression, temperature control, motion control...)
- High quality products with reliable global support



Case studies of machine innovation by increasing speed and precision

Case 1: High-speed alignment and vibration-free handling

Problems

- 1. Precisely stacking many sheets increases cycle time because retries caused by mechanical errors increase positioning time.
- 2. Vibration settling time is required when high-speed handling is stopped. Speed must be reduced to suppress vibration.

1. High-speed, high-precision alignment system

The FH Vision System provides the Shape Search function for fast and accurate shape recognition and Visual Feedback that feeds back the current position to control the motor in every measurement cycle. These increase alignment speed without sacrificing accuracy.

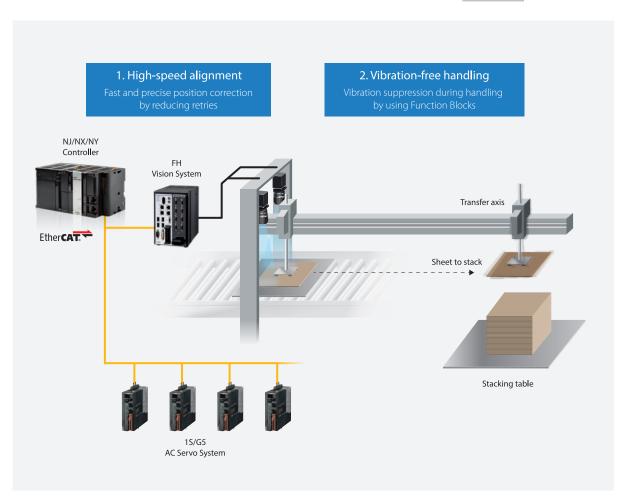


2. Software functional components for vibration suppression

The Vibration Suppression Library facilitate programming for high-speed handling while suppressing vibration. Waiting time is reduced, and positional accuracy is increased.



Vibration Suppression Library



Case 2: Packaging machine using electric cam

Problems

- 1. The PLC and mechanical cam control cannot accurately synchronize axes. In addition, low precision, vibration, and noise caused by mechanical cam limit high-speed and high-precision packaging.
- 2. It takes time to adjust mechanical cam to different packaging materials and settings every time a different type of product is packaged.

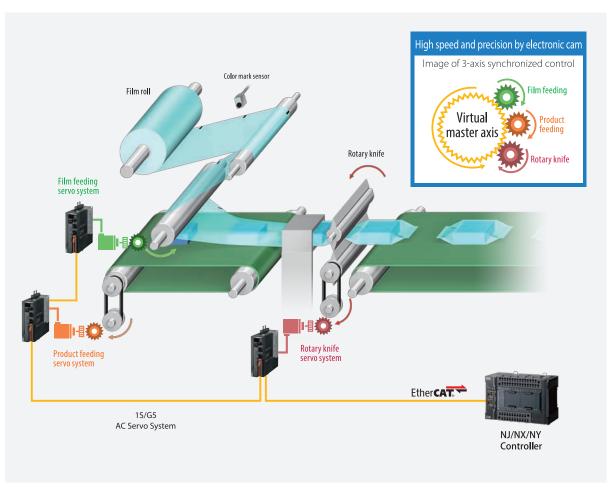
Electronic cam optimizes packaging speed and precision

Electronic cam motion control realizes machine cam motion. Electronic cam enables 3 axes - "film feeding", "product feeding", and "rotary knife" - to be synchronized at high speed. This eliminates following errors between axes even during high-speed operation, leading to higher-speed and higher-quality packaging. Registering settings as a recipe reduces changeover time.

Software functional components for electronic cam control

The Rotary Knife Function Block in the Packaging Machine Library increases the speed and precision of horizontal flow packaging and enables mechanical cam motion without electronic cam table.





Controller

NX1 Machine Automation Controller

Compact size controller integrates production line and IT systems

Improve productivity, improve your business

The NX1 can utilize information, take safety measures, and control quality while at the same time improving production efficiency through high-speed, high-precision control.

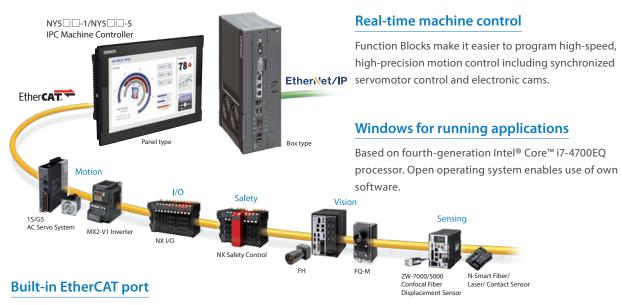
Fulfilling functions in compact size

Three industrial Ethernet ports and a power supply are housed in a compact design with a width of 66 mm. The multicore microprocessor and OPC UA connectivity enable information utilization without compromising control performance.



NY5 - 1/NY5 - 5 **IPC Machine Controller**

An IPC machine controller combines machine control and IT technology



EtherCAT connectivity simplifies installation of FA devices and safety devices: up to 192 synchronized slaves, up to 64 axes of motion control, and Safety over EtherCAT. Fully conforms to IEC 61131-3 standard programming.

Series	NX Series			NJ Series				
Model		NX1P2- □□□□	NX102-	NX701-	NJ101-□□□□	NJ101-□□20	NJ301-□□□□	NJ501-□□□□
Feature		Motion control and built-in I/O	Compact control- ler with up to 8 axes motion control	For large-scale control with up to 256 axes	For simple machine	?S	For small-scale control with up to 8 axes	For large-scale control with up to 64 axes
Appearance								
Instruction execution til	mes (LD	3.3 ns	3.3 ns	0.37ns	3.3 ns		2.0 ns	1.1 ns
Program cap	acity	1.5 MB	5 MB	80MB	3 MB		5 MB	20 MB
Variables ca (No retain at		2 MB	32 MB	256MB	2 MB		2 MB	4 MB
I/O capacity		40 points	_	_	2,560 points		2,560 points	2,560 points
Number of EtherCAT sla	ives	16	64	512	64		192	192
Number of motion axes		0, 2, 4	0, 2, 4, 8	128, 256	0, 2		4, 8	16, 32, 64
Functions		_	Database connection (NX102- 20)	Database connection (NX701-1 20)	_	Database con- nection	_	_
Detailed specification	Catalog	P116	P130	P089	P089			

Series	NJ Series				NY Series		
Model	NJ501-4□□□	NJ501-1□20	NJ501-1340	NJ501-5300	NY51□-1	NY53□-1	NY53□-5□00
Feature	For large-scale con	trol with up to 64 axe	S		Perfect integration: Sysmac machine control and ICT		
Appearance							
Instruction execution times (LD instruction) 1.1 ns		0.33 ns					
Program capacity	20 MB				40 MB		
Variables capacity (No retain attribute)	4 MB			64 MB			
I/O capacity	2,560 points				_		
Number of EtherCAT slaves	192				192		
Number of motion axes 16, 32, 64 16			16, 32, 64		32		
Functions	Robot control	Database connection	SECS/GEM communication	Numerical control (NC)	_	_	Numerical control (NC)
Detailed specification Catalog	P089			P118			

Software

SYSMAC-SE2 **Automation Software Sysmac Studio**

One software for programming, configuration, simulation and monitoring

- · One software for motion, logic sequence, safety, motion, vision and visualization
- · Fully compliant with open standard IEC 61131-3
- · Supports Ladder, Structured Text, and Function Block programming with a rich instruction set
- · Advanced security function with 32 digit security password



SYSMAC-XR Sysmac Library

Omron's control expertise changes programming

- · Advanced control such as vibration suppression and temperature control
- · High-precision control of packaging machines and actuators for servo presses
- · Productivity improvement by monitoring device operations and restoring parameters
- \cdot Reduction in programming time





Series	Automation Software Sysmac Studio	Collection of software functional components Sysmac Library	
Model	SYSMAC-SE2□□	SYSMAC-XR□□□	
Appearance	Sysmac Studio Autorizing Printers omron	Sysmac Library	
System requirements	[Operating system (OS)] Windows 7 (32-bit/64-bit version), Windows 8 (32-bit/64-bit version), Windows 8.1 (32-bit/64-bit version), Windows 10 (32-bit/64-bit version) [CPU] Windows computers with Intel® Celeron™ processor 540 (1.8 GHz) or faster CPU. Intel® Core™ i5 M520 processor (2.4 GHz) or equivalent or faster recommended.	[Applicable models] For details, refer to the catalog of Sysmac Library.	
CX-Designer CX-Integrator CX-Protocol Network Configurator SECS/GEM Configurator Adept Robot IP Address Setting Tool CX-ConfigratorFDT IODD DTM Configurator		MC Test Run Library MC Command Table Library MC Tool Box Library EtherCAT GS Series Library EtherCAT N-Smart Series Library Vibration Suppression Library Temperature Control Library Device Operation Monitor Library Adept Robot Control Library Weighing Control Library EtherCAT 1S Series Library Packaging Machine Library Servo Press Library Dimension Measurement Library Safety System Monitor Library High-Speed Analog Inspection Library SLMP Communications Library Visual Feedback Alignment Library	
Detailed specification	Refer to your OMRON website.		

Sysmac Family HMI

NA Programmable Terminal

Make industrial machines more attractive and competitive by bringing technology to life

As part of the Sysmac automation platform, NA transforms machine data into information, shows information and controls devices based on requirements at FA manufacturing sites.





IAG – Intelligent Application Gadgets
The graphics collection accelerates the development process.
You can make your own collections and share them between projects.

Series	NA Series	NA Series				
Feature	More than 16 million color (24 bit full o	More than 16 million color (24 bit full color) and wide screen for all models				
Appearance		0 0 0				
Display device	TFT LCD					
Screen size	15.4-inch widescreen	12.1-inch widescreen	9.0-inch widescreen	7.0-inch widescreen		
Number of dots (horizontal × vertical)	WXGA 1,280×800 dots					
Colors	16,770,000 colors (24 bit full colors)					
Built-in ports	2 Ethernet ports, 2 USB host ports, 1 USB slave port					
Allowable power supply voltage range	19.2 to 28.8 VDC					
Degree of protection	Front-panel controls: IP65 oil-proof type					
Memory card	SD/SDHC memory card					
Flame colors	Black, silver					
Detailed specification Catalog	V413					

Motion

R88M-1□/R88D-1SN□-ECT 1S AC Servo System

Improved machine design. Increased machine productivity

Optimized installation and commissioning tasks

- · Cabinet size reduction: Compact servo drive with same height throughout the whole power range
- · Fast and secure screw-less push-in in control I/O connector and brake interlock connector

23 bit high resolution encoder

· No battery, no maintenance and compact size

Multi-axis setup and tuning

- · Configure and monitor multiple axes in one view
- · Easy & fast parameter transfer among axes in the machine (up to 256 axes)
- · Comprehensive gain tuning

Safety control via EtherCAT

- · EN ISO 13849-1(Cat.3 PLd)
- · EN61508(SIL2), EN62061(SIL2)
- · EN61800-5-2(STO)





R88M-K/R88D-KNI - ECTI R88L-EC/R88D-KNI - ECT-L G5 AC Servomotor/Linear Motor/Servo Drive

At the heart of every great machine

Rotary motors

- · Motors with IP67
- · Large range of motors from 0.16 Nm up to 96 Nm nominal torque (224 Nm peak)

Ironless linear motors

- · Excellent force-to-weight ratio
- · No latching force

Iron-core linear motors

- · Optimum ratio between force and volume
- · Weight-optimized magnetic track

Safety conformance

- · ISO13849-1(PLc,d)
- · EN61508(SIL2)
- · IEC61800-5-2(STO)







Ether CAT.

Series	1S Series		G5 Series		
Model	R88M-1□/R88D-1SN□-E	СТ	R88M-K/R88D-KN□-ECT R88D-KN□-ECT-L	•R88L-EC/	
Appearance			B P NO		
Туре	Built-in EtherCAT Communicat	ions	Built-in EtherCAT Communicat	ions	
Linear Type	No		Yes. Refer to the G5 Series Cata for details.	llogs (Cat. No. 1815 and 1816)	
100 VAC Applicable motor capacity/ force	50 W to 400 W		50 W to 400 W		
200 VAC Applicable motor capacity/ force	50 W to 3 kW		50 W to 15 kW		
400 VAC Applicable motor capacity/ force	600 W to 3 kW		400 W to 15 kW		
Applicable servomotor	1S Servomotor		G5 Rotary Servomotor		
Control mode	Position, speed and torque cor	ntrol	Position, speed and torque cor	ntrol	
Safety approvals	- ISO 13849-1 (PL-e/PL-d) - EN61508 (SIL3/SIL2) - EN62061 (SIL3/SIL2) - IEC 61800-5-2 (STO)		· ISO 13849-1 (PL-c,/PL-d) · EN61508 (SIL2) · EN62061 (SIL2) · IEC 61800-5-2 (STO)		
Full closed loop	-	_	Built-in		
Appearance		(3)			
Rated rotation speed	3,000 r/min	2,000 r/min	3,000 r/min	2,000 r/min	
Momentary maximum rotation speed	5,000 to 6,000 r/min	3,000 r/min	4,500 to 6,000 r/min	3,000 r/min	
Rated torque	0.318 to 9.55 N·m	4.77 to 14.3 N·m	0.16 to 15.9 N·m	1.91 to 23.9 N·m	
Capacity	50 W to 3 kW	400 W to 3 kW	50 W to 5 kW	400 W to 5 kW	
Applicable servo drive	1S Servo Drive		G5 Servo Drive (for rotary servo	omotor)	
Encoder resolution	23-bit absolute	23-bit absolute	20-bit incremental/ 17-bit absolute	20-bit incremental/ 17-bit absolute	
Protective structure		II	P67		
Appearance					
Rated rotation speed	1,000 r/min		1,500 r/min	1,000 r/min	
Momentary maximum rotation speed	2,000 r/min		2,000 to 3,000 r/min 2,000 r/min		
Rated torque	8.59 to 28.7 N·m		59 to 28.7 N·m 47.8 to 95.5 N·m 8.59 to 57.3 N		
Capacity	900 W to 3 kW		7.5 to 15 kW 900 W to 6 kW		
Applicable servo drive	1S Servo Drive		G5 Servo Drive (for rotary servo	omotor)	
Encoder resolution	23-bit absolute		17-bit absolute 20-bit incremental/ 17-bit absolute		
Protective structure	IP67				
Detailed specification Catalog	1821		1815 and 1816	I815 and I816	

Motion

3G3MX2-A□□□□-V1 MX2-V1 Multi-function Compact Inverter

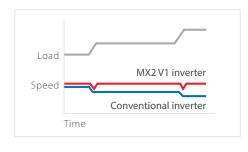
Born to drive machines

Torque control in open loop

- · Ideal for low to medium torque applications
- · Can replace a flux vector inverter or servo drive in suitable systems

Quick response to load fluctuation

· Stable control without decreasing machine speed improves quality and productivity



Safety inside

- · Conforms to safety norm ISO 1384901 Cat. 3 performance level PLd
- · 2 Safety inputs
- · External device monitoring (EDM)

Other Features

- · Maximum applicable motor capacity: 15 kW
- · Double rating (CT: Heavy load/VT: Light load)
- · Permanent magnet motors
- · Drive Programming
- · Built-in brake control function



3G3RX-□□□□□-V1 RX-V1 High-function General-purpose Inverter

Ether CAT.

Ether CAT.

Versatile for a wide range of applications

- · Maximum applicable motor capacity: 132 kW
- · Double rating (CT: Heavy load/VT: Light load)
- · Sensorless vector control, Vector control with a PG
- · Drive Programming
- · Built-in Electronic gear



Series		MX2 Series V1 type	RX Series V1 type
Model		3G3MX2-V1	3G3RX-V1
Appearance			
	Three-phase 200 V	0.1 to 15 kW(CT)	0.4 to 55 kW(CT)
Power supply	Three-phase 400 V	0.4 to 15 kW(CT)	0.4 to 132 kW(CT)
and capacity	Single-phase/three-phase 200 V	No	_
	Single-phase 200 V	0.1 to 2.2 kW(CT)	_
Control metho	ds	V/F control Sensorless vector control	V/F control Sensorless vector control Vector control with a PG
	No. of multi-function I/O points	· 7 inputs · 2 transistor outputs · 1 relay output	9 inputs (1 RUN (FWD) input + 8 multi-function inputs) 5 transistor outputs 1 relay output
nput/ output	Analog I/O	· 2 inputs (0 to 10 V, 4 to 20 mA) · 1 output (0 to 10 V)	- 2 inputs (1) 0 to 10 V, 4 to 20 mA (2) 0 to ±10 V - 2 outputs (1) 0 to 10 V (2) 4 to 20 mA - 1 PWM voltage output
Braking		Braking resistor connection Regenerative Braking Unit connection Regenerative Braking Unit + braking resistor connection	Braking resistor connection (22 kW max.) Regenerative Braking Unit connection Regenerative Braking Unit braking resistor connection
Frequency	Frequency setting range	0.1 to 400 Hz	0.1 to 400 Hz
rrequency	Frequency output method	Line-to-line sine wave PWM	Line-to-line sine wave PWM
	Side-by-side mounting	Yes	No
nstallation and wiring	Removable terminal block	No	Yes
	Power supply and motor wiring	Bottom wiring	Bottom wiring
	Multistep speed control	16 steps + jog	16 steps + jog
	Carrier frequency setting	2 to 15 kHz (default setting: 5 kHz)	2 to 15 kHz (default setting: 5 kHz)
	Torque assist function	Auto/manual torque assist	Auto/manual torque assist
	PID function	Yes	Yes
	Absolute value positioning	No	Yes
	Emergency shutoff	Yes	Yes
Main	0-Hz domain sensorless vector control	No	Yes
unctions	Tripless function	Yes	Yes
	Momentary power interruption restart	Yes	Yes
	Double Rating	Yes	Yes
	Permanent magnet motor control	Yes	_
	Starting torque	200% at 0.5 Hz	· 200% at 0.3 Hz in open loop · Full torque at 0 Hz in closed loop
PLC functionality (Drive Programming)		Provided	Provided
Communicatio	ns	Optional EtherCAT communication unit	Optional EtherCAT communication unit
Safety approva	ıls	· ISO 13849-1 (Cat.3/PLd) · IEC 60204-1 Stop Category 0	_
Detailed specification	Catalog	1920	1919

NX I/O System

Speed and accuracy for machine performance

Based on an internal high-speed bus running in synchronization with the EtherCAT network and using the time-stamp function, the NX I/O can be controlled with microsecond accuracy and with nanosecond resolution.

The I/O range consists of over 100 models including position control, temperature inputs and integrated safety.



Communications coupler

- EtherCAT®
- EtherNet/IP™



IO-Link master

devices with one master

Serial communications

·RS-232C or RS-422A/485 interface



RFID

Direct connection to V680 RFID System



Digital I/O

- · 4, 8, 16, or 32 channels per input unit
- 2, 4, 8, 16, or 32 channels per output unit (8 channels per relay output unit)
- · 16 channels per mixed I/O unit
- ·Standard, high-speed,
- · Units with Push-In Plus/MIL/ Fuiitsu/M3 Screw connector



Analog I/O

- ·+/-10V voltage and 4-20
- mA current signals · 2, 4 or 8 channels per
- input unit · 2 or 4 channels per
- output unit · Standard and
- high-performance models
- · Single-ended input and

High-speed analog input

- · 4 channels per input unit
- · Differential input
- · Sampling as fast as every 5 µs



Load cell inputs

·One load cell with one unit · Fastest conversion cycle of 125 µs



Safety I/O

- · 4 or 8 safety input points per unit
- · 2 or 4 safety output points per unit ·Free allocation of the safety I/O units on the internal high speed bus

Safety CPU

·EN ISO13849-1 (PLe/Safety Category 4), IEC 61508 (SIL3) certified



Temperature inputs

·Thermocouple or RTD inputs, 2 or 4 per unit ·Conversion time of 10 ms, 60 ms or 250 ms

Heater burnout detection

4 CT sensor inputs and 4 trigger outputs to



Temperature control

- 2 or 4 multi-input (thermocouple and resistance thermometer)
- channels per unit
- ·Conversion time of 50 ms · Voltage output (for driving SSR) or linear current output
- · 1 CT input per channel



Position interface

- ·Incremental and absolute encoder support
- ·Pulse output unit (line driver output model)

Series	NX Series		
Features	· Over 100 models including digital I/O, analog I/O, position interface, temperature inputs, temperature control, RFID, safety CPU, and safety I/O · NsynX technology provides I/O response with less than 1 µs jitter · Screwless terminal block, connector, and M3 screw types · Up to 32 channels per digital input unit or output unit		
Appearance			
Туре	Modular I/O		
Communications interface	EtherCAT		
Number of connectable units	- 63 units max. - Input: 1,024 bytes max., output: 1,024 bytes max.		
Unit types	Communications coupler, IO-Link master, serial communication, RFID, digital I/O, analog I/O, high-speed analog input, load cell input, safety I/O, safety CPU, temperature input, heater burnout detection, temperature control, position interface		
Mounting	DIN track		
Detailed specification Catalog	R183		

 $[\]ensuremath{^{*}}$ See page 27 for more information on safety I/O.

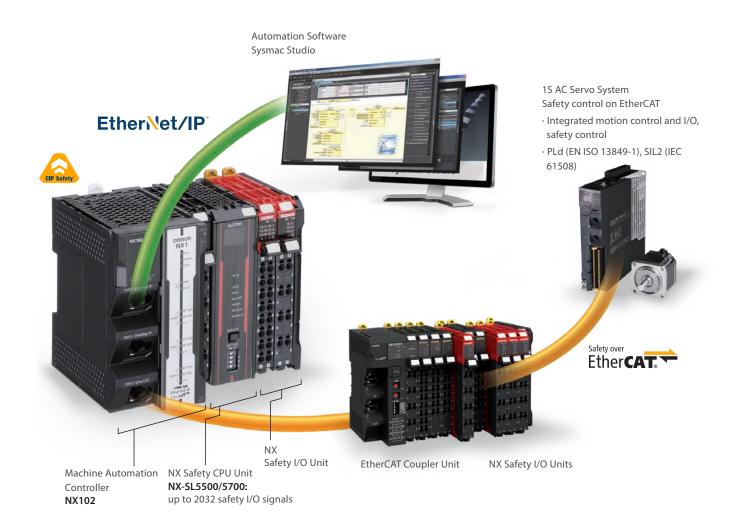
Series	GX Series
Features	Detachable screw terminal block and e-CON connector types Easy set-up: automatic and manual address setting
Appearance	0000
Туре	Block I/O
Communications interface	EtherCAT
Number of connectable units	One expansion unit can be connected with one digital I/O terminal (16 inputs + 16 outputs)
I/O types	Digital I/O, analog I/O, encoder input, IO-Link master, expansion unit
Mounting DIN track	
Detailed specification	Refer to your OMRON website.

Safety

NX-SL/SI/SO **NX Safety Controller**

Integrated safety into machine automation

- ·The safety controller meets PLe according to the ISO 13849-1 and SIL3 according to IEC 61508
- \cdot Flexible system lets you freely mix safety controller and safety I/O units with standard NX I/O
- · Integration in One software, Sysmac Studio
- · Certified programs can be reused, which reduces the amount of verification work



Safety Controller

Product name	Safety CPU Unit		
Model	NX-SL5500/5700	NX-SL3300/3500	
Two different networks, Safety over EtherCAT (FSoE) and EtherNet/IP (CIP Safety), in a single system Line safety control and fast machine control at the same time Sysmac Studio version 1.24 or higher for hardware configuration and programming Flexible Safety system building Optimal I/O building		Integrated safety into machine automation through the use of Safety over EtherCAT -FSoE- protocol. Freely mixing with standard NX I/O Sysmac Studio version 1.07 or higher for hardware configuration and programming Flexible Safety system building Optimal I/O building	
Appearance	I trittel [] passing		
Network	Safety over EtherCAT (FSoE), EtherNet/IP (CIP Safety)	Safety over EtherCAT (FSoE)	
Applicable standards	EN ISO 13849-1 (PLe/Safety Category 4), IEC 61508(SIL3), IEC/EN 62061(SIL CL3), IEC/EN 61131-2 , IEC 6132-3-1, IEC 61131-6	EN ISO 13849-1 (PLe/Safety Category 4), IEC 61508 (SIL3), EN 62061 (SIL CL3), IEC/EN 61131-2, IEC 6132-3-1	
Programming	· IEC 61131-3 standard · PLCopen Function Blocks for Safety		
Program capacity	2048 KB, 4096 KB	512 KB, 2048 KB	
Safety I/O connection	128/254	32/128	
Maximum number of safety I/O points	1024, 2032	256, 1024	
Units that can connect	NX102 CPU Unit, Communication Control Unit	NX102 CPU Unit, EtherCAT Coupler Unit, EtherNet/IP Coupler Unit	
Detailed specification	Catalog: F104	Refer to your OMRON website.	

Product name	Safety Input Unit	Safety Output Unit	
Model	NX-SIH400/SID800	NX-SOH200/SOD400	
Appearance			
Applicable standards	EN ISO 13849-1 (PLe/Safety Category 4), IEC 61508(SIL3), IEC/EN 62061(SIL CL3), IEC/EN 61131-2, IEC 6132-3-1		
Number of safety input/ output points	4,8	2, 4	
Detailed specification	Refer to your OMRON website.		

Vision

FΗ Vision System

Flexible solution for machine vision

The FH Vision System is optimized to detect the position and orientation of any object at high speed and with high accuracy. The built-in EtherCAT communications enable reliable and easy networking with motion control, increasing the overall machine performance. A flexible machine vision tailored for quality inspection.



Wide camera range

- · Up to 20.4 M pixel
- · High speed CMOS camera
- · Use different fields of vision and at any angle



Advanced shape search technology

- · Differences of the work piece
- · Dust and dirt conditions
- · Detection of overlapping objects
- · Changing ambient environment







Thinning and thickening

Unique light

· The MDMC light flexibly changes illumination colors and angles according to items to measure.



Multiple inspection

- · Powerful 4-core i7 parallel processor
- · Up to 8 camera by one controller



FQ-M Vision Sensor

Designed for object tracking

The FQ-M Series is a vision sensor designed specifically for pick and place applications. Up to 5,000 pieces per minute with 360 degree rotation can be detected. The FQ-M series include an incremental encoder input for easy tracking and calibration.



Compact design

Camera and image processing in one

Standard C-mount lenses; choose the field of view and focus distance you need

- Flexible cables
- · Vision sensor with encoder input for tracking function

Ether CAT.

Advanced shape search technology

Varying material ie. shiny



Overlapping products



Product detection: 10 pcs with rotation < 200 ms



Product name		Smart Camera	Vision System	
Series		FQ-M Series	FH Series	
Appearance				
Hardware features		· Camera and image processing in one · Easy to installation	Flexible configuration of cameras and controller to suit your applications	
Software feature		Communication wizard for easy setting	Flexible setting with flowchart	
Processing items		Processing items for Pick & Place applications	Processing items covering general applications	
	0.4 Mpix	752 (H)×480 (V)	720 (H)×540 (V)	
Processing resolu- tion	5 Mpix	_	2448 (H)×2048 (V)	
20.4 Mpix		_	5544 (H)×3692 (V)	
Communications interfaces		EtherCAT, Ethernet, Parallel I/O, encoder input		
Detailed specification	Catalog	Q183	Q197	

Sensing

ZW-8000/7000 Confocal Fiber Displacement Sensor

Measure anything from anywhere The most reliable in-line measurements

The ZW-8000 Series provides high-precision in-line measurements of rattling or inclined shiny, thin, or minute parts. The ZW-7000 Series provides ultra-high-speed, stable measurements of diffuse reflective objects during movement. These sensors help increase quality inspection accuracy and reduce inspection time.



Reliable measurements for any material and surface types

The white light confocal principle allows a continuous measurement of object in any mixed conditions such as mirror, coarse, transparent, curved, or narrow areas without stopping the sensor head.



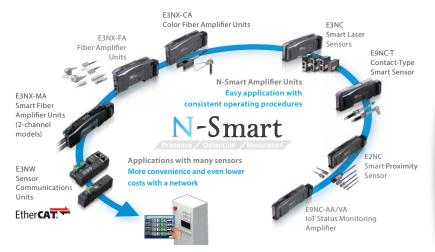
- · Angle characteristic: ±25° for shiny surfaces
- \cdot Linearity for different materials: $\pm 0.3~\mu m$
- · Minimum sampling period: 20 μs
- · Minimum spot diameter: 4 μm

Note: Specifications differ among models. Please ask Omron sales representative for details.

E3NX/E3NC/E9NC Series N-Smart Series

Various sensors connected over EtherCAT

The N-Smart lineup of next-generation fiber sensors, laser sensors and contact sensors will quickly solve your problems and therefore maximize uptime and minimize downtime with optimum cost performance.



Features

- Ultra-easy Advanced Smart Tuning with the push of a button
- More stable detection of high-speed workpieces
- Predictive maintenance to reduce downtime
- Highly visible white LED display
- E3NX-FA has 1.5x the sensing distance of conventional amplifiers*

* Compared with E3X-HD

Product nan	ne	Confocal Fiber Displacement Sensor	Confocal Fiber Displacement Sensor				
Series		ZW-8000 Series	ZW-7000 Series	ZW-5000 Series			
Feature		For measurements of rattling or inclined "transparent objects or mirror surfaces" such as thin film sheets or glass	For accurate shape measurements of "coarse surfaces" while the sensor head is moving	Bring the benefits of the white light confocal principle to production lines			
Appearance							
Measurement	method	White light confocal principle					
Measuring rar	ige	Min : 7±0.3 mm, Max : 30±2 mm					
Static resoluti	on	0.002 to 0.016 µm					
Linearity		±0.3 to ±3.0 µm					
Spot diameter		4 to 11 μm	50 to 190 μm	9 to 20 μm			
Measurement cycle		60 to 7500 μs	20 to 400 μs	80 to 1600 μs			
Detailed	Catalog	Q250					
specification							

Product name		Fiber Sensor/Laser Sensor/Proximity Sensor/Contact Sensor			
Series		N-Smart Series	E3X/E3C/E2C		
Feature		Connect fiber, laser and contact sensors to EtherCAT at low initial cost	Easily connect fiber, laser photoelectric and proximity sensors to EtherCAT		
Appearance					
Network specification		EtherCAT communication unit	EtherCAT communication unit		
Sensor Communica- tions Units		E3NW-ECT/DS	E3X-ECT		
Connectable sensor amplifier units		Fiber Sensor E3NX-FA0 E3NX-CA0 Laser Sensor E3NC-LA0 E3NC-SA0 Contact Sensor E9NC-TA0 IoT Status Monitoring Amplifier E9NC-AA0/VA0	Fiber Sensor E3X-HD0 E3X-MDA0 Laser Sensor E3C-LDA0 Proximity Sensor E2C-EDA0		
Maximum number of connectable sensors		30	30		
Detailed specification	Catalog	E3NW: E418 E3NX-FA: E418 E3NX-CA: Y216 E9NC-T: E434 E9NC-AA/VA: E474	_		
	Web	Refer to your OMRON website.			

Robot

Hornet/Quattro, Cobra/eCobra, Viper Parallel Robot, SCARA Robot, Articulated Robot

Robots for flexible production lines

Parallel, SCARA, and articulated robots are designed to be programmed using familiar programming languages (IEC 61131-3) through the NJ/NX/NY Controller that is connected to the robots via EtherNet/IP.

Parallel robots

The Hornet and Quattro are parallel robots ideal for use in the food and beverage, pharmaceutical, and healthcare industries. The Quattro that is a four-axis parallel robot with a high payload capacity achieves high speed and high precision.

- · Fast and high-precision conveyance and assembly
- · Supports fast Pick & Place on a fast conveyor
- · Maximum working range: 1130, 1300, and 1600 mm models



SCARA robots

High-performance four-axis SCARA robots are ideal for mechanical assembly, material handling, packaging, machine tending, and screw driving.

Table/floor or Inverted mounting models are available.

- · High repeatability suitable for material handling and precision assembly
- · Reach: 450, 500, 600, 650, and 800 mm models



Articulated robots

Six-axis articulated robots are ideal for mechanical assembly, material handling, packaging, and palletizing.

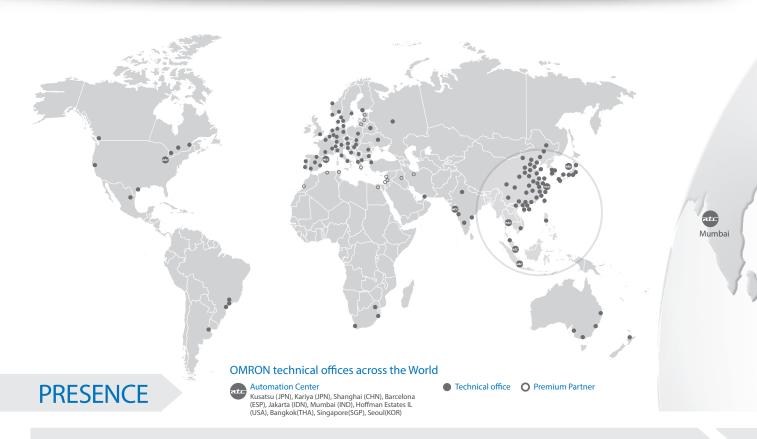
- · Diagnostics display enables faster trouble shooting
- · High accuracy, superior slow-speed following, and easy calibration
- · Reach: 653 and 855 mm models



Series		Hornet 565	Quattro 650/800	Cobra 450/500/650	
Feature		Parallel robot ideal for use in the food and beverage, pharmaceutical, and healthcare industries	Four-axis parallel robot achieves high speed and high precision	Mid-size SCARA robot for material han- dling, assembly, precision machining and adhesive application	
Appearance					
Robot type		Parallel robot	Parallel robot	SCARA robot	
Number of axes		3, 4	4	4	
Mounting		Inverted	Inverted	Table/Floor	
Payload capacity		3 kg (8 kg: without rotation axis)	· Quattro 650 6 kg (No rotation: 15 kg) · Quattro 800 4 kg (No rotation: 10 kg)	5 kg	
Working volume (radius)		565 mm	650 to 800 mm	_	
Reach		_	_	450 to 650 mm	
Position repeatability		±0.10 mm	±0.10 mm	±0.02 mm	
Protection/ Cleanroom classes	Specifications	IP67: arms and platform IP65: underside of robot IP20: topside of robot	· H type IP67: arms and platform IP65: underside of robot IP20: topside of robot · HS type IP67: arms and platform IP66: robot base	IP20	
	Option	IP65: topside of robot (with optional cover)	H type IP65: topside of robot (with optional cover)	_	
Detailed specification Catalog		1822			

Series		eCobra 600/800	eCobra 800 Inverted	Viper 650/850	
Feature		Mid-size/large SCARA robot for precision machining, assembly, and material handling	Overhead-mount large SCARA robot for precision machining, assembly, and material handling	Articulated robot for machining, assembly, and material handling	
Appearance				· Ari	
Robot type		SCARA robot	SCARA robot	Articulated robot	
Number of axes		4	4	6	
Mounting		Table/Floor	Inverted	Table/Floor/Inverted	
Payload capacity		5.5 kg	5.5 kg	5 kg	
Working volume (radius)		_	_	_	
Reach		600 to 800 mm	800 mm	635 to 855 mm	
Position repeatability		±0.017 mm	±0.017 mm	±0.02 to 0.03 mm	
Protection/ Cleanroom classes	Specifications	IP20	IP20	IP40	
	Option	· eCobra 600 Class10 Cleanroom model · eCobra 800 IP65, Class10 Cleanroom model	IP65, Class10 Cleanroom model	IP54: robot main body IP65: robot joints (J4, J5, J6) Class10 Cleanroom model	
Detailed Specification Catalog		1822			

Service and support



COMPETENCE



Design

Our wi de net work of machine automation specialists will help you to select the right automation architecture and products to meet your requirements. Our flat structure based on expert-to-expert contact ensures that you will have ONE accountable and responsible expert to deal with on your complete project.



Proof of concept

As your project matures make use of our Automation centers to test and catch-up with technology trends in motion, robotics, networking, safety, quality control etc. and to interface, test and validate your complete system with our new machine network (EtherCAT) and factory network (EtherNet/IP).

We will assign a dedicated application engineer to assist with initial programming and proof testing of the critical aspects of your automation system. Our application engineers have indepth expertise in and knowledge of networks, PLCs, motion, safety and HMIs when applied to machine automation.





Service & Support **Networks**



CONFIDENCE

Jakarta Selatan

Beijing

Guangzhou Hong Kong

X'i an

Hanoi

Kuala Lumpur

Bangkok

Dailian

SHANGHAI

Seoul

ASSURANCE



Development

During your prototyping phase you will need flexibility in technical support, product supply and exchange. We will assign an inside sales contact to help you source the correct products fast during your prototyping phase.



Commissioning

With our world-wide network for service and support the export of your product is made simple, we will support you on-site with your customer, anywhere in the world. We can arrange a liaison sales engineer to facilitate training, spare parts supply or even machine commissioning. All this in a localised language with localised documentation - giving you complete peace of mind.



Serial production

As your production increases we will engage in supplying you within 24hrs and repairing within 3 days. All our products are global products meeting global standards - CE, cULus, NK, LR -

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