K3HB

**Digital Indicators** 

Communications

Manual

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Overview

# **Digital Indicators**

# K3HB

# **Communications User's Manual**



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# **K3HB Digital Indicators**

# **Communications User's Manual**

Produced February 2004

# **Preface**

OMRON products are manufactured for use according to proper procedures by a qualified operator and only for the purposes described in this manual.

This manual describes the functions, performance, and application methods needed for optimum use of the K3HB.

Please observe the following items when using the K3HB.

- This product is designed for use by qualified personnel with a knowledge of electrical systems.
- Read this manual carefully and make sure you understand it well to ensure that you are using the K3HB correctly.
- Keep this manual in a safe location so that it is available for reference when required.

# Visual Aids

The following headings appear in the left column of the manual to help you locate different types of information.

**Note** Indicates information of particular interest for efficient and convenient operation of the product.

1,2,3... 1. Indicates lists of one sort or another, such as procedures, checklists, etc.

# **Trademarks**

- DeviceNet is a registered trademark of the Open DeviceNet Vendors Association, Inc.
- Other product names and company names that appear in this manual are the trademarks or registered trademarks of the respective companies.

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# Read and Understand this Manual

Please read and understand this manual before using the product. Please consult your OMRON representative if you have any questions or comments.

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The following are some examples of applications for which particular attention must be given. This is not intended to be an exhaustive list of all possible uses of the products, nor is it intended to imply that the uses listed may be suitable for the products.

- Outdoor use, uses involving potential chemical contamination or electrical interference, or conditions or uses not described in this manual.
- Nuclear energy control systems, combustion systems, railroad systems, aviation systems, medical
  equipment, amusement machines, vehicles, safety equipment, and installations subject to separate
  industry or government regulations.
- Systems, machines, and equipment that could present a risk to life or property.

Please know and observe all prohibitions of use applicable to the products.

NEVER USE THE PRODUCTS FOR AN APPLICATION INVOLVING SERIOUS RISK TO LIFE OR PROPERTY WITHOUT ENSURING THAT THE SYSTEM AS A WHOLE HAS BEEN DESIGNED TO ADDRESS THE RISKS, AND THAT THE OMRON PRODUCTS ARE PROPERLY RATED AND INSTALLED FOR THE INTENDED USE WITHIN THE OVERALL EQUIPMENT OR SYSTEM.

# **PROGRAMMABLE PRODUCTS**

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# **Disclaimers**

#### **CHANGE IN SPECIFICATIONS**

Product specifications and accessories may be changed at any time based on improvements and other reasons.

It is our practice to change model numbers when published ratings or features are changed, or when significant construction changes are made. However, some specifications of the products may be changed without any notice. When in doubt, special model numbers may be assigned to fix or establish key specifications for your application on your request. Please consult with your OMRON representative at any time to confirm actual specifications of purchased products.

#### **DIMENSIONS AND WEIGHTS**

Dimensions and weights are nominal and are not to be used for manufacturing purposes, even when tolerances are shown.

#### PERFORMANCE DATA

Performance data given in this manual is provided as a guide for the user in determining suitability and does not constitute a warranty. It may represent the result of OMRON's test conditions, and the users must correlate it to actual application requirements. Actual performance is subject to the OMRON Warranty and Limitations of Liability.

#### **ERRORS AND OMISSIONS**

The information in this document has been carefully checked and is believed to be accurate; however, no responsibility is assumed for clerical, typographical, or proofreading errors, or omissions.

# **Safety Precautions**

# **■** Definition of Precautionary Information

The following notation is used in this manual to provide precautions required to ensure safe usage of the product.

The safety precautions that are provided are extremely important to safety. Always read and heed the information provided in all safety precautions.

The following notation is used.



Indicates a potentially hazardous situation which, if not avoided, will result in minor or moderate injury, or may result in serious injury or death. Additionally there may be significant property damage.



Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury or in property damage.

# **■** Symbols

Symbol		Meaning	
Courties	$\triangle$	General Caution Indicates non-specific general cautions, warnings, and dangers.	
Caution		Electrical Shock Caution Indicates possibility of electric shock under specific conditions.	
Prohibition	$\bigcirc$	General Prohibition Indicates non-specific general prohibitions.	
Mandatory Caution	0	General Caution Indicates non-specific general cautions, warnings, and dangers.	

# **■** Precautions

<b>⚠ WARNING</b>	
Do not touch the terminals while power is being supplied. Doing so may possibly result in electric shock. Make sure that the terminal cover is installed before using the product.	A
Always provide protective circuits in the network. Without protective circuits, malfunctions may possibly result in accidents that cause serious injury or significant property damage. Provide double or triple safety measures in external control circuits, such as emergency stop circuits, interlock circuits, or limit circuits, to ensure safety in the system if an abnormality occurs due to malfunction of the product or another external factor affecting the product's operation.	0

<b>⚠ CAUTION</b>	
Do not allow pieces of metal, wire clippings, or fine metallic shavings or filings from installation to enter the product. Doing so may occasionally result in electric shock, fire, or malfunction.	
Do not use the product in locations where flammable or explosive gases are present. Doing so may occasionally result in minor or moderate explosion, causing minor or moderate injury, or property damage.	$\Diamond$
Do not attempt to disassemble, repair, or modify the product.  Doing so may occasionally result in minor or moderate injury due to electric shock.	
Do not use the equipment for measurements within Measurement Categories III and IV for K3HB-X and II, III, and IV for K3HB-S, K3HB-V, and K3HB-H (according to IEC61010-1). Doing so may occasionally cause unexpected operation, resulting in minor or moderate injury, or damage to the equipment. Use the equipment for measurements only within the Measurement Category for which the product is designed.	
Perform correct setting of the product according to the application. Failure to do so may occasionally cause unexpected operation, resulting in minor or moderate injury, or damage to the equipment.	
Ensure safety in the event of product failure by taking safety measures, such as installing a separate monitoring system. Product failure may occasionally prevent operation of comparative outputs, resulting in damage to the connected facilities and equipment.	<b>Q</b>
Tighten the screws on the terminal block and the connector locking screws securely using a tightening torque within the following ranges. Loose screws may occasionally cause fire, resulting in minor or moderate injury, or damage to the equipment. Terminal block screws: 0.43 to 0.58 N⋅m Connector locking screws: 0.18 to 0.22 N⋅m	

# **⚠** CAUTION

Make sure that the product will not be adversely affected if the DeviceNet cycle time is lengthened as a result of changing the program with online editing. Extending the cycle time may cause unexpected operation, occasionally resulting in minor or moderate injury, or damage to the equipment.



Before transferring programs to other nodes or changing I/O memory of other nodes, check the nodes to confirm safety. Changing the program or I/O memory of other nodes may occasionally cause unexpected operation, resulting in minor or moderate injury, or damage to the equipment.

# Precautions for Safe Use

- (1) Do not use the product in the following locations.
  - · Locations subject to direct radiant heat from heating equipment
  - · Locations where the product may come into contact with water or oil
  - · Locations subject to direct sunlight
  - Locations where dust or corrosive gases (in particular, sulfuric or ammonia gas) are present
  - Locations subject to extreme temperature changes
  - · Locations where icing or condensation may occur
  - · Locations subject to excessive shocks or vibration
- (2) Do not use the product in locations subject to temperatures or humidity levels outside the specified ranges or in locations prone to condensation. If the product is installed in a panel, ensure that the temperature around the product (not the temperature around the panel) does not go outside the specified range.
- (3) Provide sufficient space around the product for heat dissipation.
- (4) Use and store the product within the specified temperature and humidity ranges. If several products are mounted side-by-side or arranged in a vertical line, the heat dissipation will cause the internal temperature of the products to rise, shortening the service life. If necessary, cool the products using a fan or other cooling method.
- (5) The service life of the output relays depends on the switching capacity and switching conditions. Consider the actual application conditions and use the product within the rated load and electrical service life. Using the product beyond its service life may result in contact welding or burning.
- (6) Install the product horizontally.
- (7) Mount to a panel between 1 and 8-mm thick.
- (8) Use the specified size of crimp terminals (M3, width: 5.8 mm max.) for wiring. To connect bare wires, use AWG22 (cross section: 0.326 mm²) to AWG14 (cross section: 2.081 mm²) to wire the power supply terminals and AWG28 (cross section: 0.081 mm²) to AWG16 (cross section: 1.309 mm²) for other terminals. (Length of exposed wire: 6 to 8 mm)
- (9) In order to prevent inductive noise, wire the lines connected to the product separately from power lines carrying high voltages or currents. Do not wire in parallel with or in the same cable as power lines. Other measures for reducing noise include running lines along separate ducts and using shield lines.
- (10) Ensure that the rated voltage is achieved no longer than 2 s after turning the power ON.
- (11) Allow the product to operate without load for at least 15 minutes after the power is turned ON.
- (12) Do not install the product near devices generating strong high-frequency waves or surges. When using a noise filter, check the voltage and current and install it as close to the product as possible.
- (13) Do not use thinner to clean the product. Use commercially available alcohol.
- (14) Be sure to confirm the name and polarity for each terminal before wiring the

- terminal block and connectors.
- (15) Use the product within the noted supply voltage and rated load.
- (16) Do not connect anything to unused terminals.
- (17) Output turns OFF when the mode is changed or settings are initialized. Take this into consideration when setting up the control system.
- (18) Install an external switch or circuit breaker that complies with applicable IEC60947-1 and IEC60947-3 requirements and label them clearly so that the operator can quickly turn OFF the power.
- (19) Use the specified cables for the communications lines and stay within the specified DeviceNet communications distances.
- (20) Do not pull the DeviceNet communications cables with excessive force or bend them past their natural bending radius.
- (21) Do not connect or remove connectors while the DeviceNet power is being supplied. Doing so will cause product failure or malfunction.
- (22) Use cables with a heat resistance of 70°C min.

# **EC Directives**

EMC Directives

# **Concepts**

#### **EMC Directives**

OMRON devices that comply with EC Directives also conform to the related EMC standards so that they can be more easily built into other devices or the overall machine. The actual products have been checked for conformity to EMC standards. Whether the products conform to the standards in the system used by the customer, however, must be checked by the customer.

EMC-related performance of the OMRON devices that comply with EC Directives will vary depending on the configuration, wiring, and other conditions of the equipment or control panel on which the OMRON devices are installed. The customer must, therefore, perform the final check to confirm that devices and the overall machine conform to EMC standards.

# Conformance to EC Directives

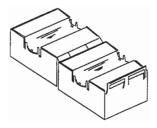
The K3HB Digital Indicators comply with EC Directives. To ensure that the machine or device in which the Unit is used complies with EC Directives, the Unit must be installed as follows:

- **1,2,3...** 1. You must use reinforced insulation or double insulation for the DC power supplies used for the communications power supply, internal power supply, and I/O power supplies.
  - Units complying with EC Directives also conform to the Common Emission Standard (EN61326). Radiated emission characteristics (10-m regulations) may vary depending on the configuration of the control panel used, other devices connected to the control panel, wiring, and other conditions. You must therefore confirm that the overall machine or equipment complies with EC Directives.

The following example shows one means of reducing noise.

Noise from the communications cable can be reduced by installing a ferrite core on the communications cable within 10 cm of the DeviceNet Master Unit.

Ferrite Core (Data Line Filter): 0443-164151 (manufactured by Fair-Rite Products Co., Ltd.)



Impedance specifications					
25 MHz	105 Ω				
100 MHz	190 Ω				

- 2. Wire the control panel with as thick and short electric lines as possible and ground to 100  $\Omega$  min.
- 3. Keep DeviceNet communications cables as short as possible and ground to 100  $\Omega$  min.

# **Complying with Safety Standards**

For the DeviceNet power supply, always use a power supply with reinforced or double insulation, that complies with EN/IEC standards.

Conformance to the standards is for indoor applications only.

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# About this Manual:

This manual describes communications for the K3HB Digital Indicators and includes the sections described below divided into two parts according to the type of communications.

Please read this manual carefully and be sure you understand the information provided before attempting to setup or operate communications for a K3HB Digital Indicator.

# Part 1: CompoWay/F

Section 1 describes CompoWay/F communications.

Section 2 provides a list of K3HB settings.

# Part 2: DeviceNet

**Section 1** introduces the features and specifications of K3HB-DRT Digital Indicators.

Section 2 outlines the basic operating procedures for the K3HB-DRT Digital Indicators.

Section 3 describes the methods used to install and wire K3HB-DRT Digital Indicators.

**Section 4** describes the input (IN) areas and output (OUT) areas that K3HB-DRT Digital Indicators can use for remote I/O communications. The methods to allocate data for master communications are also described using sample programming.

**Section 5** describes how to send explicit messages to the K3HB-DRT Digital Indicator, including how to send CompoWay/F commands using explicit messages.

**Section 6** provides information on the time required for a complete communications cycle, for an output response to be made to an input, to start the system, and to send messages.

**Section 7** describes error processing, periodic maintenance operations, and troubleshooting procedures needed to keep the DeviceNet Network operating properly. Details on resetting replaced Digital Indicators are also provided. Read through the error processing procedures in both this manual and the operation manual for the DeviceNet master being used before operation so that operating errors can be identified and corrected more quickly.

**Section 8** provides DeviceNet specifications, tables of mounted objects, and tables of DeviceNet connection hardware.

**WARNING** Failure to read and understand the information provided in this manual may result in personal injury or death, damage to the product, or product failure. Please read each section in its entirety and be sure you understand the information provided in the section and related sections before attempting any of the procedures or operations given.

# Part 1: CompoWay/F

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# Part 1: CompoWay/F

# SECTION 1 CompoWay/F Communications

This section describes communications using CompWay/F.

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# 1-1 Communications Method

# 1-1-1 CompoWay/F Communications Protocol

CompoWay/F is OMRON's unified protocol for general purpose serial communications. Featuring a unified frame format and commands that are compliant with FINS, which has a record of successful use with OMRON programmable controllers, CompoWay/F makes communications easy between multiple components and a computer.

## **FINS (Factory Interface Network Service)**

This is a protocol for message communications between controllers on an OMRON factory automation network.

## Supplement

The communications function is used by creating a program on the host computer. As such, the explanations in this chapter are from the perspective of the host computer

For example, "Read/Write" refers to the host computer reading or writing to the K3HB.

# 1-1-2 Communications Specifications

Transfer connection: Multi-point

Communications method: RS-485 or RS-232C (half duplex)

Synchronization method: Start-stop

Baud rate: 9.6k, 19.2k, 38.4k bit/s

Send code: ASCII

Data length: 7 or 8 bits

Stop bit length: 1 or 2 bits

Error detection: Vertical parity (none, even, or odd)

BCC (Block Check Character)

Start-stop synchronized data configuration

Flow control: None

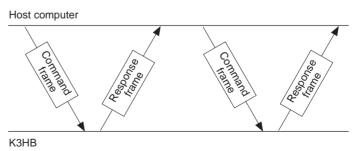
Interface: RS-485 or RS-232C

Retry function: None

**Note** Initial settings are shaded.

# 1-1-3 Transfer Protocol (CompoWay/F Communications)

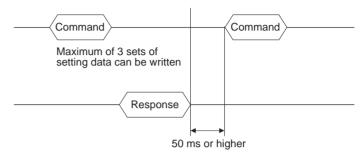
The host computer sends a command frame, and the K3HB sends a response frame based on the content of the command frame. One response frame is sent in response to one command frame.



The exchange between the command frame and response frame is explained below.

After a receiving a response from the Digital Indicator, have the host computer wait at least 50 ms before sending the next command.

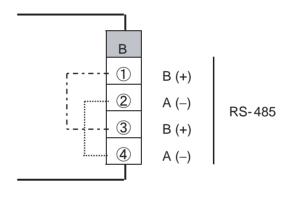
When writing multiple sets of setting data in a row, such as when writing to the variable area or performing a compound write, controllability may be affected. Pay attention to the following points:



# 1-1-4 Cable Connections

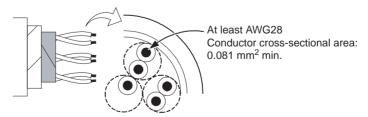
#### **RS-485**

	Α	В	С	D	Е	
1		DC 405				1
2		RS-485				2
3		RS-485				3
4		110-405				4
5						5
6						6



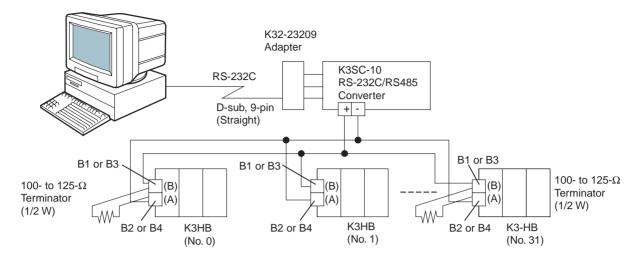
- Use terminals B1 through B4 to communicate with the host. The terminal layout is designed for cross-over wiring and thus the B1-B3 and B2-B4 terminals are connected internally.
- Wiring is configured either 1:1 or 1:N. A maximum of 32 Units, including the host computer can be connected with a 1:N configuration.
- The maximum total cable length is 500 m.
- Use shielded, twisted-pair wires of at least AWG28 to AWG16 for all cables.

#### Cable Diagram (Reference)



- Attach a terminator to each end of the transmission path, including the host computer. Use a 100- to 125- $\Omega$  (1/2 W) resistor for the terminator.
- Use an RS-232C/RS-485 Converter to connect RS-232C devices, such as personal computers.

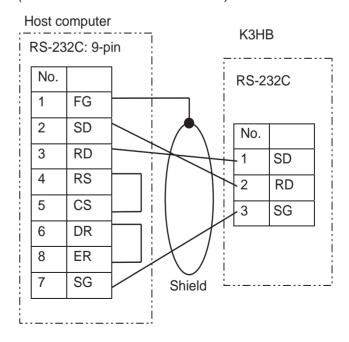
# Converter Example: RS-232C/RS-485 Converter



## **RS-232C**

	Α	В	С	D	Е		
1						1	
2		RS-232C				2	В
3						3	① SD
4						4	② RD RS-232C
5						5	② RD RS-232C ③ SG
6						6	

- Use terminals B1 through B3 to communicate with the host.
- Wiring is configured 1:1.
- The maximum cable length is 15 m. Use OMRON's Z3RN RS-232C Optical Interface to extend the wiring path.
- Use shielded, twisted-pair wires of at least AWG28 to AWG16 for all cables. (Same wire used for RS-485 cable.)



# 1-2 Frames (CompoWay/F Communications)

Based on CompoWay/F protocol, commands from the host computer and responses from the K3HB take the form of frames.

The data comprising command frames and response frames are explained below.

In the following explanation, an "H" following a numeric value (for example 02H) indicates that the value is a hexadecimal number. A number or letters enclosed in quotation marks (for example "00") is an ASCII character.

# 1-2-1 Command Frame

STX	Node No.	Sub- address	SID	FINS-mini command text	ETX	всс
02H	1	"00"	"0"	1 1 1	03H	
1	2	2	1		1	1 byte
		BCC c	alcul	ation range		

STX	Code that indicates the beginning of the communications frame (02H).
	Be sure to set this code in the leading byte.
Node No.	This number specifies the destination.
	Specify the Unit No. of the K3HB.
	When broadcasting to all units, specify "XX". Responses are not sent to a broadcast.
Sub-address	Not used on the K3HB. Be sure to set to "00".
SID (Service ID)	Not used on the K3HB. Be sure to set to "0".
FINS-mini Command text	The text of the command.
ETX	Code that indicates the end of the text (03H).
BCC	Block Check Character.
	This stores the result of the BCC calculation from Node No. to EXT.

STX	Node No.	address	SID		INS-m nman	nini d text	ETX	всс			
02H	30H <sub>,</sub> 30H	30H <sub>,</sub> 30H	30H	30H <sub>1</sub> 3	35H <sub>1</sub> 30	0H <sub>1</sub> 30H	H03H	36H			
DCC	2011	2011 2 20	211.6	2011	T 2011	o 201	1 0 25		0110	2011.0	0211

BCC = 30H  $\oplus$  03H = 36H  $\oplus$  XOR (exclusive OR) operation

# 1-2-2 Response Frame

STX	Node No.	Sub- address	End Code	FINS-mini response text	ETX	всс
02H		"00"		1 1 1	03H	
1	2	2	2		1	1 byte

## **Supplement**

A response is not sent to command frames that do not end with ETX.BCC characters.

STX	Code that indicates the beginning of the communications frame (02H).			
	Be sure to set this code in the leading byte.			
Node No.	The number that was specified in the command frame is repeated here.			
	This is the Unit No. of the responding K3HB.			
Sub-address	Not used on the K3HB. Set to "00".			

FINS-mini Text Section 1-3

End code	Returns the result of the command executed as instructed by the command frame.
FINS-mini Response text	Text of the response
ETX	Code that indicates the end of the text (03H)
BCC	Block Check Character
	Stores the result of the BCC calculation from Node No. to EXT.

# End Codes (CompoWay/F Communications)

End code	d code Name Description		Error detection order of priority		
"0F"	FINS command error	Could not execute the specified FINS command	8		
"10"	Parity error	Sum of bits that are "1" in received data does not agree with the set communications parity value.	2		
"11"	Framing error	Stop bit of command frame characters is "0".	1		
"12"	Overrun error	Attempted to transfer new data because received data buffer is already full.	3		
"13"	BCC error	Calculated BCC different from received BCC.	5		
"14"	Format error	Characters other than "0" to "9" or "A" to "F" in FINS-mini command text. In the case of an echo-back test, when data other than the test data is sent.	7		
		No SID and FINS-mini command text, or no FINS-mini command text.			
		"MRC/SRC" not correct in FINS-mini command text.			
"16"	Sub-address error	No sub-address, SID, or FINS-mini command text; or sub-address less than 2 characters and no SID and FINS-mini command text.	6		
"18"	Frame length error	The received frame exceeds the required number of bytes.	4		
"00"	Normal end	Command was executed normally without error. None			

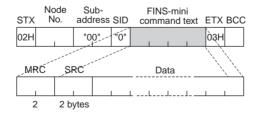
# 1-3 FINS-mini Text

The FINS-mini command text and FINS-mini response text form the body of command/response communications.

FINS-mini command text and FINS-mini response text are configured as follows.

## **Command Text**

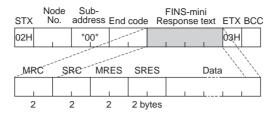
FINS-mini command text consists of an MRC (main request code) and an SRC (sub request code), followed by the required data.



FINS-mini Text Section 1-3

# Response text

FINS-mini response text consists of the MRC and SRC, followed by an MRES (main response code) and SRES (sub response code), and then the required data.



If the specified FINS-mini command was not successfully executed, the response will only contain the MRC, SRC, MRES and SRES.

# List of FINS-mini Service Commands (CompoWay/F Communications)

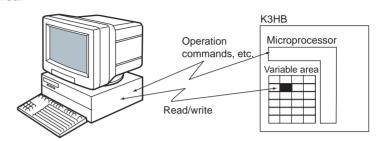
MRC	SRC	Service name	Description
"01"	"01"	Monitor value/setting data read	Reads monitor values/setting data.
"01"	"02"	Monitor value/setting data write	Writes monitor values/setting data.
"01"	"04"	Monitor value/setting data compound read	Performs multiple reads of monitor values/setting data.
"01"	"13"	Monitor value/setting data compound write	Performs multiple writes of monitor values/setting data.
"01"	"10"	Monitor value/setting data compound stored read	Sequentially reads contents of addresses specified in "monitor value/setting data compound read store."
"01"	"11"	Monitor value/setting data compound read store (write)	Specifies addresses to be read using "monitor value/setting data compound stored read."
"01"	"12"	Monitor value/setting data compound read store check (read)	Reads the contents stored using "variable area compound read store."
"05"	"03"	Machine attribute read	Reads the model and other attributes.
"06"	"01"	Controller status read	Reads the operation status.
"08"	"01"	Echo-back test	Performs an echo-back test.
"30"	"05"	Operation command	Commands such as Run/Stop, AT Execute/Cancel, and "Move to setting area 1".

Variable Areas Section 1-4

# 1-4 Variable Areas

The area used for data exchange when communicating with the K3HB is called the "variable area." The PV is read and various setting data are read and written using the variable area of the K3HB.

Operation commands and reading of machine attributes do not use the variable area.



A variable area is accessed by specifying the position of a variable within the variable area using the variable type and address.

#### Variable Types

Variable types in variable areas are as follows:

Variable type	Description	Area
C0	Read-only parameters	Setting area 0
C1	Protect level	(during operation)
C2	RUN level	
C4	Initial setting level	Setting area 1
C5	Input adjustment level	(during stop)
C6	Display adjustment level	
C8	Comparative set value level	
C9	Linear output level	
CA	Communications setting level	
СВ	Advanced function setting level	

# Addresses (CompoWay/F Communications)

Each variable type has an address. Addresses are 2 bytes long and written in hexadecimal. Addresses are assigned according to units of access size.

Address (2 bytes)															
0	0	0	0	0	0	#	#	0	A <sub>6</sub>	A <sub>5</sub>	A <sub>4</sub>	A <sub>3</sub>	$A_2$	A <sub>1</sub>	A <sub>0</sub>

For more information on addresses, refer to List of Settings on page 2-1.

#### **Number of Elements**

The number of elements is expressed as a 2-byte hexadecimal number. The specification range for the number of elements varies depending on the command. See 1-9 Commands and Responses (CompoWay/F Communications) (page 1-13) for more information.

For example, if the number of elements is 0010, the first 16 elements of data (H'10) from the address are specified.

#### **Set Values**

Values read and written to the variable area are expressed in hexadecimal and disregard the decimal point position (negative values are expressed as a two's complement).

Example: D'105.0 → H'0000041A

The variable is an 8-digit number in hexadecimal. Negative values are expressed as a two's complement. The decimal is disregarded.

For example, if the PV of the K3HB is 105.0, it will be read as H'0000041A (105.0  $\rightarrow$  1050  $\rightarrow$  H'0000041A).

# 1-5 Reading the Variable Area

The data area is read by setting the required data in the following FINS-mini command text format.

## Command

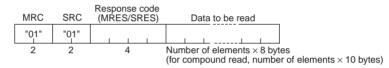
## **FINS-mini Command Text**

MRC	SRC	Variable type	Read start address	Bit position	Number of elements
"01"	"01"		1 1 1	"00"	"0001" to "0019"
2	2	2	4	2	4

Data name	Explanation				
MRC/SRC	Specifies the FINS-mini monitor value/setting data read command.				
Variable type	Specify a variable type.				
First address of read	Specify the address for the beginning of the read.				
Bit position	Not used on the K3HB. Specify "00".				
Number of elements	Specifies the number of variables to read (max. of 25 (H'19)). Not needed for a compound read.				

## Response

# **FINS-mini Response Text**



Data name	Explanation
MRC/SRC	The FINS-mini command text appears here.
Response code	Result of execution of the command.
Read data	Values for variables that were read.

# **Response Codes**

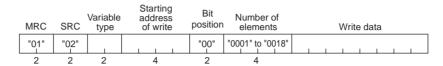
Response code	Error name	Explanation
"1001"	Command length too long	The command is too long.
"1002"	Command length too short	The command is too short.
"1101"	Area type error	Incorrect variable type.
"110B"	Response length too long	Number of elements > 25 (H'0019).
"1100"	Parameter error	Specified bit position is other than "00".
"2203"	Operation error	Unit error, unit change, display unit error, internal non-volatile memory error
"0000"	Normal end	

# 1-6 Writing to the Variable Area

Write to the data area by setting the required data in the following FINS-mini command text format.

## Command

## **FINS-mini Command Text**



Data name	Explanation	
MRC/SRC	Specifies the FINS-mini monitor value/setting data write command.	
Variable type	Specify a variable type.	
First address of write	Specify the address for the beginning of the write.	
Bit position	Not used on the K3HB. Specify "00".	
Number of elements	Specifies the number of variables to be written (max. of 24 (H'18)). Not needed for a compound write.	
Write data	Enter data to be written.	

## Response

# **FINS-mini Response Text**



Data name	Explanation
MRC/SRC	FINS-mini command text appears here.
Response code	Result of execution of the command.

## **Response Codes**

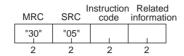
Response code	Error name	Explanation
"1002"	Command length too short	The command is too short.
"1101"	Area type error	Incorrect variable type.
"1003"	Number of elements/Data number do not agree	The specified number of elements does not agree with the actual number of data elements.
"1100"	Parameter error	Bit position specification other than "00".
		Written data was outside of setting range.
"2203"	Operation error	Write via communications is disabled.
		Write to setting area 1 was attempted from setting area 0.
		Write to setting data of protect level was attempted from other than protect level.
		Calibration level in progress.
		Unit error, unit change, display unit error, internal non-volatile memory error.
"0000"	Normal end	

# 1-7 Operation Commands (CompoWay/F Communications)

Operation commands are sent using the following FINS-mini command text format.

## Command

## **FINS-mini Command Text**



Data name	Explanation
MRC/SRC	Specify the FINS-mini operation command.
Operation code	Specify an operation code.
Related information	Specify information related to the command.

Operation commands for the K3HB are shown in the following table.

Operation code	Description	Related information
00	Write via communications	00: OFF (Disabled)
		01: ON (Enabled)
01	Reset	00
02	Bank selection	00 to 07: Bank 0 to 7
03	Zero execute/cancel	00: Zero cancel
		01: Zero execute
06	Software reset	00
07	Move to setting area 1	00
08	Move to protect level	00
0B	Initialize settings	00

#### Note

A software reset will not respond (no service PDU response).

# Response

# **FINS-mini Response Text**



Data name	Explanation
MRC/SRC	FINS-mini command text appears here.
Response code	Result of execution of the command.

## **Response Codes**

Response code	Error name	Explanation
"1001"	Command length too long	The command is too long.
"1002"	Command length too short	The command is too short.
"1100"	Parameter error	Operation code or related information is not correct.

Setting Areas Section 1-8

Response code	Error name	Explanation
"2203"	Operation error	Unable to execute because write via communications is disabled.
		Unable to execute operation command. For more information, see corresponding operation command explanation in 1-9 Commands and Responses (CompoWay/F Communications).
		Unit error, unit change, display unit error, internal non-volatile memory error
"0000"	Normal end	

# 1-8 Setting Areas

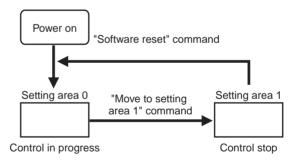
The K3HB has two setting areas for communications: Setting area 0 and setting area 1.

In setting area 0, control continues.

As such, setting area 0 makes it possible to perform operations that require control to be in progress, such as reading the PV, writing an SP, and run/stop, as well as operations that do not interfere with control. On the other hand, operations that may change control such as writing initial setting data cannot be performed. (Note that setting data that cannot be written can still be read.) In setting area 1, control is stopped.

This makes it possible to perform operations such as writing initial setting data which are not possible in setting area 0.

When the power is turned on, setting area 0 is selected. To access setting area 1, use the "Move to setting area 1" operation command. To return to setting area 0 from setting area 1, turn off the power or use the "Software reset" operation command.



Variable type	Description	Area
C0	Read-only parameters	Setting area 0 (during control)
C1	Protect level	
C2	RUN level	
C4	Initial setting level	Setting area 1 (during stop)
C5	Input adjustment level	
C6	Display adjustment level	
C8	Comparative set value level	
C9	Linear output level	
CA	Communications setting level	
СВ	Advanced function setting level	

# 1-9 Commands and Responses (CompoWay/F Communications)

The K3HB provides a set of applied commands that make use of variable area read/write commands, operation commands, and other services provided by the CompoWay/F communications protocol.

K3HB applied commands are explained below.

# 1-9-1 Monitor Value Read (CompoWay/F Communications)

## Command

MRC	SRC	Variable type	Address	Bit position	Number of elements
"01"	"01"			"00"	"0001"

Variable type	Address	Monitor value (data name)
"C0"	"0000"	Version
	"0001"	Status
	"0002"	Measurement value
	"0003"	Maximum value
	"0004"	Minimum value

This command is used to read the PV, status, and other monitor values. The number of elements can be set from 0002 to 0019 to allow reading of monitor values in contiguous addresses.

## Response

MRC	SRC	Response code	Data
"01"	"01"	"0000"	Monitor value

Response codes: The above indicates a normal end. For the response codes, see 1-5 Reading the Variable Area (page 1-9).

# 1-9-2 Setting Data Read (CompoWay/F Communications)

#### Command

MRC	SRC	Variable type	Address	Bit position	Number of elements
"01"	"01"			"00"	"0001"

Variable type	Address	Setting data (explanation)
"C1"	"0000" to "0004"	Setting data of setting area 0
"C2"		Protect level
		RUN level
"C4"	"0000" to "001F"	Setting data of setting area 1
"C5"		Initial setting level
"C6"		Input adjustment level
"C8"		Display adjustment level
"C9"		Comparison setting
"CA"		Linear output setting level
"CB"		Communications setting level
		Advanced function setting level

This command is used to read setting data. The number of elements can be set from 0002 to 0019 to allow successive reading of 2 to 25 items of setting data in contiguous addresses.

To specify the variable type or address, see *SECTION 2 List of Settings* (page 2-1). The upper limit of an address will vary depending on the variable type.

This command can be used in both setting area 0 and setting area 1.

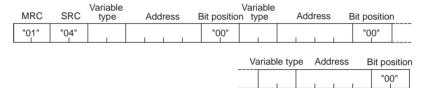
#### Response

MRC	SRC	Response code	Data
"01"	"01"	"0000"	Setting data

Response codes: The above indicates a normal end. For the response codes, see 1-5 Reading the Variable Area (page 1-9).

# 1-9-3 Monitor Value/Setting Data Compound Read (CompoWay/F Communications)

#### Command



Variable type Address		Setting data (explanation)	
"C0"	"0000" to "0004"	Monitor values	
"C1" to "C2"	"0000" to "0004"	Setting data of setting area 0	
"C4" to "C6"	"0000" to "001F"	Setting data of setting area 1	
"C8" to "CB"			

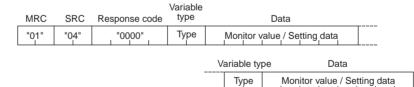
Multiple monitor values or setting data can be read by sending a single command. Up to 20 items can be read even if the addresses are not contiguous.

To specify the variable type or address, see *SECTION 2 List of Settings* (page 2-1). The upper limit of an address will vary depending on the variable type.

This command can be used in both setting area 0 and setting area 1.

If an area type error or a setting data error occurs in any of the data being read, no data will be read.

#### Response



Response codes: The above indicates a normal end. For the response codes, see 1-5 Reading the Variable Area (page 1-9).

# 1-9-4 Protect Level Setting Data Write

#### Command

MRC	SRC	Variable type	Address	Bit positio	Number of n elements	Data
"01"	"02"	"C <sub>5</sub> "	1 1 1	"00"	"0001"	Protect level setting data

Address	Setting data
"0000"	Operation adjustment protect
"0001"	Setting level protect
"0002"	Setting change protect
"0003"	Forced zero protect
"0004"	MAX/MIN protect

This command writes protect level setting data.

This command is used in setting area 0. An error will result if used in setting area 1.

To use this command, use the "Write via communications" operation command to enable "Write via communications," and then use the "Move to protect level" operation command to move to "Protect level."

#### Response

MRC	SRC	Response code
"01"	"02"	"0000"

Response codes: The above indicates a normal end. For the response codes, see 1-6 Writing to the Variable Area (page 1-10).

# 1-9-5 Setting Data Write (CompoWay/F Communications)

#### Command

MRC	SRC	Variable type	Address	Bit positio	Number of n elements	Data
"01"	"02"			"00"	"0001"	Setting data

Variable type	Address	Setting data (explanation)
"C1"	"0000" to "0004"	Setting data of setting area 0
"C2"		Protect level
		RUN level
"C4"	"0000" to "001F"	Setting data of setting area 1
"C5"		Initial setting level
"C6"		Input adjustment level
"C8"		Display adjustment level
"C9"		Comparison setting
"CA"		Linear output setting level
"CB"		Communications setting level
		Advanced function setting level

The above setting data is written. The number of elements can be set from 2 to 24 to write setting data of contiguous addresses.

To specify an address, see SECTION 2 List of Settings (page 2-1).

Setting data of setting area 1 can be written in setting area 1. An error will result if written in setting area 0.

To use this command, "Write via communications" must be enabled using the "Write via communications" operation command.

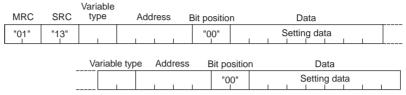
# Response

MRC	SRC	Response code
"01"	"02"	"0000"

Response codes: The above indicates a normal end. For the response codes, see 1-6 Writing to the Variable Area (page 1-10).

# 1-9-6 Setting Data Compound Write (CompoWay/F Communications)

#### Command



Variable type Address		Setting data (explanation)	
"C1" to "C2"	"0000" to "0004"	Setting data of setting area 0	
"C4" to "C6"	"0000" to "001F"	Setting data of setting area 1	
"C8" to "CB"			

Multiple setting data items can be written by sending a single command. Up to 12 items can be written even if the addresses are not contiguous.

To specify the variable type or address, see SECTION 2 List of Settings (page 2-1).

Setting data of setting area 1 is written in setting area 1. An error will result if written in setting area 0.

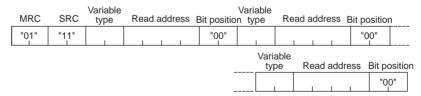
To use this command, "Write via communications" must be enabled using the "Write via communications" operation command.

#### Response

Response codes: The above indicates a normal end. For the response codes, see 1-6 Writing to the Variable Area (page 1-10).

# 1-9-7 Monitor Value/Setting Data Compound Read Store (Write)

#### Command



Variable type	Address	Setting data (explanation)
"C0"	"0000" to "0004"	Monitor values
"C1" to "C2"	"0000" to "0004"	Setting data of setting area 0
"C4" to "C6"	"0000" to "001F"	Setting data of setting area 1
"C8" to "CB"		

This command is used to store the addresses of multiple monitor values or setting data that you wish to read.

The stored monitor values or setting data can be read by sending a single "Monitor value/setting data compound store read" command. Up to 20 items can be stored, even if the addresses are not continuous.

To specify the variable type or address, see *SECTION 2 List of Settings* (page 2-1). The upper limit of an address will vary depending on the variable type.

This command can be used in both setting area 0 and setting area 1.

#### Response

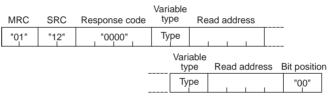
Response codes: The above indicates a normal end. For the response codes, see 1-5 Reading the Variable Area (page 1-9).

# 1-9-8 Monitor Value/Setting Data Compound Read Store Check (Read)

#### Command

This is used to check the contents that were stored using "Monitor value/setting data compound read store."

## Response



Response codes: The above indicates a normal end. For the response codes, see 1-5 Reading the Variable Area (page 1-9).

# 1-9-9 Monitor Value/Setting Data Compound Store Read

#### Command

This is used to read by a single command the multiple monitor values or setting data items that were stored using "Monitor value/setting data compound read store (write)."

This command can be used in both setting area 0 and setting area 1.

If an area type error or a setting data error occurs in any of the data being read, no data will be read.

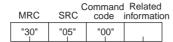
## Response

	MRC	SRC	Response code	Varia typ		Data
	"01"	"10"	"0000"	Тур	ре	Monitor value / Setting data
•				Va	riable t	type Data
			-		Туре	Monitor value / Setting data

Response codes: The above indicates a normal end. For the response codes, see 1-5 Reading the Variable Area (page 1-9).

## 1-9-10 Write via Communications

#### Command



Related information	Description
"00" Write via communications disabled	
"01"	Write via communications enabled

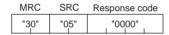
This command is used to enable or disable "Write via communications." When sent, it changes the set value of "Write via communications."

When write via communications is disabled, communications cannot be used to write setting data or send operation commands such as Run/Stop.

The initial setting is "disabled."

This command can be used in both setting area 0 and setting area 1.

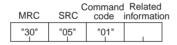
### Response



Response codes: The above indicates a normal end. For the response codes, see 1-7 Operation Commands (CompoWay/F Communications) (page 1-11).

## 1-9-11 Reset

#### Command



Related information	Description	
"00"	Reset	

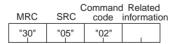
This command resets the system to no measurement status. It can only be used in setting area 0.

### Response

Response codes: The above indicates a normal end. For the response codes, see 1-7 Operation Commands (CompoWay/F Communications) (page 1-11).

## 1-9-12 Bank Selection

#### Command



Related information	Bank No. selected	
"00" to "07"	0 to 7	

This command can be used only when "Bank Selection" is set to "Key."

This command is used to change between comparative set values preset in banks. There are 8 banks numbered 0 to 7.

This command can be used in both setting area 0 and setting area 1.

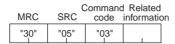
## Response

MRC	SRC	Response code
"30"	"05"	"0000"

Response codes: The above indicates a normal end. For the response codes, see 1-7 Operation Commands (CompoWay/F Communications) (page 1-11).

## 1-9-13 Zero Execute/Cancel

#### Command



Related information	Description	
"00"	Zero cancel	
"01"	Zero execute	

This command is used to execute/cancel the forced zero and tare zero functions. The results of the command will depend on the status of the tare zero setting, as shown below.

Tare	Commands executed in order left to right.			
zero	Zero execute	Zero execute	Zero cancel	Zero cancel
OFF	Forced zero ON	Forced zero ON	Forced zero OFF	Forced zero OFF
ON	Forced zero ON	Tare zero ON	Tare zero OFF	Forced zero OFF

This command can be used only in setting area 0. An operation error will occur in the following situations.

- When there is no measurement status, there is an input error, or a measurement is outside the display range (but zero cancel is possible.)
- When a RESET or HOLD input is ON
- When the command is used in setting area 1

#### Response

MRC	SRC	Response code
"30"	"05"	"0000"

Response codes: The above indicates a normal end. For the response codes, see 1-7 Operation Commands (CompoWay/F Communications) (page 1-11).

## 1-9-14 Software Reset

#### Command

MRC	SRC	Command code	Related information	
"30"	"05"	"06"	"00"	

A software reset causes the same operation as turning the power off and on.

This command can be used in both setting area 0 and setting area 1.

To use this command, "Write via communications" must be enabled using the "Write via communications" operation command.

#### Response

(No response)

A response is not returned to this operation command.

## 1-9-15 Move to Setting Area 1

#### Command

MRC	SRC		Related information	
"30"	"05"	"07"	"00"	

Use this command to move to setting area 1.

The command is used in setting area 0. Nothing happens if the command is used in setting area 1.

If the command is used when "Initial setting protect" is set to 2 (Disable move to input initial setting level), an operation error will result.

To use this command, "Write via communications" must be enabled using the "Write via communications" operation command.

### Response

MRC	SRC	Response code
"30"	"05"	"0000"

Response codes: The above indicates a normal end. For the response codes, see 1-7 Operation Commands (CompoWay/F Communications) (page 1-11).

## 1-9-16 Move to Protect Level

#### Command

MRC	SRC		Related information	
"30"	"05"	"08"	"00"	

Use this command to move to protect level.

This command is used in setting area 0. If used in setting area 1, an operation error will result.

To use this command, "Write via communications" must be enabled using the "Write via communications" operation command.

## Response

MRC	SRC	Response code
"30"	"05"	"0000"

Response codes: The above indicates a normal end. For the response codes, see 1-7 Operation Commands (CompoWay/F Communications) (page 1-11).

## 1-9-17 Initialize Settings

#### Command

MRC	SRC	Command code	l Related informati	
"30"	"05"	"0B"	"00"	

This returns all settings to the initial settings.

This command is used in setting area 1. If used in setting area 0, an operation error will result.

To use this command, "Write via communications" must be enabled using the "Write via communications" operation command.

## Response

MRC	SRC	Response code						
"30"	"05"	"0000"						

Response codes: The above indicates a normal end. For the response codes, see 1-7 Operation Commands (CompoWay/F Communications) (page 1-11).

## 1-9-18 Read Machine Attributes

#### Command

This command reads the K3HB model and communications buffer size.

The command can be used in any state of the K3HB.

### Response

MRC SRC		Response code	Format	Buffer size
"05"	"03"	"0000"		"00D9"

Response codes: The above indicates a normal end. For the response codes, see 1-7 Operation Commands (CompoWay/F Communications) (page 1-11).

### Model



\*Bytes 8 and 9 are blank

	А		В
Symbol Series		Symbol	Input
Χ	Analog input	VD	DC voltage
			AC voltage
			DC current
			AC current
٧	mV input	LC	mV
S	Linear Sensor input	SD	Linear Sensor
Н	Temperature input	TA	Temperature

## 1-9-19 Controller Status Read (CompoWay/F Communications)

#### Command

This command reads the operation state of the K3HB.

The command can be used in any state of the K3HB.

## Response

MRC	SRC	Response code	Operation state	Related information
"06"	"01"	"0000"		

Response codes: The above indicates a normal end. For the response codes, see 1-7 Operation Commands (CompoWay/F Communications) (page 1-11).

#### **Operation State**

Operation state	Description
00	Operating (no errors in setting area 0, see note)
01	Stopped (all other situations)

#### Note

Measurements outside the display range and no measurement status do not generate errors and thus may be possible even for an operation state of 00.

#### **Related Information**

Bit position	Sta	itus				
7	Not used					
6	Not used					
5	Not used	Not used				
4	Not used					
3	Input error B	Present value				
2	Input error A					
1	Measurement outside the display range					
0	No measurement status					

#### Note

- (1) The bit will be ON (1) or when an error occurs and otherwise will be OFF (0).
- (2) Information is in the same order as status information.

## 1-9-20 Echo Back Test

## Command

MRC	SRC	Test data
"08"	"01"	0 to 200 bytes

This command is used to perform an echo back test.

The command can be used in any state of the K3HB.

Keep the test data within the following ranges depending on the communications data length.

Communications data length	Description
7 bits	ASCII code H'20 to H'7E
8 bits	ASCII code H'20 to H'7E or H'A1 to H'FE

#### Response

MRC	SRC	Test data	
"08"	"01"	"0000"	0 to 200 bytes

Response codes: The above indicates a normal end. For the response codes, see 1-7 Operation Commands (CompoWay/F Communications) (page 1-11).

## 1-10 Program Example

## N88Basic

This program displays the response from the K3HB on the screen when command data is entered from the keyboard.

Command data from the unit number to the number of elements must be entered.

The program was created in N88BASIC.

```
1000
1010
       'PROGRAM: E5AR/ER Communication Sample Program(CompoWay/F)
       'VERSION:1.00
1020
       (c)Copyright OMRON Corporation 2003
1030
1040
       All Rights Reserved
1050
1060
1070
       '====Communication port (PARITY=EVEN, DATA=7, STOP=2) ======"
1080
       OPEN "COM:E73" AS #1
1090
1100
1110
       *SENDDATA
1120
1130
       ====== Communication routine=======
1140
1150
            --Communication data input--
       INPUT "SEND DATA:", SEND$
1160
1170
       -----If no input, jump to end routine------
IF SEND$ = " " THEN *EXITSEND
1180
1190
1200
1210
       -----BCC calulation-----
1220
       BCC = 0
1230
       SEND$ = SEND$+CHR$(3)
1240
       FOR I=1 TO LEN(SEND$)
1250
        BCC = BCC XOR ASC(MID$(SEND$, I, 1))
1260
       NEXT I
1270
       BCC$ = CHR$(BCC)
1280
1290
          --Send---
       SDATA$ = CHR$(2)+SEND$+BCC$
1300
1310
       PRINT #1, SDATA$;
1320
1330
       ====== Receive routine =======
1340
1350
       RDATA$ = " "
       TIMEOUT = 0
1360
       *RCVLOOP
1370
1380
       -----No response detection-----
1390
       TIMEOUT = TIMEOUT+1
       IF TIMEOUT > 2000 THEN RESP$ = "No Response":GOTO *RCVEND IF LOC(1) = 0 THEN *RCVLOOP
1400
1410
1420
       -----Check for end character (if no end character, continue reading)
RDATA$ = RDATA$+INPUT$(LOC(1),#1)
1430
1440
       IF LEN(RDATA$) <2 THEN *RCVLOOP

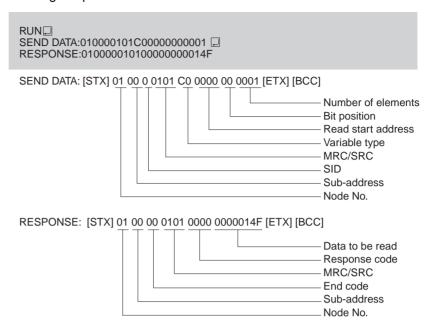
IF MID$(RDATA$,LEN(RDATA$)-1,1) <> CHR$(3) THEN *RCVLOOP
1450
1460
1470
       RESP$ = MID$(RDATA$,2,LEN(RDATA$)-2)
1480
       *RCVEND
1490
1500
         ----Display received data----
1510
       PRINT "RESPONSE:"; RESP$
1520
       GOTO *SENDDATA
1530
1540
       *EXITSEND
1550
       ======End routine======
1560
       CLOSE #1
1570
       END
```

Program Example Section 1-10

compoway/r Communications

## **Operation Example**

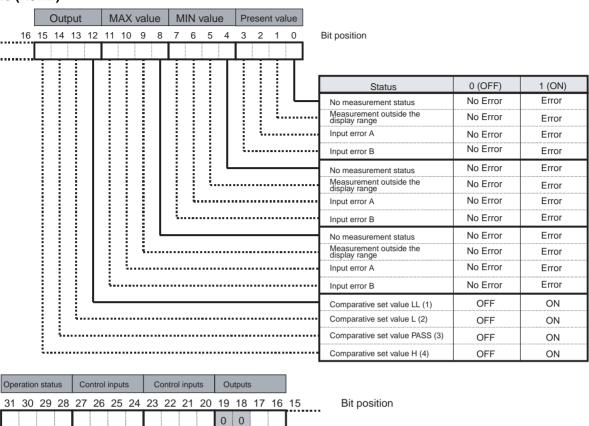
Reading the present value of Unit No.01.

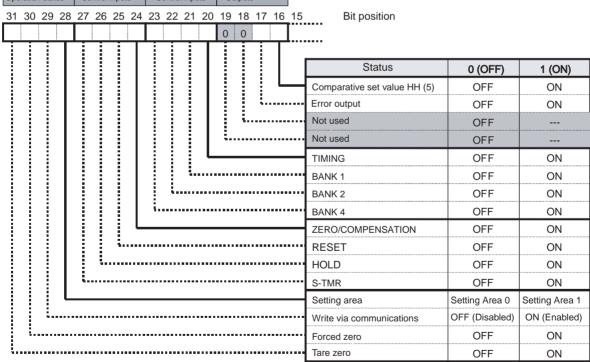


# **SECTION 2** List of Settings

This list of settings shows addresses for CompoWay/F communications. Refer to the address for the communications protocol that is used.

## Status (K3HB)





Note The output status turns ON and OFF whether or not an Output Unit is mounted. The output status is undefined if there is no output terminal when Unit 3 outputs a two-relay comparative output pattern. If the output is a two-relay plus one-relay comparative output pattern, LL turns ON when PASS turns ON (output and display colors are not changed in communications status). A 5-output judgement is performed internally regardless of the number of output points. The LL output is always ON in the above configuration so the PASS output does not turn ON. To avoid this situation, the HH/LL status is ignored when Unit 3 uses a two-relay output pattern. The PASS judgement is performed with just H and L for operations like that described.

## **Communications Monitoring Settings**

Variable	Address	Setting data	Character	Character Monitor/Setting range	Character		Decimal	Unit	Model			
type						setting	point		Х	٧	S	Н
C0	0000	Version										
	0001	Status										
	0002	Measurement value		H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)				EU				
	0003	MAX value		H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)				EU				
	0004	MIN value		H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)				EU				

**Note** The values beginning with H' in the *Monitor/Setting range* column are used when setting or monitoring data via communications.

## **Protect Level**

Variable	Address	Parameter	Character	aracter Monitor/Setting range	Character	Default	Decimal	Unit	Model				
type		name				setting	point		Х	٧	s	Н	
C1	0000	RUN/Adjust- ment protect	rUn.Pt	H'00000000 to H'00000002: (0 to 2)	0 to 2	0							
	0001	Setting level protect	SE <i>E.PE</i>	H'00000000 to H'00000002: (0 to 2)	0 to 2	1							
	0002	Setting change protect	<u> Y</u> E.PE	H'00000000: OFF(0) H'00000001: ON(1)	ăFF, ăn	āFF							
	0003	Forced zero protect	≛r.Pb	H'00000000: OFF(0) H'00000001: ON(1)	ăFF, ăn	ăFF						х	
	0004	MAX/MIN pro- tect	ññ.Pt	H'00000000 to H'00000002: (0 to 2)	0 to 2	0							

**Note** The values beginning with H' in the *Monitor/Setting range* column are used when setting or monitoring data via communications.

#### **RUN Level**

Variable	Address	Parameter	Character	Monitor/Setting range	Character	Default	Decimal	Unit		Мо	del	
type		name				setting	point		Х	٧	s	Н
C2	0000	Comparative set value HH		H'FFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	33333	According to the decimal position set- ting	EU				
	0001	Comparative set value H		H'FFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	99999	According to the decimal position set- ting	EU				
	0002	Comparative set value L		H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	19999	According to the decimal position set- ting	EU				
	0003	Comparative set value LL		H'FFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	19999	According to the decimal position set- ting	EU				

**Note** The values beginning with H' in the *Monitor/Setting range* column are used when setting or monitoring data via communications.

## **Initial Setting Level**

Variable	Address	Parameter	Char-	Monitor/Setting range	Character	Default	Decimal	Unit		Мо	del	
type		name	acter			setting	point		X	٧	s	Н
C4	0000	Calculation	EAL	H'00000000: A(0), H'00000001:B(1), H'00000002:K-A(2), H'00000003: A+B(3), H'00000004: A-B(4), H'00000005: K- (A+B)(5), H'00000000: B/A×10000(6), H'00000007: (B/A-1) × 10000(7)	0, 1, 2, 3, 4, 5, 6, 7	0			x	x		х
	0001	Input type A	in-tR	X(VD): H'0000000: ±199.99 V(0), H'00000001: ±19.999 V(1), H'00000002: ±1.9999 V(2), H'00000003: 1.0000 to 5.0000 V(3) X(AD): H'00000000: ±199.99 mA(0), H'00000001: ±19.999 mA(1), H'00000003: ±1.9999 mA(2), H'00000003: 4.000 to 20.000 mA(3) X(VA): H'00000001: 0.0 to 400.0 V(0), H'00000001: 0.00 to 199.99 V(1), H'00000001: 0.00 to 199.99 V(2), H'00000003: 0.0000 to 1.99.99 V(3) X(AA): H'00000000: 0.000 to 10.000 A(0), H'00000001: 0.000 to 19.999 M(1), H'00000001: 0.000 to 19.999 M(1), H'00000001: 0.000 to 19.999 mV(2), H'00000001: 0.000 to 19.999 mV(2), H'00000001: 0.000 to 19.999 mV(1), H'00000001: 10.000 mV(2), H'00000001: 5 to 20 mA(0) H'00000001: 4 to 20 mA(0) H'00000001: 5 V(4), H'00000001: ±10.000 mV(2), H'00000001: ±10.000 mV(2), H'00000001: 4 to 5 V(3), H'00000001: 4 to 5 V(4), H'00000001: 5 V(4), H'00000001: 5 V(4), H'00000001: 5 V(4), H'00000001: 1-10.000 mO(2: 2-K(2), H'00000001: 1-10.000 mO(2: 2-K(2), H'00000001: 1-10.0000001: 1-10.0000001: 1-10.0000001: 1-10.0000001: 1-10.0000001: 1-10.0000001: 1-10.0000001: 1-10.00000001: 1-10.0000001: 1-10.0000001: 1-10.0000001: 1-10.0000001: 1-10.00000001: 1-10.00000001: 1-10.00000001: 1-10.00000001: 1-10.00000001: 1-10.00000001: 1-10.00000001: 1-10.00000001: 1-10.00000001: 1-10.00000001: 1-10.0000000000000000000000000000000000	X(VD):	X(VD): R ud X(AD): R Rd X(VA): R ud X(AA): R RR V: R LE S: Y to 20 H: Z-P						
	0002	Power sup- ply fre- quency	FrE	H'00000000: 50(0), H'00000001: 60(1)	50, 60	S0		Hz			х	
	0003	Scaling input value A1	EnP.RI	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	49999 to 99999	X (VD): 499.99 X (AD): 499.99 X (VA): 0.0 X (AA): 0.000 V: 0.00 S: 4.000	Accord- ing to the input type	According to the input type				х
	0004	Scaling dis- play value A1	dSP.RI	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	X (VD): 1999 X (AD): 1999 X (VA): 0 X (AA): 0 V: 0 S: 4000		EU				х

Variable	Address	Parameter	Char-	Monitor/Setting range	Character	Default	Decimal	Unit		Мо	del	
type		name	acter			setting	point		Х	٧	s	Н
C4	0005	Scaling input value A2	inP.R≥	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	X (VD): 199.99 X (AD): 199.99 X (VA): 190.00 X (AA): 10.000 V: 199.99 S: 20.000	Accord- ing to the input type	According to the input type				x
	0006	Scaling dis- play value A2	dSP.R2	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	49999 to 99999	X (VD): 19999 X (AD): 19999 X (VA): 4000 X (AA): 10000 V: 19999 S: 20000		EU				x
	0007	Input type B	in-tb	H'00000000: 0 to 20 mA(0), H'00000001: 4 to 20 mA(1), H'00000002: 0 to 5 V(2), H'00000003: 1 to 5 V(3), H'00000004: ±5 V(4), H'00000005: ±10(5)	0-20, 4-20, 0-5, 1-5, 5, 10	4 to 20 mA			x	X		х
	0008	Scaling input value B1	inP.b l	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	20.000	Accord- ing to the input type	According to the input type	х	х		х
	0009	Scaling dis- play value B1	dSP.b l	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	4000		EU	х	х		х
	000A	Scaling input value B2	inP.b2	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	20.000	Accord- ing to the input type	According to the input type	х	x		х
	000B	Scaling dis- play value B2	d5P.b2	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	20000		EU	х	х		х
	000C	Constant K	'n	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	8		EU	х	х		Х
	000D	Decimal point posi- tion	d₽	H'00000000 to H'00000004: 0 to 4	00000, 00000, 000.00, 00.000, 0.0000	X (VD): aaa.aa X (AD): aaa.aa X (VA): aaaa.a X (AA): aa.aaa V: aaa.a S: aa.aaa						х
	000F	Tempera- ture units	d-U	H'00000000 °C(0), H'00000001: F(1)	£, F	Ε			х	Х	х	
	000E	Compara- tive output pattern	åUt-P	H'00000000: standard output(0), H'00000001: zone output(1), H'00000002: zone output(2)	nöñAL, žonE, LEuEL	něňŘĽ						

**Note** The values beginning with H' in the *Monitor/Setting range* column are used when setting or monitoring data via communications.

## **Input Adjustment Level**

Variable	Address	Parameter	Character	Monitor/Setting	Character	Default	Decimal	Unit		mo	del	
type		name		range		setting	point		Х	٧	s	Н
C5	0000	Timing hold	FYC-H	H'0000000: Normal(0), H'0000001: sampling(1), H'0000002: peak(2), H'0000003: bottom(3), H'00000004: peak to peak(4)	năñЯL, S-H, P-H, b-H, P-P	něňRL						
	0001	ON timing delay	ŏn-Ł	H'00000000 to H'00001387: (0 to 4999)	0 to 4999	0		S: ms Others: 100 ms				
	0002	OFF timing delay	åFF-Ł	H'00000000 to H'00001387: (0 to 4999)	0 to <b>4999</b>	a		S: ms Others: 100 ms				
	0003	Zero limit	E-LIA	H'00000000: OFF(0) H'00000001: ON(1)	ăFF, ăn	ōFF						
	0004	Zero limit value	Līñ-P	H'00000000 to H'0000063: (0 to 99)	0 to 99	a	According to the decimal position set- ting	EU				
	0005	Step value	SEEP	H'0000000: OFF(0), H'0000001: 2(1), H'00000002: 5(2), H'00000003: 10(3)	ăFF, 2, 5, 10	ăFF		digit				
	0006	Average type	AuG-E	H'00000000: Simple average(0), H'00000001: move average(1)	SAPL, AĞUE	SAPL						
	0007	Averaging times	8u6-n	H'00000000: 1(0)/H'00000001: 2(1)/ H'00000002: 4(2)/ H'00000003: 8(3)/ H'00000004:16(4)/ H'00000005: 32(5)/ H'00000006: 64(6)/ H'00000007: 128(7)/ H'00000008: 256(8)/ H'00000009: 512(9)/ H'00000000A: 1024(10) times	1, 2, 4, 8, 16, 32, 64, 128, 256, 512, 1024	1						
	8000	Input shift input 1	252.1	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	-200.0	According to the input type	EU	х	х	х	
	0009	Input shift value 1	255.1	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	199.99 to 999.99	0.00	2	EU	х	х	х	
	000A	Input shift input 2	252.2	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	1300.0	According to the input type	EU	х	х	х	
	000B	Input shift value 2	255.2	H'FFFFB1E1 to H'0001869F (-199.99 to 99.999)	199.99 to 99.999	0.00	2	EU	х	х	х	
	0010	Power interrup- tion memory	ňEňň	H'00000000: OFF(0), H'00000001: ON(1)	ăFF, ăn	<u>ā</u> FF						

**Note** The values beginning with H' in the *Monitor/Setting range* column are used when setting or monitoring data via communications.

## **Display Adjustment Level**

Variable	Address	Parameter	Character	Monitor/Setting range	Character	Default	Decimal	Unit		Мо	del	
type		name				setting	point		Х	٧	s	Н
C6	0000	Compara- tive set value dis- play	Su.d5P	H'00000000: OFF(0), H'00000001: ON(1)	ăFF, ăn	ōFF						
	0001	Display refresh period	drEF	H'0000000: OFF(0), H'0000001: 0.5 s(1), H'0000002: 1 s(2), H'0000003: 2 s(3), H'0000004: 4 s(4)	ěff, 0.5, 1, 2, 4	òff		s				
	0002	Display color selec- tion	EåLår	H'00000000: Green (red)(0), H'00000001: green(1), H'00000002: red (green)(2), H'00000003: red(3)	Gra-r, Gra, rEd-G, rEd	Grn-r						
	0003	Display value selec- tion	dZ5P	H'00000000: PV(0), H'00000001: MAX(1), H'00000002: MIN (2)	Pu, กักับ, กับก	Pu						
	0004	Automatic display return	r8t	H'00000000 to H'00000063: (0 to 99)	0 to 99	10		s				
	0005	Position meter type	PāS-Ł	H'00000000: OFF(0), H'00000001: increase(1), H'00000002: increase (inverted)(2), H'00000003: deviation (3), H'00000004: deviation, (inverted)(4)	öff, ini, ini-r, deu, deu-r	int						
	0006	Position meter upper limit	PäS-X	H'FFFB1E1 to H'0001869F (-19,999 to 99,999)	49999 to 99999	X (VD): 1999 X (AD): 1999 X (VA): 4000 X (VA): 4000 V: 1999 V: 1999 H: 1300.0	According to the decimal position set- ting	EU				
	0007	Position meter lower limit	PāS-L	H'FFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	X (VD): 1999 X (AD): 1999 X (VA): 0 X (A)): 0 V: 0 S: 19999 H: -200.0	According to the decimal position set- ting	EU				
	0008	PV decimal point indication	PudP	H'00000000: OFF(0) H'00000001: ON(1)	ăFF, ăn	ăn			х	х	х	

**Note** The values beginning with H' in the *Monitor/Setting range* column are used when setting or monitoring data via communications.

## **Comparative Set Value Level**

Variable	Address	Parameter	Character	Monitor/Setting range	Character	Default	Decimal	Unit		Мо	del	
type		name				setting	point		Х	٧	s	Н
C8	0000	Compara- tive set value 0HH	5 <u>.0</u> XX	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	33333	According to the decimal position set- ting	EU				
	0001	Compara- tive set value 0H	Suax	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	33333	According to the decimal position set- ting	EU				
	0002	Compara- tive set value 0L	5 <i>u01</i> .	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	19999	According to the decimal position set- ting	EU				
	0003	Compara- tive set value 0LL	Suall	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	19999	According to the decimal position set- ting	EU				

Variable	Address	Parameter	Character	Monitor/Setting range	Character	Default	Decimal	Unit		Мо	del	
type		name				setting	point		X	٧	S	Н
C8	0004	Compara- tive set value 1HH	5u (XX	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	99999	According to the decimal position set- ting	EU				
	0005	Compara- tive set value 1H	Su IX	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	39333	According to the decimal position set- ting	EU				
	0006	Compara- tive set value 1L	Su (L	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	19999	According to the decimal position set- ting	EU				
	0007	Compara- tive set value 1LL	Su ILL	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	19999	According to the decimal position set- ting	EU				
	0008	Compara- tive set value 2HH	SuZXX	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	39393	According to the decimal position setting	EU				
	0009	Compara- tive set value 2H	SuZX	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	39999	According to the decimal position setting	EU				
	000A	Compara- tive set value 2L	SuZL	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	19999	According to the decimal position set- ting	EU				
	000B	Compara- tive set value 2LL	SuZLL	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	19999	According to the decimal position set- ting	EU				
	000C	Compara- tive set value 3HH	Suzikk	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	99999	According to the decimal position set- ting	EU				
	000D	Compara- tive set value 3H	Suax	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	39999	According to the decimal position set- ting	EU				
	000E	Compara- tive set value 3L	5 <i>u3l</i> .	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	19999	According to the decimal position set- ting	EU				
	000F	Compara- tive set value 3LL	Su3LL	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	19999	According to the decimal position set- ting	EU				
	0010	Compara- tive set value 4HH	Suyak	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	39999	According to the decimal position set- ting	EU				
	0011	Compara- tive set value 4H	Suyx	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	39999	According to the decimal position set- ting	EU				
	0012	Compara- tive set value 4L	5.J4L	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	19999	According to the decimal position set- ting	EU				
	0013	Comparative set value 4LL	SuYLL	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	19999	According to the decimal position set- ting	EU				
	0014	Compara- tive set value 5HH	Susxx	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	33333	According to the decimal position set- ting	EU				
	0015	Compara- tive set value 5H	Su <b>S</b> X	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	33333	According to the decimal position set- ting	EU				

Variable	Address	Parameter	Character	Monitor/Setting range	Character	Default	Decimal	Unit		Мо	del	
type		name				setting	point		Х	٧	S	Н
C8	0016	Compara- tive set value 5L	Su5.L	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	19999	According to the decimal position setting	EU				
	0017	Compara- tive set value 5LL	SuSLL	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	19999	According to the decimal position setting	EU				
	0018	Compara- tive set value 6HH	Su8.XX	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	99999	According to the decimal position setting	EU				
	0019	Compara- tive set value 6H	Subx	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	33333	According to the decimal position set-ting	EU				
	001A	Compara- tive set value 6L	Su6.L	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	19999	According to the decimal position set-ting	EU				
	001B	Compara- tive set value 6LL	Su&.LL	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	19999	According to the decimal position setting	EU				
	001C	Compara- tive set value 7HH	ร <sub>บ</sub> าหห	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	99999	According to the decimal position set-ting	EU				
	001D	Compara- tive set value 7H	ארייב	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	99999	According to the decimal position set-ting	EU				
	001E	Compara- tive set value 7L	SuriL	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	19999	According to the decimal position set-ting	EU				
	001F	Compara- tive set value 7LL	Suall	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	19999	According to the decimal position setting	EU				

**Note** The values beginning with H' in the *Monitor/Setting range* column are used when setting or monitoring data via communications.

## **Linear Output Level**

Variable	Address	Parameter	Character	Monitor/Setting range	Character	Default	Decimal	Unit		Мо	del	
type		name				setting	point		Х	٧	s	Н
C9	0000	Linear cur- rent type	LSEEL	H'00000000: 0 to 20 mA(0), H'00000001: 4 to 20 mA(1)	0-20, 4-20	4-20						
	0001	Linear volt- age type	LSEŁw	H'00000000: 0 to 5 V(0), H'00000001: 1 to 5 V(1), H'00000002: 0 to 10 V(2)	0-5, 1-5, 0-10	1-5						
	0002	Linear out- put upper limit	LSEEH	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	X (VD): 19993 X (AD): 19999 X (VA): 4000 X (A)): 10000 V: 19999 H: 1300.0	According to the decimal position set- ting	EU				
	0003	Linear out- put lower limit	LSEEL	H'FFFFB1E1 to H'0001869F (-19,999 to 99,999)	19999 to 99999	X (VD): 4999 X (AD): 48999 X (VA): 0 X (A)): 0 V: 0 S: 49999 H: -200.0	According to the decimal position set- ting	EU				

**Note** The values beginning with H' in the *Monitor/Setting range* column are used when setting or monitoring data via communications.

## **Communications Setting Level**

Variable	Address	Parameter	Character	Monitor/Setting range	Character	Default	Decimal	Unit		Мо	del	
type		name				setting	point		Х	٧	s	Н
CA	0000	Unit No.	U-nă	H'00000000 to H'00000063: (0 to 99)	0 to 99	1						
	0001	Baud rate	<i>6P</i> 5	H'00000000: 9.6(0), H'00000001: 19.2(1), H'00000002: 38.4(2)	9.5, 19.2, 38.4	9.5		kbps				
	0002	Data length	LEn	H'00000000: 7(0), H'00000001: 8(1)	7,8	7		bit				
	0003	Stop bit length	Sbit	H'00000000: 1(0), H'00000001: 2(1)	1, 2	2		bit				
	0004	Parity	Prey	H'00000000: None (0), H'00000001: Even (1), H'00000002: Odd (2)	nonE, EuEn, odd	EuEn						
	0005	Send wait time	SdYt	H'00000000 to H'00000063 (0 to 99)	0 to 99	20		ms				

**Note** The values beginning with H' in the *Monitor/Setting range* column are used when setting or monitoring data via communications.

## **Advanced Function Setting Level**

Variable	Address	Parameter	Charac-	Monitor/Setting range	Character	Default	Decimal	Unit		Мо	del	
type		name	ter			setting	point		Х	٧	S	Н
СВ	0000	PASS-output change	PRSS	H'00000000: LL(0), H'00000001: L(1), H'00000002: PASS(2), H'00000003: H(3), H'00000004: HH(4), H'00000005: ERR(5)	LL,L,PR55, H,HH,Ecc	PRSS						
	0001	Hysteresis	HYS	H'00000000 to H'0000270F: (0 to 9,999)	û to 9999	1	According to the decimal position set- ting	EU				
	0002	Output OFF delay	ăFF-d	H'00000000 to H'000007CF (0 to 1,999)	0 to 1999	0		S: ms Others: 100 ms				
	0003	Shot output	SHåŁ	H'00000000 to H'000007CF (0 to 1,999)	0 to 1999	0		S: ms Others: 100 ms				
	0004	Output logic	ăUt-n	H'00000000 :Close in alarm(0), H'00000001: Open in alarm(1)	n-ă, n-E	n-ō						
	0005	Output refresh stop	ō-5 <i>EP</i>	H'00000000: OFF(0), H'00000001: OUT(1), H'00000002: ALL(2)	ăff, ăUŁ, RLL	ŏFF						
	0006	Tare zero	b-Er	H'00000000: OFF(0) H'00000001: ON(1)	ăFF, ăn	ōFF						х
	0007	Zero trim- ming	i-brň	H'00000000: OFF(0) H'00000001: ON(1)	ăFF, ăn	ăFF						х
	8000	Previous average value com- parison	HP-F	H'00000000: OFF(0) H'00000001: ON(1)	ōFF, ōn	ăFF						
	0009	Bank selec- tion	bnY-[	H'00000000: OFF(0), H'00000001: KEY(1), H'00000002: EV(2)	ăFF, PEY, Eu	(See note.)						
	000A	Startup com- pensation timer	5-bār	H'00000000 to H'0000270F: (0 to 99.9)	0.0 to 99.9	0.0	1	S				
	000B	Input error enable	5.800	H'00000000: Disable(0), H'00000001: overflow(1), H'00000002: input error(2)	öff, öuEr, S.Err	S.Err						
	000C	Standby sequence	Stdby	H'00000000: OFF(0) H'00000001: ON(1)	ŏFF, ŏn	ōFF						
	000D	Cold junction compensating circuit	EGE	H'00000000: OFF(0) H'00000001: ON(1)	ăFF, ăn	ăn			х	х	х	

**Note** (1) If the event connector is provided as a standard feature or an event connector is added, use EV for the "bank selection" setting.

(2) The values beginning with H' in the *Monitor/Setting range* column are used when setting or monitoring data via communications.

## Part 2: DeviceNet

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## Part 2: DeviceNet

## Overvie/

## SECTION 1 Overview

This section introduces the features and specifications of K3HB-DRT Digital Indicators.

1-1	Features				
	1-1-1	Outline	3-2		
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Features Section 1-1

## 1-1 Features

In this manual, the DeviceNet-compatible K3HB Digital Indicator is abbreviated as K3HB-DRT.

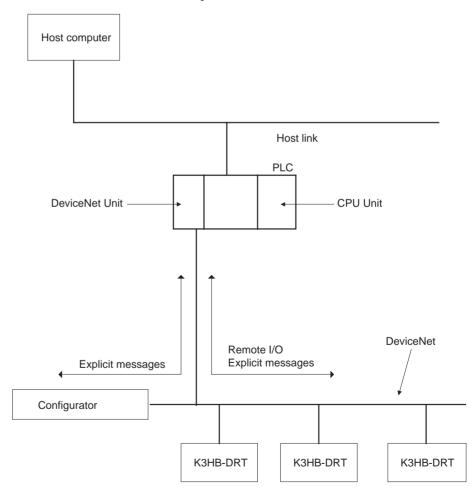
## 1-1-1 **Outline**

The K3HB-DRT Digital Indicators are slaves that connect to the DeviceNet open field network. DeviceNet communications enable controlling operation, collecting measurement data, and writing settings from a host computer or PLC. The K3HB-DRT support both remote I/O communications and explicit message communications.

Remote I/O communications allow the master and the K3HB-DRT to automatically share data via high-speed I/O without any special programming of the master. Remote I/O communications are particularly suited to operation control, error warnings, and monitoring applications.

Explicit messages use a communications protocol for sending commands and receiving responses. The main application for explicit message communications is for changing K3HB-DRT settings data.

## 1-1-2 Communications Connection Example



Features Section 1-1

## 1-1-3 Using DeviceNet

## Remote I/O Communications

The master and K3HB-DRT Digital Indicators can share I/O by using remote I/O communications. Data in the K3HB-DRT Digital Indicators, such as measurement values and comparative set values, can be allocated for communications with the master to enable sending and receiving the allocated data via remote I/O communications without requiring special programming.

User-set Data Allocations with a Configurator
 The specific data required for communications with the master can be allocated by using I/O allocations from the DeviceNet Configurator.

## **Explicit Message Communications**

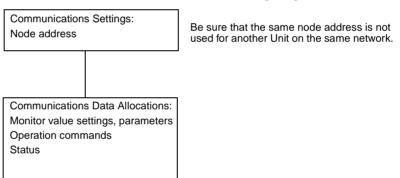
By sending commands from a PLC, various operations can be performed, including reading/writing specific monitor values and parameters, such as reading measurement values or writing comparative set values, and performing operations using operation commands. CompoWay/F communications commands can also be executed using explicit message communications.

## Automatically Detects Baud Rate

Previously, the baud rate had to be set for each slave, but the K3HB-DRT Digital Indicators automatically detect and match the baud rate of the master, so this setting is not required. (If the master's baud rate is changed, turn OFF the communications power supply to the Digital Indicator and then turn it ON again.)

## 1-1-4 Default Communications Settings

The default settings required for communications when K3HB-DRT are used as DeviceNet slaves are listed in the following diagram.



Refer to the *DeviceNet Operation Manual* (Cat. No. W267) for information such as the order for turning ON power to the master and slaves and master I/O tables.

## 1-1-5 Data Allocation

K3HB-DRT communications data must be allocated for the Read and Write Areas for communications with the master. Up to 30 items can be allocated for the Read Area and up to 15 items can be allocated for the Write Area. The data for each word is allocated using the parameters write data 1 to 15 and read data 1 to 15.

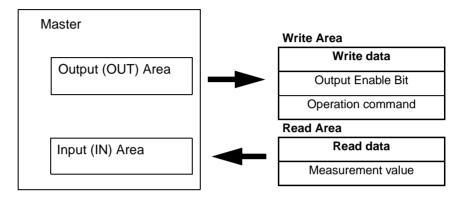
Unused words can be specified to reserve space according to data types or to otherwise reduce the number of words.

Refer to 4-2 I/O Allocation on page 6-2 for details on allocation methods.

## 1-1-6 Remote I/O Communications

Read/write table data is automatically read and written when communications start. The Communications Write setting must be set to ON to write data from the master to the K3HB-DRT. Data will not be written to the Digital Indicator if the Communications Write setting is OFF. The following diagram shows communications with the default data allocation parameters.

**Note** The Communications Write setting is ON by default.



Specifications Section 1-2

## 1-2 Specifications

## 1-2-1 DeviceNet Communications Specifications

Item		Specifications			
Communications protocol		Conforms to DeviceNet			
Communica-	Remote I/O	Master-slave connections (polling, bit-strobe, COS, or cyclic)			
tions functions	communications	• Conform to [	DeviceNet specifications.		
	I/O allocations		any I/O data from the Confi	•	
		<ul> <li>Can allocate Indicator vari</li> </ul>	any data, such parameters iable area.	specific to the Devic	ceNet and the Digital
		• Up to 2 block	s for the IN Area, up to a to	tal of 60 words (See	note 1.)
			r the OUT Area, up to 29 wo le Bits.) (See note 2.)	ords (The first word i	s always allocated to
	Message com-	• Explicit mess	sage communications		
	munications	CompoWay/lexplicit mess	F communications command age format).	ds can be sent (com	mands are sent in
Connection format		Combination of multidrop and T-branch connections (for trunk and drop lines)			
Baud rate		DeviceNet: 500, 250, or 125 kbps, or automatic detection of master baud rate			
Communications	media	Special 5-wire cable (2 signal lines, 2 power lines, and 1 shield line)			
Communications	distance	Baud rate	Network length	Drop line length	Total drop line length
		500 kbps	100 m max. (100 m max.)	6 m max.	39 m max.
		250 kbps	100 m max. (250 m max.)	6 m max.	78 m max.
		125 kbps	100 m max. (500 m max.)	6 m max.	156 m max.
		The values in parentheses apply when Thick Cables are used.			
Communications	power supply	11 to 25 VDC			
Maximum number of nodes that can be connected		64 (includes Configurator when used)			
Maximum number of slaves that can be connected		63			
Error control		CRC error detection			
Power supply		Power supplie	d from DeviceNet communic	cations connector	

## Note

- (1) The IN Area can be divided into two blocks only when a CS/CJ-series DeviceNet Unit is used as the master. (The connection type can also be selected.) If a CVM1, CV, or C200HX/HG/HE DeviceNet Master Unit is used as the master, the IN Area must be in 1 block with a maximum 100 words (200 bytes). (Polling connection only.)
- (2) If a CVM1, CV, or C200HX/HG/HE DeviceNet Master Unit used, only up to 32 words can be allocated per node.

## 1-2-2 DeviceNet General Specifications

Item	Specifications
Supply voltage	DeviceNet power supply: 24 VDC (internal circuit)
Allowable voltage range	DeviceNet power supply: 11 to 25 VDC
Current consumption	DeviceNet power supply: 50 mA max. (24 VDC)
Vibration resistance	Vibration: 10 to 55 Hz Acceleration: 50 m/s <sup>2</sup>
Shock resistance	150 m/s <sup>2</sup> max. 3 times each in 3 axes, 6 directions
Dielectric strength	2,300 VAC for 1 min. between all the external terminals and case
Insulation resistance	20 MΩ min. (at 500 VDC)
Ambient temperature	-10 to 55°C (with no condensation or icing)
Ambient humidity	25% to 85%
Storage temperature	-25 to 65°C (with no condensation or icing)
Enclosure rating	IP00 (connector)
Memory protection	EEPROM (100,000 write operations)
Weight	DeviceNet connector: Approx. 8 g Crimp terminals: Approx 1 g (each)

# **SECTION 2 Operating Procedures**

This section outlines the basic operating procedures for the K3HB-DRT Digital Indicators.

2-1	Introduction		
	2-1-1	Setup Procedure	4-2
	2-1-2	Startup Procedure	4-2
	2-1-3	Setting Node Addresses	4-3
2-2	Function	ons Supported Only by the K3HB-DRT	4-4
	2-2-1	Network Power Monitor Function	4-4
	2-2-2	Unit Conduction Time Monitor Function	4-4

## 2-1 Introduction

Use the procedures in the following sections to prepare the K3HB-DRT Digital Indicators for use. Refer to the following reference pages/sections provided for detailed information on each step.

## 2-1-1 Setup Procedure

Step	Item	Details	Reference
1	Mount the Digital Indicator.	Mount the Digital Indicator to the panel.	page 5-2
2	Wire the Digital Indicator.	Wire the temperature inputs and comparative outputs to the Digital Indicator terminals.	
		<b>Note</b> Do not turn ON the power supply to the peripheral devices at this time.	
3	Turn ON the power to the Digital Indi-	Turn ON the power connected to the Digital Indicator.	
	cator.	Note The Digital Indicator will start.	
4	Set the DeviceNet node address.	Set the DeviceNet node address (0 to 63) for the Digital Indicator on the front panel. Set a unique node address for each slave connected to the same master.	page 4-3
5	Turn OFF the power to the Digital Indicator.	Turn OFF the power connected to the Digital Indicator.	

## 2-1-2 Startup Procedure

Prepare the master, DeviceNet communications power supply, and Configurator that will be used in the system. Use the Configurator to allocate Digital Indicator data in the IN and OUT Areas. Refer to the *DeviceNet Operation Manual* (W267) for information on related connection devices.

Note

Up to 30 items can be allocated in the IN Area and up to 15 items can be allocated in the OUT Area for remote I/O communications. To read and write larger amounts of data, use explicit messages. Use explicit messages also for reading and writing data only when required.

Step	Item	Details	Reference
6	Connect the DeviceNet com-	Connect the DeviceNet communications connector.	page 5-4
	munications connector.	Note Do not turn ON the communications power supply at this time. This power supply is also used as the internal circuit power supply for DeviceNet communications.	
7	Turn ON the power to the Digi-	Turn ON the power connected to the Digital Indicator.	
	tal Indicator.	Note The Digital Indicator will start.	
8	Turn ON the DeviceNet com-	Turn ON the communications power supply to DeviceNet.	
	munications power (V+, V-).	Note The DeviceNet communications will start.	
9	Check the MS/NS indicators	Check that the status of the MS and NS indicators is as follows:	page 5-3
		MS: Operating normally when lit green.	
		NS: Operating normally when lit green. (DeviceNet online or communications connected.)	

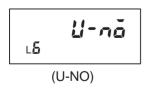
Introduction Section 2-1

Step	Item	Details	Reference
10	Operate from the Configurator.	Set from the Configurator when changing data allocated in the IN and OUT Areas from the default values.	SECTION 4 Remote I/O Com- munications
		To split the IN Area used by the K3HB-DRT into two areas, select K3HB-DRT in the master's Edit Device Parameters Window and set the connection in the detailed settings.	
		When the IN Area is split into two areas, for example, operating parameters, such as measurement values and comparative set values, can be allocated in IN Area 1, and status values can be allocated in IN Area 2. For example, IN Area 1 can be allocated in the DM Area and IN Area 2 can be allocated in the CIO Area.	
11	Start remote I/O communications.	Enable the master's scan list and change the PLC to RUN Mode.	
		Remote I/O communications will start, and the contents of the IN and OUT Areas in the master and K3HB-DRT Digital Indicator will be synchronized.	
12	Use explicit message commu-	Send explicit messages from the master.	SECTION 5
	nications.	Explicit messages can be used to perform control and monitoring that cannot be achieved using the IN and OUT Areas alone, by sending explicit messages to the K3HB-DRT Digital Indicator.	Explicit Message Communications

#### Note

- (1) When changing the baud rate of the master after starting the K3HB-DRT Digital Indicator, turn ON the communications power supply of the Digital Indicator again, and restart the Digital Indicator. When setting the Configurator only, without a master, the baud rate of the Configurator will be automatically detected.
- (2) The following points are important when editing device parameters using the Configurator.
  - It is recommended that device default values are uploaded before the parameters are edited because the EDS parameter defaults and the device defaults are different.
  - The setting for some parameters are different for the list of settings provided in the CompoWay/F SECTION 2 List of Settings. For example, the parameter setting for input type A is different for each model.
  - Set the unit number in the Communications Setting Level parameter group to change the node address.

## 2-1-3 Setting Node Addresses



DeviceNet node addresses are set in the communications setting level. Set the node addresses on the front panel of the K3HB-DRT.

Parameter	Setting value	Meaning
Unit No. ป-กอั	0 to 99	0 to 99 (See note.)

**Note** The node address will be 0 if an address between 64 and 99 is set.

#### Setting Parameters



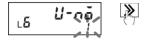
A. Press the LEVEL Key for at least 3 s to move to the input initial setting level.

• The initial setting level is indicated by L0 being displayed in the level/bank display.



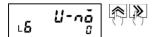
B. Press the LEVEL Key several times to move to the communications setting level.

• The communications setting level is indicated by L6 being displayed in the level/bank display.



C. Press the SHIFT Key so that the SV display flashes.

The SV will flash to indicate that it can be changed.



D. Press the UP and SHIFT Keys to change the Unit No. (DeviceNet node address) setting.

The number of words allocated will depend on the K3HB-DRT communications data allocations. The following points are important when setting node addresses or allocating I/O memory.

- Do not allocate the same words to other slaves.
- Make sure the I/O area does not exceed the valid range.

## 2-2 Functions Supported Only by the K3HB-DRT

A Configurator is used to make settings for the network power monitor function and Unit conduction time monitor function.

## 2-2-1 Network Power Monitor Function

The K3HB-DRT has a network power monitor function that turns ON the Communications Power Voltage Monitor Error Flag in the General Status when the communications power voltage drops below the set monitor value. The monitor value for the network power voltage is set using the Configurator and is found in the General Setting parameter group.

## 2-2-2 Unit Conduction Time Monitor Function

The K3HB-DRT has a Unit conduction time monitor function that records internally the total time communications power is supplied to the Digital Indicator. The Unit Maintenance Flag in the General Status will turn ON if the Unit conduction time exceeds a set monitor value.

The Detection Time (Unit conduction time monitor value) is set using a Configurator and is found in the General Setting parameter group.

The Unit conduction time monitor can be used as a guide for replacing the K3HB-DRT Digital Indicator.

Measurement unit: 0.1 h

Measurement range: 0 to 429496729.5 h (Stored data: 00000000 to FFFFFFF hex).

Note

- (1) The conduction time is held even when the power is turned OFF.
- (2) The conduction time will not be measured if communications power is not supplied to the K3HB-DRT.
- (3) The K3HB-DRT Digital Indicator checks the ON status of the target channel approximately every 0.1 h (6 min).

# Parts, Install tion, and Wiri

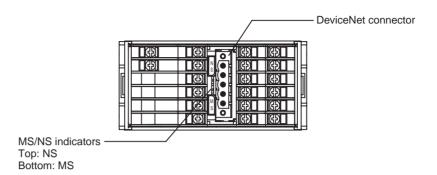
## **SECTION 3 Parts, Installation, and Wiring**

This section describes the methods used to install and wire K3HB-DRT Digital Indicators.

3-1	Part Names and Functions				
	3-1-1	Part Names	5-2		
	3-1-2	External Dimensions	5-2		
	3-1-3	MS and NS Indicators	5-3		
3-2	Device	Net Communications Cables Wiring	5-4		
	3-2-1	Preparing DeviceNet Communications Cables	5-4		
	3-2-2	Attaching the DeviceNet Communications Unit Connector	5-6		

## 3-1 Part Names and Functions

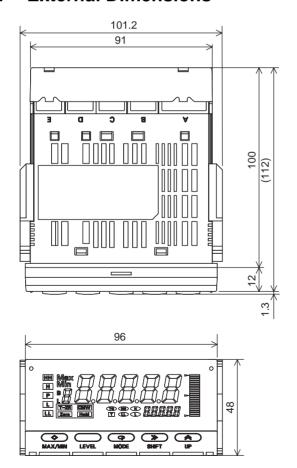
## 3-1-1 Part Names

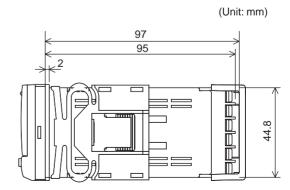


DeviceNet Communications Connector

The DeviceNet communications connector is used to connect the communications cable to the DeviceNet network. The DeviceNet communications power is also supplied through this connector. The connector provided with the Digital Indicator is a HR31-5.08P-5SC(01) (Hirose Electric). The provided connector crimp terminals are HR31-SC-121 (Hirose Electric) and are for Thin DeviceNet Communications Cables. The K3HB-DRT cannot be used with any other connector than the DeviceNet one provided.

## 3-1-2 External Dimensions





## 3-1-3 MS and NS Indicators

The indicators show the status of the Digital Indicator and the DeviceNet Network.

Indicator	Name	Color	Status	Meaning (main errors)
MS	Module status	Green	MS	The Digital Indicator is normal.
		Red	MS	Fatal error  • Digital Indicator error  • Watchdog timer error (DeviceNet communications)
			MS	Non-fatal error  • Unit error  • Unit changed  • Display Unit error  • Non-volatile memory error.
		OFF	MS	No power is being supplied.  • DeviceNet communications power is not being supplied.  • Power is not being supplied to the Digital Indicator.  • The Digital Indicator is being reset.  • Waiting for initialization to start.
NS	Network status	Green	NS	Online/communications established (normal network status)
			NS	Online/communications established (waiting for communications to be established with the master)
		Red	NS	Fatal communications error (The Digital Indicator has detected an error that does not allow communications with the network.)
				<ul><li>Node address duplication error</li><li>Bus Off error detected</li></ul>
			NS	Non-fatal communications error  • Communications timeout
		OFF	NS	Offline or power supply is OFF  Waiting for completion of the master's node address duplication check.  DeviceNet communications power is not being supplied.



**Normal Indicator Display** 

The MS and NS indicators are both lit green when the status of the Digital Indicator and the Network are normal.

## 3-2 DeviceNet Communications Cables Wiring

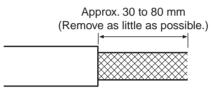
The methods used for preparing DeviceNet communications cables to be connected for DeviceNet communications are explained here.

For details on the DeviceNet Network, such as supplying the DeviceNet communications power and grounding the DeviceNet Network, refer to the DeviceNet Operation Manual (W267).

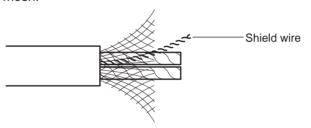
## 3-2-1 Preparing DeviceNet Communications Cables

Use the following procedure to prepare and connect the communications cables to the connectors.

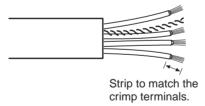
Remove approximately 30 to 80 mm of the cable covering, being careful not to damage the shield mesh underneath. Do not remove too much covering or a short circuit may result.



2. Carefully peel back the shield mesh to reveal the signal lines, power lines, and the shield wire. The shield wire is slightly harder to the touch than the mesh.



 Remove the exposed mesh and the aluminum tape from the signal and power lines. Strip the covering from the signal and power lines to the proper length for the crimp terminals. Twist together the wires of each of the signal and power lines.



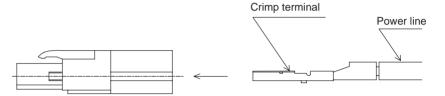
4. Attach crimp terminals to the lines and then cover any exposed areas with vinyl tape or heat-shrink tubing.

Making sure that the connector hole numbers are correct, insert each of the signal lines, power supply lines, and the shield wire into the corresponding connector holes, as shown in the following diagram.



- 1: V- (Power line: black)
- 2: CAN low (Communications line: blue)
- 3: Shield
- 4: CAN high (Communications line: white)
- 5: V+ (Power line: red)

Make sure that the connector is oriented correctly before inserting the crimp terminal into the connector, as shown in the following diagram.

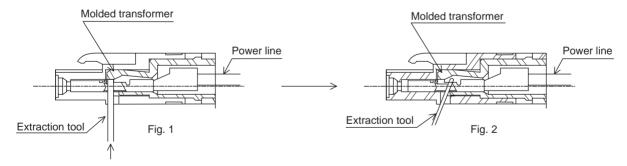


The crimp terminals can be crimped using a crimp tool that conforms to JIS C9711. The following crimp tool is also available:

HR31-TC-01 (Hirose Electric)

If wiring is not correct, use an extraction tool to extract the wires using the following procedure.

- **1,2,3...** 1. Press down the molded transformer using the extraction tool, as shown in Fig. 1.
  - 2. While keeping the molded transformer pressed down, tilt the extraction tool to release the crimp terminal lock.
  - 3. Remove the extraction tool.
  - 4. Pull the cable and pull out the crimp terminal.

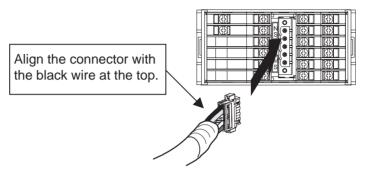


The following extraction tool is available: HR31-SC-TP (Hirose Electric)

## 3-2-2 Attaching the DeviceNet Communications Unit Connector

Align the DeviceNet Communications Unit connector (marked with a C) with the cable connector, and insert the cable connector fully into the DeviceNet Communications Unit connector.

Tighten the set screws to a torque between 0.18 and 0.22 N⋅m to secure the connector.



Use the following crimp terminals if using Thick DeviceNet Communications Cables.

HR31-SC-111 (Hirose Electric)

## **SECTION 4 Remote I/O Communications**

This section describes the input (IN) areas and output (OUT) areas that K3HB-DRT Digital Indicators can use for remote I/O communications. The methods to allocate data for master communications are also described using sample programming.

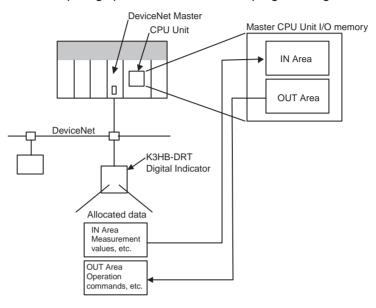
4-1	Overvi	ew	6-2	
4-2	I/O All	I/O Allocation		
	4-2-1	Allocation Area Sizes (IN Data Sise and OUT Data Size)	6-3	
	4-2-2	Allocation Parameters	6-3	
	4-2-3	Allocation Default Values	6-4	
	4-2-4	Allocation Settings	6-4	
	4-2-5	Input Data	6-5	
	4-2-6	Output Data	6-5	
	4-2-7	Operation Commands	6-6	
4-3	Ladder	Programming Examples	6-7	
	4-3-1	Zero Execute/Cancel Sample Programming	6-7	

Overview Section 4-1

### 4-1 Overview

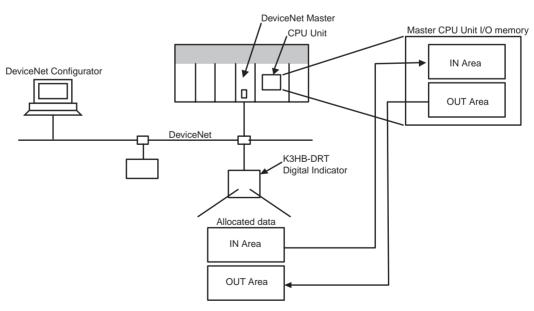
I/O memory in the master can be allocated to data from the K3HB-DRT Digital Indicator, such as data from the Digital Indicator's variable area, merely by specifying what Digital Indicator data is to be transferred to where.

Data is automatically exchanged between the master and Digital Indicator, allowing the Digital Indicator to be controlled and monitored from the master without requiring special communications programming.



# 4-2 I/O Allocation

The Configurator can be used to select any data from the list of allocation parameters for the Digital Indicator and then allocate the data in a user-set destination.



### 4-2-1 Allocation Area Sizes (IN Data Sise and OUT Data Size)

The size of allocated data in each of the IN and OUT Areas is shown in the following table.

I/O memory	Words	Bytes	Setting		
			Allocated data size: 2 bytes size: 4 bytes		
IN Area	0 to 60	0 to 120	30	30	
OUT Area	0 to 29	0 to 58	15	15	

Note

- (1) When the master is a CS/CJ-series DeviceNet Unit, the IN Area can be divided into two areas (IN Area 1 and IN Area 2). Any allocation data from the list of parameters can be allocated in each area.
- (2) The actual size of the allocated area depends on the size of allocation data selected.
- (3) The default allocation data size is two bytes.

When the allocation data size is two bytes, the monitor and setting data will be displayed in the range FFFF hex to 0000 hex. Data will be fixed at 7FFF hex or 8000 hex if the data exceeds the range that can be displayed. For example, —32769 would be displayed as 8000 hex.

The following data sizes are fixed, however.

- General status: 2 bytes (fixed)
- K3HB-DRT status: 4 bytes (fixed)
- K3HB-DRT Output Enable Bits and operation commands: 2 bytes (fixed)

Note

Refer to 4-2-5 Input Data on page 6-5 for details on General Status. Refer to 4-2-6 Output Data on page 6-5 for details on Output Enable Bits and operation commands.

#### 4-2-2 Allocation Parameters

The parameters that can be allocated are shown below. These parameters can be broadly classified as K3HB-DRT status bits/operation commands, and K3HB-DRT operation data and setting data.

1. K3HB-DRT Status Bits/Operation Commands
The status bits and operation commands for the K3HB-DRT Digital Indicator are shown in the following table.

For status details, refer to the CompoWay/F SECTION 2 List of Settings.

Read	Write	ltem
Yes	No	General status
No	Yes	Operation commands

Note

- (1) When items that are write-only are allocated in the IN Area, they are always set to 0.
- (2) When items that are read-only are allocated in the OUT Area, they are allocated words in memory but operate the same as if they had not been allocated.

#### 2. K3HB-DRT Operation Data and Setting Data

Monitor values and setting data with communications addresses that belong to the following variable types can be allocated. Duplicate settings are possible and are processed in ascending order.

Variable type			
C0 Operation monitor data			
C2	RUN level		

**Note** If items are allocated in the read-only area of the OUT Area, words are allocated in memory but operate as if they had not been allocated.

3. Output Enable Bits

Output Enable Bits are allocated in the first word of the OUT Area. When Output Enable Bits are allocated in the IN Area, they are always set to 0 (OFF).

**Note** If data allocated to the IN or OUT Area is changed, use a software reset or cycle the power to enable the new settings.

### 4-2-3 Allocation Default Values

The default values for I/O allocations are listed in the following table.

Area	ltem		
IN Area	Measurement value		
OUT Area	Output Enable Bits		
	Operation commands		

# 4-2-4 Allocation Settings

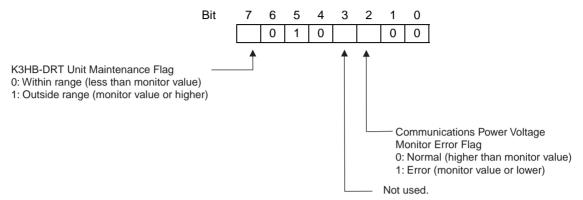
The I/O allocation settings are listed in the following table.

Allocated to IN Area	Allocated to OUT Area	Configurator display	Item		
No	Yes	<b>-1</b>	Output Enable Bits (Always 2 bytes)		
No	Yes	Operation command	Operation command		
No	Yes	Generic status	General status		
Yes	No	Status	Status (Always 4 bytes)		
Yes	No	Measurement value	Measurement value		
Yes	No	Maximum value	MAX value		
Yes	No	Minimum value	MIN value		
Yes	Yes Yes Comparative set value HH (5)		Comparative set value HH		
Yes	Yes	Comparative set value H (4)	Comparative set value H		
Yes	Yes	Comparative set value L (2)	Comparative set value L		
Yes	Yes	Comparative set value LL (1)	Comparative set value LL		

### 4-2-5 Input Data

The input data specific to Digital Indicators with DeviceNet communications that is not allocated in the variable area of the K3HB-DRT is described here.

#### **General Status**



- The Communications Power Voltage Monitor Error Flag indicates the status of the power being supplied through the DeviceNet communications cable.
- The Unit Maintenance Flag is set to 1 when the Unit conduction time of the K3HB-DRT Digital Indicator exceeds the monitor value.

### 4-2-6 Output Data

Output data specific to DeviceNet that is not allocated to the K3HB-DRT variable area is described here.

#### **Output Enable Bits**

Output Enable Bits are used when settings are written to the OUT Area, e.g., when comparative set values are set or RUN/STOP is executed using operation commands. The area for Output Enable Bits is always allocated in the first word of the OUT Area.

When Output Enable Bits are set to 0 (OFF), the settings and bits set in the OUT Area are not transmitted and, therefore, nothing is executed. The settings can be executed by setting the Output Enable Bits to 1 (ON). Writing is not executed if the Output Enable Bits are not set to 1.

Setting Output Enable Bits prevents unintentional setting changes and enables various settings in the OUT Area to be enabled simultaneously. For example, a new value may written to a word for which a SP has already been set. If the Output Enable Bits are set to 1 and then set to 0, no SP will be written even if one is accidentally allocated. (However, care must be taken because writing is enabled if Output Enable Bits are set to 1.)

Furthermore, if set values are written for all the words and the Output Enable Bits are set to 1, the set values will all be enabled at once.

Note

When Output Enable Bits are set to 1, data allocated to the OUT Area is written whenever it changes.

### 4-2-7 Operation Commands

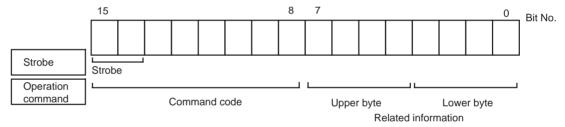
Operation commands are used to for software resetting, to move to setting area 1, and other similar operations. As shown in the following table, operation commands are executed using a combination of command codes, related information, and strobes.

Operation commands for the K3HB-DRT are shown in the following table.

Command code	Details	Related information		
00	Communications write	00: OFF (Read only)		
		01: ON (Read/write)		
01	Reset	00		
02	Bank selection	00 to 07: Bank 0 to bank 7		
03	Zero execute/cancel	00: Zero cancel		
		01: Zero execute		
06	Software reset	00		
07	Move to Setting Area 1	00		
08	Move to protect level	00		
0B	Initialize setting	00		

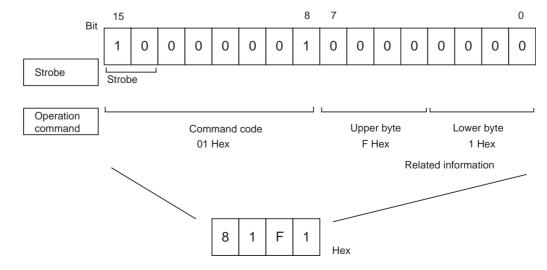
**Note** A software reset will not respond (no service PDU response).

Operation commands are created as shown in the following diagram.



Bit 15 is strobe 2 and bit 14 is strobe 1. A logical OR is taken between the two leftmost bits of the command code and bits 15 and 14, and the result is attached as the strobe to the operation command. The command code for K3HB-DRT operation commands is  $0\Box$  hex, so when the logical OR is  $8\Box$  hex, the strobe is ON.

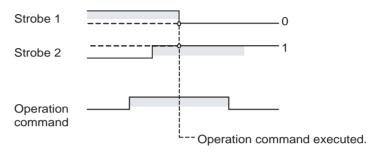
Resetting with an operation command is used for the following example.



With the CS1W-DRM21 and CJ1W-DRM21 DeviceNet Units, operation commands are made ready for execution by writing to the allocated words (CIO 3202 when the default I/O allocation (fixed allocation area 1) is set.)

Operation commands are executed only when the Output Enable Bit is set to 1 (ON) and the strobe is ON. The strobe is ON when the following two conditions are met:

- 1. Strobe 2 = 1 and strobe 1 = 0
- The strobe was cleared after the previous operation command was executed.



Note

Software resets are executed again even if the strobe has not been cleared. Therefore the Output Enable Bit or the strobe must be cleared after the software reset command has been sent.

# 4-3 Ladder Programming Examples

## 4-3-1 Zero Execute/Cancel Sample Programming

The zero execute/cancel ladder programming example here is executed under the following conditions.

 Using default I/O allocations to allocate data in fixed allocation area 1 of a CS/CJ-series DeviceNet Unit (OUT Area = CIO 3200 to CIO 3263, IN Area = CIO 3300 to CIO 3363).

This ladder programming example executes zero execute and zero cancel for the K3HB-DRT. Zero execute and zero cancel are executed using operation commands.

Output Enable Bit (CIO 320100) and strobe are used to execute the operation command.

- First, the Output Enable Bit is turned ON. The hexadecimal values are set to D1000 and D1001 at the start of the ladder program. These values prepare the zero cancel operation command 0300 hex and the zero execute
- Zero cancel is executed when CIO 000000 turns ON.

operation command 0301 hex.

- The contents of D1000 (= 0300 hex) is copied to CIO 3202, where the operation command is allocated.
- The strobe is turned ON (strobe 1 = 0 and strobe 2 = 1) and the operation command is executed.
- A timer is used and the strobe is disabled to 1 after 0.1 s (see note).
- Zero execute is executed in the same way as for zero cancel when CIO 000100 turns ON.

Outline

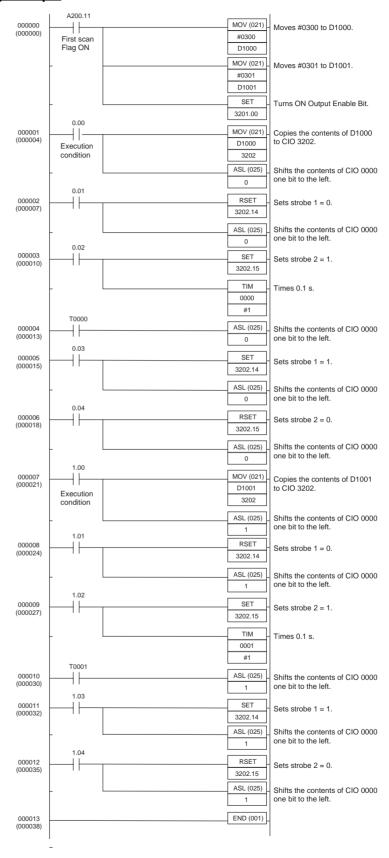
Operation

Note

When using this type of ladder programming, do not use the timer method used in this example. Instead, allocate the status and confirm that the value has changed and then disable the strobe, specifically:

- a. Allocate status in the IN Area using the Configurator.
- b. Execute operation commands and use the status to confirm that the status has been cleared to zero and then disable the strobe.

#### **■** Programming Example



# **SECTION 5 Explicit Message Communications**

This section describes how to send explicit messages to the K3HB-DRT Digital Indicator, including how to send CompoWay/F commands using explicit messages.

5-1	Overvi	ew of Explicit Message Communications	7-2
	5-1-1	Explicit Message Communications	7-2
	5-1-2	Explicit Message Types	7-2
	5-1-3	Explicit Messages Basic Format	7-3
5-2	Sendin	g CompoWay/F Commands to the Digital Indicator	7-4
	5-2-1	CompoWay/F Binary Commands	7-5
	5-2-2	CompoWay/F ASCII Commands	7-5
5-3	Explici	t Messages Specific to DeviceNet-compatible Digital Indicators	7-6
	5-3-1	Reading General Status	7-7
	5-3-2	Writing Maintenance Mode Data	7-7
	5-3-3	Setting and Monitoring the Digital Indicator Words	7-7

# 5-1 Overview of Explicit Message Communications

### 5-1-1 Explicit Message Communications

Explicit message communications is a communications protocol for sending commands from the master as explicit messages, and receiving explicit messages as responses from the nodes that receive the commands.

Explicit messages can be sent from the master to the Digital Indicator to read and write the K3HB-DRT Digital Indicator variable area, send operation commands, and read and write various other DeviceNet functions supported by the Digital Indicator.

Explicit message communications can be used to send and receive data that is not allocated in the IN and OUT Areas due to word size restrictions, and data that does not require the frequent refreshing used by the IN Area and OUT Area.

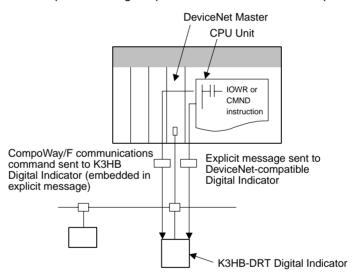
Use either of the following two methods depending on the application.

#### Reading/Writing K3HB-DRT Variable Area Data and Sending Operation Commands

Send CompoWay/F communications commands to K3HB-DRT Digital Indicators by embedding them in explicit messages.

#### Reading/Writing K3HB-DRT Maintenance Information

Send explicit messages specific to the DeviceNet-compatible Digital Indicator.



# 5-1-2 Explicit Message Types

The explicit messages sent to the Digital Indicator can be divided into two types: messages in which CompoWay/F commands are embedded and messages specific to DeviceNet-compatible Digital Indicators.

#### Sending CompoWay/F Commands to the K3HB-DRT (Embedded in Explicit Messages)

The master can send CompoWay/F communications commands to the K3HB-DRT Digital Indicator by sending them as explicit message data.

When DeviceNet-compatible Digital Indicators are used, the explicit messages are automatically converted to CompoWay/F communications commands and sent to the K3HB-DRT Digital Indicator. The responses from the Digital Indicator are converted into explicit messages and returned to the master. CompoWay/F commands are used to read from and write to the K3HB-DRT variable area and to execute operation commands.

CompoWay/F commands consist of binary commands and ASCII commands.

#### **■** CompoWay/F Binary Commands

CompoWay/F binary commands are CompoWay/F communications commands expressed in hexadecimal, and are easy to execute from ladder programs. CompoWay/F communications commands that include ASCII data, however, cannot be sent or received. Therefore, Read Controller Attribute (05 03) and broadcasting (unit number = XX) cannot be used.

#### **■** CompoWay/F ASCII Commands

CompoWay/F ASCII commands are CompoWay/F communications commands expressed in ASCII, so numerical values must be converted to ASCII when executing these commands from a ladder program. CompoWay/F binary commands cannot be used. Broadcasting (unit number = XX) cannot be used, but all other CompoWay/F communications commands can be sent and received, including Read Controller Attribute (05 03), which cannot be used with CompoWay/F binary commands.

#### Sending Explicit Messages Specific to DeviceNet-compatible Digital Indicators

The master can send explicit messages to a DeviceNet-compatible Digital Indicator to control various operations supported only by DeviceNet-compatible Digital Indicators and to read DeviceNet-specific settings and status information.

These explicit messages are used to read and write maintenance information specific to DeviceNet-compatible Digital Indicators.

### 5-1-3 Explicit Messages Basic Format

The basic formats of explicit message commands and responses are described here.

#### Command Block

Destination node address Service code Class	D Instance ID	Attribute ID	Data
---	---------------	--------------	------

#### **Destination Node Address**

This parameter specifies the node address of the Controller to which the explicit messages (commands) will be sent in single-byte (2-digit) hexadecimal.

#### Service Code, Class ID, Instance ID, Attribute ID

These parameters specify the command type, processing target, and processing details.

The Attribute ID does not need to be specified for some commands.

#### Data

Specifies the details of the commands, set values, etc. The data section is not required for read commands.

#### **Response Block**

The following format is used when a normal response is returned for the sent explicit message.

No. of bytes	Source node	Service code	Data
received	address		

The following format is used when an error response is returned for the sent explicit message.

No. of bytes received 0004 hex, fixed	Source node address	Service code	Error code (2 bytes, fixed)
---	---------------------	--------------	--------------------------------

#### **Number of Bytes Received**

The number of data bytes received from the source node address is returned as a hexadecimal. When an error response is returned for the explicit message, the contents is always 0004 hex.

#### **Source Node Address**

The node address of the master that sent the explicit message is returned as a hexadecimal.

#### **Service Code**

For normal responses, the service code specified in the command turns with the most significant bit (bit 07) turned ON is returned. (For example, when the service code of the command is 0E hex, the service code of the response will be 8E hex.) When an error response is returned for the explicit message, the service code is always 94 hex.

#### **Data**

Read data is included in the response only when a read command is executed. There is no data for commands that do not read data.

#### **Error Code**

The following table shows the error codes for explicit messages.

Error code	Error name	Cause		
08FF	Service not supported	The service code is incorrect.		
09FF	Invalid Attribute value	The Attribute Value is not supported.		
16FF	Object does not exist	The Instance ID is not supported.		
15FF	Too much data	The data string is too long.		
13FF	Not enough data	The data string is too short.		
14FF	Attribute not supported	The Attribute ID is not supported.		
0CFF	Object state conflict	The command cannot be executed.		
0EFF	Attribute not settable	A write service code was sent for a read-only Attribute ID.		
20**	Invalid Parameter	There is an error in the specified parameter.		

# 5-2 Sending CompoWay/F Commands to the Digital Indicator

The master can send CompoWay/F command frames to the K3HB-DRT Digital Indicator by embedding them in explicit message commands, and receive CompoWay/F response frames that are embedded in explicit messages responses.

The following services, however, cannot be used.

- Monitor value/set data composite registration read
- Monitor value/set data composite read registration (write)
- Monitor value/set data composite read registration confirmation (read)

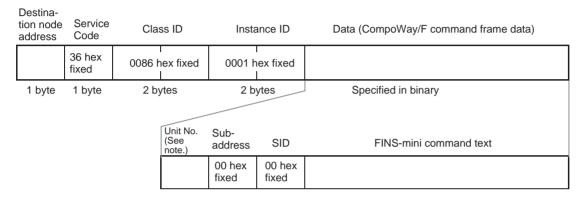
# 5-2-1 CompoWay/F Binary Commands

CompoWay/F binary commands use hexadecimal values for the CompoWay/F frames, and not ASCII. Therefore, the data volume is about half of CompoWay/F ASCII commands. The following restrictions apply.

 Read Controller Attribute (05 03), which includes ASCII in the Compo-Way/F frame, cannot be used.

The following command and response formats are used when executing CompoWay/F binary commands from an OMRON Master.

#### **Command Block**

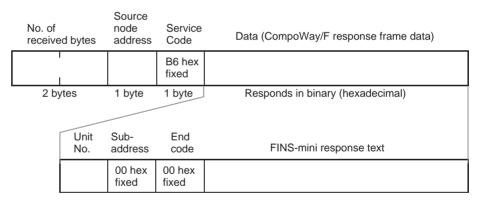


Note

Specify the same value as the destination node address. Broadcasting cannot be specified.

#### Response Block

#### **Normal Response**

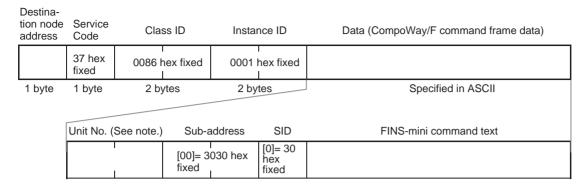


# 5-2-2 CompoWay/F ASCII Commands

When CompoWay/F ASCII commands are used, the CompoWay/F frames are expressed in ASCII (each digit in a specified numerical value is also converted to ASCII, so 52 is specified as ASCII 3532).

The following command and response formats are used when the commands are executed from an OMRON Master Unit.

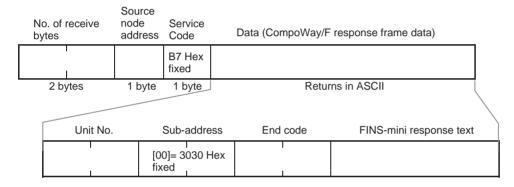
#### **Command Block**



**Note** Specify the same value as the destination node address. Broadcasting cannot be specified.

#### **Response Block**

#### Normal Response



# 5-3 Explicit Messages Specific to DeviceNet-compatible Digital Indicators

The following list shows explicit messages that can be sent to K3HB-DRT Digital Indicators. These messages are used to read and write maintenance information (such as Unit conduction time) for the DeviceNet-compatible Digital Indicator.

For details on sending explicit messages from an OMRON Master PLC, refer to the DeviceNet Master Unit operation manual.

**Note** The number of digits used for the Class ID, Instance ID, and Attribute ID depends on the master used. When sending parameters from an OMRON Master Unit, the values are expressed as follows:

Class ID: 4-digit (2-byte) hexadecimal Instance ID: 4-digit (2-byte) hexadecimal Attribute ID: 2-digit (1-byte) hexadecimal

# 5-3-1 Reading General Status

Explicit	Read/					Response		
message	write		Service code	Class ID	Instance ID	Attribute ID	Data size	
General Status Read	Read	Reads the DeviceNet-compatible Digital Indicator's general status bits (8 bits). (Refer to page 6-5).	0E hex	95 hex	01 hex	65 hex		1 byte

# 5-3-2 Writing Maintenance Mode Data

Explicit	Read/	Function Command				Response		
message	write		Service code	Class ID	Instance ID	Attribute ID	Data size	
Mainte- nance Counter Save	Save	Records the maintenance counter (PV of Unit conduction time for all Digital Indicators) in memory.	16 hex	95 hex	01 hex	75 hex		

# 5-3-3 Setting and Monitoring the Digital Indicator Words

Explicit	Read/	Function			Comma	and		Response
message	write		Service code	Class ID	Instance ID	Attribute ID	Data size	
Set Value for Unit Conduction Time	Read	Reads the set value (monitor value) for the Unit conduction time (unit: 0.1 h (6 min)).	0E hex	7A hex	01 hex	68 hex		4 bytes 00000000 to FFFFFFF hex (0 to 4294967295)
	Write	Writes the set value (monitor value) for the Unit conduction time (unit:0.1 h (6 min)).	10 hex	7A hex	01 hex	68 hex	4 bytes 00000000 to FFFFFFF hex (0 to 429496729 5)	
Unit Con- duction Time Read	Read	Reads the PV for the Unit conduction time (unit: 0.1 h (6 min)).	0E hex	7A hex	01 hex	66 hex		4 bytes 00000000 to FFFFFFF hex (0 to 4294967295)
Monitor Status of Unit Con- duction Time Read	Read	Reads the monitor status for the Unit conduction time.	0E hex	7A hex	01 hex	67 hex		1 byte 00 hex: Within range 01 hex: Out of range (moni- tor value exceeded)

# **SECTION 6 Communications Performance**

This section provides information on the time required for a complete communications cycle, for an output response to be made to an input, to start the system, and to send messages.

6-1	Remote	e I/O Communications Performance	8-2
	6-1-1	I/O Response Time	8-2
	6-1-2	Communications Cycle time and Refresh Processing Time	8-3
	6-1-3	Networks with More Than One Master	8-4
6-2	Messag	ge Communications Performance	8-6
	6-2-1	Message Communications Time.	8-6

### 6-1 Remote I/O Communications Performance

The performance of remote I/O communications between an OMRON Master Unit and OMRON Slave is described in this section. Use this information for reference with precise timing is required.

The following conditions are assumed in the calculations provided in this section.

- The Master Unit is operating with the scan list enabled.
- All required slaves are participating in communications.
- · No error has occurred in the Master Unit.
- No messages are being sent on the network by Configurators or other devices from other manufacturers.

Note

The calculations given in the section may not be accurate if a master from another manufacturer is used or if slaves from other manufacturers are used on the same network.

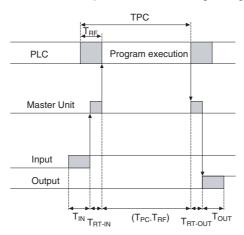
### 6-1-1 I/O Response Time

The I/O response time is the time required from when the master is notified of an input on an input slave until an output is made on an output slave (including ladder diagram processing in the PLC).

CS/CJ-series, C200HX/HG/HE (-Z), and C200HS PLCs

#### Minimum I/O Response Time

The minimum I/O response time occurs when the slave I/O refresh is performed immediately after the input is received by the master and the output is sent to the output slave at the beginning of the next I/O refresh.



T<sub>IN</sub>: ON/OFF delay time of the input slave (0 used as minimum value)
 T<sub>OUT</sub>: ON/OFF delay time of the output slave (0 used as minimum value)

 $T_{RT-IN}$ : Communications time for one slave for input slaves  $T_{RT-OUT}$ : Communications time for one slave for output slaves

T<sub>PC</sub>: Cycle time of PLC

T<sub>RF</sub>: DeviceNet Unit refresh time at PLC

Note

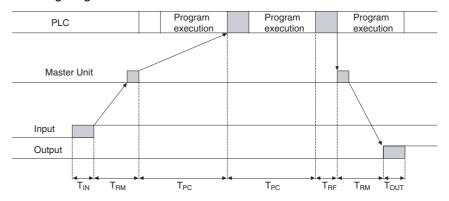
Refer to the operation manuals for the slaves for the input slave ON/OFF delay times and the output slave ON/OFF delay times. Refer to 6-1-2 Communications Cycle time and Refresh Processing Time and to the operation manual for the PLC for the PLC cycle time.

The minimum I/O refresh time can be calculated as follows:

$$T_{MIN} = T_{IN} + T_{RT-IN} + (T_{PC} - T_{RF}) + T_{RT-OUT} + T_{OUT}$$

#### **Maximum I/O Response Time**

The maximum I/O response time occurs under the conditions shown in the following diagram.



T<sub>IN</sub>: ON/OFF delay time of the input slave (0 used as minimum value)

T<sub>OUT</sub>: ON/OFF delay time of the output slave (0 used as minimum value)

T<sub>RM</sub>: Communications time for entire network

T<sub>PC</sub>: Cycle time of PLC

T<sub>RF</sub>: DeviceNet Unit refresh time at PLC

Note

Refer to the operation manuals for the slaves for the input slave ON/OFF delay times and the output slave ON/OFF delay times. Refer to 6-1-2 Communications Cycle time and Refresh Processing Time and to the operation manual for the PLC for the PLC cycle time.

The maximum I/O refresh time can be calculated as follows:

 $T_{MAX} = T_{IN} + 2 \times T_{RM} + 2 \times T_{PC} + T_{RF} + T_{OUT}$ 

# 6-1-2 Communications Cycle time and Refresh Processing Time

This section describes the communications cycle time and refresh processing time, which are required to calculate various processing times for DeviceNet.

#### **Communications Cycle Time**

The communications cycle time is the time from the completion of a slave's I/O communications processing until I/O communications with the same slave are processed again. The communications cycle time is the maximum communications cycle time  $T_{\text{IN}} + T_{\text{OUT}}$ .

The equations used to calculate the communications cycle time are described here.

#### **Communications Cycle Time Equations**

Total communications cycle time = IN communications cycle time + OUT communications cycle time.

#### ■ IN Communications Cycle Time

IN communications cycle time =  $(39 \text{ ms} + 8 \text{ ms x number of allocated data}) + (6 \text{ ms} \times \text{total allocated words in IN Areas 1 and 2})$ 

#### **■ OUT Communications Cycle Time**

OUT communications cycle time =  $(29 \text{ ms} + 27 \text{ ms x number of allocated data}) + (7 \text{ ms} \times \text{total allocated words in OUT Areas 1 and 2})$ 

# Refresh Processing Time

The refresh processing time is the time required for the CPU Unit of the PLC and the DeviceNet Master Unit to pass I/O information back and forth. The cycle time of the PLC is affected as described below when a DeviceNet Unit is mounted.

#### Note

Refer to the operation manuals for the PLCs for details on the refresh processing time and the PLC's cycle time.

#### CS/CJ-series, C200HX/HG/HE (-Z), and C200HS PLCs

The following times for I/O refreshing are added to the cycle time of the PLC when a Master Unit is mounted.

Item	Processing time
I/O refresh	DeviceNet Unit I/O Refresh Processing
	CS/CJ-series or C200HX/HG/HE (-Z) PLCs 1.72 + 0.022 x number of allocated words (see note) ms
	C200HS PLCs 2.27 + 0.077 x number of allocated words (see note) ms

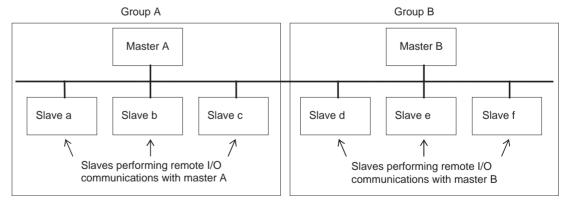
#### Note

The number of allocated words is the total number of I/O area words allocated to all of the slaves. Any unused areas within the allocations must be included. For example, if only node address 1 with a 1-word input and node address 5 with a 1-word input are connected, the total number of words would be 5. When message communications are performed, the number of words required for message communications would have to be added to the above total number of words during the cycles in which message communications are processed.

#### 6-1-3 Networks with More Than One Master

The communications cycle time,  $T_{RM}$ , when there is more than one master in the same network is described in this section. Here, a network with two masters is used as an example.

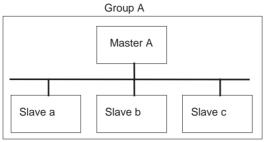
First, separate the network into two groups, slaves that perform remote I/O communications with master A and those that perform remote I/O communications with master B.

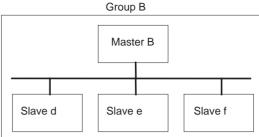


Note

Although for convenience, the slave are positioned in groups with the masters, in the actual network, the physical positions of the slaves will not necessarily be related to the master with which they communicate.

Next, calculate the communications cycle time for each group referring to 6-1-2 Communications Cycle time and Refresh Processing Time.





Group A communications cycle time: T<sub>RM-A</sub>

Group A communications cycle time: T<sub>RM-B</sub>

The communications cycle time for the overall network when there are two masters will be as follows:

$$T_{RM} = T_{RM-A} + T_{RM-B}$$

Although this example uses a network with only two masters, the same method can be used for any number of masters. Simply divide the network up according to remote I/O communications groups and then add all of the communications cycle times for the individual groups to calculate the communications cycle time for the overall network.

#### **System Startup Time**

This section describes the system startup time for a Network, assuming that the scan list is enabled and that remote I/O communications are set to start automatically at startup. The system startup time is the delay from the time that the Master Unit is turned ON or restarted until the time remote I/O communications begin.

The system startup time when the Master Unit is set to start up immediately after power supplies of all the slaves are turned ON is different from when the Master Unit is restarted while communications are in progress. The startup times are shown in the following table.

Condition	Slave's indicator status	System startup time
The master is started immediately after slave startup.	NS indicator is OFF or flashing green.	6 s
The master only is restarted.	NS indicator is flashing red while the master is OFF.	8 s
The slaves only are restarted.		10 s

Note

### **Sample Program**

The times described above are required for the DeviceNet system to start. The sample program in this section shows how to use the Master Slave Status to skip slave I/O processing until remote I/O communications have started.

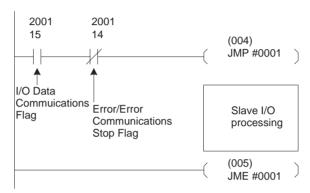
Refer to the operation manual for the Master Unit for information on the Mas-

ter Status Area.

The following conditions apply to this sample program.

PLC: CS1 Series

Master Unit's unit number: 00



# 6-2 Message Communications Performance

# 6-2-1 Message Communications Time

The message communications time is the time required from when the Master Unit starts to send a message on the network until the entire message has been sent when a message is being sent from one node to another. The message will consist of data for a SEND or RECV instruction and a FINS command for an IOWR or CMND instruction.

Note

If another message is sent before the message communications time elapses or is a message is received from another node before the message communications time elapses, the response message being sent or the message being received may be corrupted. When performing message communications it is thus necessary to allow the message communications time to elapse before performing message communications again using SEND, RECV, CMND, or IOWR instructions and to allow the message communications time to elapse between sending messages to the same node. If a send or receive message is corrupted, a record will be stored in the error log in the Master Unit. Use a FINS command to read the error record or use the Configurator to monitor the error log.

The message communications time can be estimated using the following equation:

Message communications time = Communications cycle time x  $\{(number of message bytes + 15) \div 6 + 1\}$ 

The number of message bytes in the number of bytes after the FINS command code. The communications cycle time will depend on whether remote I/O communications is being used and can be calculated as described next.

Only Message
Communications
(Remote I/O
Communications
Stopped)

Communications cycle time = 2 (see note) + 0.11 x TB + 0.6 ms

TB depends on the baud range as follows: 500 KB/s: 2, 250 KB/s: 4, 125 KB/s: 8

Note

The communications cycle time when remote I/O communications are

stopped is 2 ms.

Message
Communications and
Remote I/O
Communications

communications + 0.11 x TB + 0.6 ms

TB depends on the baud range as follows: 500 KB/s: 2, 250 KB/s: 4, 125 KB/s: 8

Note

The above calculations for the message communications times are only for use as guidelines. They do not produce maximum values. The message communications time depends on the frequency of messages, the load on the remote node, the communications cycle time, etc. If network traffic is concentrated on one Master Unit, long times will be required that those produced by the above calculations. Be sure to consider this when designing the system.

# **SECTION 7 Troubleshooting and Maintenance**

This section describes error processing, periodic maintenance operations, and troubleshooting procedures needed to keep the DeviceNet Network operating properly. Details on resetting replaced Digital Indicators are also provided. Read through the error processing procedures in both this manual and the operation manual for the DeviceNet master being used before operation so that operating errors can be identified and corrected more quickly.

7-1	Indicat	ors and Error Processing	9-2
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	7-2-1	Cleaning	9-3
	7-2-2	Inspection	9-3
	7-2-3	Replacing Digital Indicators	9-4

# 7-1 Indicators and Error Processing

The following table lists the indicator status when errors occur, the probable causes and processing.

Indicator status	Probable cause	Remedy
MS: OFF NS: OFF	The power is not being supplied to the Digital Indicator.	Supply communications power from the DeviceNet connector.
	The power voltage is not within the permitted range.	Use a power supply voltage within the permitted range.
	The Digital Indicator is faulty.	Replace the Digital Indicator.
MS: Flashing red NS: No change	A checksum error has occurred in the parameters registered in EEPROM.	Repairs are required if this error persists even if the parameters are reset. Contact your nearest OMRON representative.
	A EEPROM hardware error has occurred.	
MS: ON red NS: OFF	The Digital Indicator is faulty.	Repairs are required. Contact your nearest OMRON representative.
MS: ON green NS: Flashing green	Waiting to connect to DeviceNet communica-	Check the following items and restart the Digital Indicator.
	tions.	<ul> <li>Are lengths of cables (trunk and branch lines) correct?</li> <li>Are cables short-circuited, broken, or loose?</li> </ul>
		Are cables wired correctly?
		• Is terminating resistance connected to both ends of the trunk line only?
		• Is noise interference excessive?
	The Digital Indicator is	• Is the power to the master ON?
	The Digital Indicator is faulty.	Repairs are required. Contact your nearest OMRON representative.
MS: ON green NS: ON red	The DeviceNet is in Bus Off status.	Check the following items and restart the Digital Indicator.
		Are lengths of cables (trunk and branch lines) correct?
		Are cables short-circuited, broken, or loose?
		• Is terminating resistance connected to both ends of the trunk line only?
	Nada addusas a dust	• Is noise interference excessive?
	Node addresses duplicated.	Reset node addresses correctly.
	The Digital Indicator is faulty.	Repairs are required. Contact your nearest OMRON representative.
MS: ON green NS: Flashing red	A communications timeout has occurred.	Check the following items and restart the Digital Indicator.
		Are lengths of cables (trunk and branch lines) correct?
		Are cables short-circuited, broken, or loose?
		<ul> <li>Is terminating resistance connected to both ends of the trunk line only?</li> <li>Is noise interference excessive?</li> </ul>
	The Digital Indicator is faulty.	Repairs are required. Contact your nearest OMRON representative.

Maintenance Section 7-2

### 7-2 Maintenance

This section describes the routine cleaning and inspection recommended as regular maintenance. Handling methods when replacing Digital Indicators are also explained here.

# 7-2-1 Cleaning

Clean the Digital Indicators regularly as described below in order to keep the Network in its optimal operating condition.

- Wipe the Digital Indicator with a dry, soft cloth for regular cleaning.
- When dust or dirt cannot be removed with a dry cloth, dampen the cloth with a neutral cleanser (2%), wring out the cloth, and wipe the Digital Indicator.
- Smudges may remain on the Digital Indicator from gum, vinyl, or tape that was left on for a long time. Remove these smudges when cleaning.

**Note** Never use volatile solvents, such as paint thinner or benzene, or chemical wipes to clean the Digital Indicator. These substances may damage the surface of the Digital Indicator.

## 7-2-2 Inspection

Inspect the system periodically to keep it in its optimal operating condition.

In general, inspect the system once every 6 to 12 months, but inspect more frequently if the system is used in high-temperature, humid, or dusty conditions.

### **Inspection Equipment**

Prepare the following equipment before inspecting the system.

**Equipment Required for Regular Inspection** 

A flat-blade and a Phillips screwdriver, a screwdriver for connecting communications connectors, a tester (or a digital voltmeter), industrial alcohol, and a clean cloth are required for routine inspection.

Other Equipment that May Be Required

A synchroscope, oscilloscope, thermometer, or hygrometer may be required.

### <u>Inspection Procedure</u>

Check the items in the following table and correct any condition that is below standard by adjusting the Digital Indicator or improving the environmental conditions.

Inspection item	Details	Standard	Equipment
Environmental conditions	Are ambient and cabinet temperatures correct?	−10 to +55°C	Thermometer
	Are ambient and cabinet humidity correct?	25% to 85%	Hygrometer
	Has dust or dirt accumulated?	No dust or dirt	Visual inspection
Installation conditions	Are the connectors of the communications cables fully inserted?	No looseness	Phillips screwdriver
	Are the external wiring screws tight?	No looseness	Phillips screwdriver
	Are the connecting cables undamaged?	No external damage	Visual inspection

Maintenance Section 7-2

# 7-2-3 Replacing Digital Indicators

The Network consists of the DeviceNet Master Unit and Slave Units. The entire network is affected when a Unit is faulty, so a faulty Unit must be repaired or replaced quickly. We recommend having spare Units available to restore Network operation as quickly as possible.

#### **Precautions**

Observe the following precautions when replacing a faulty Digital Indicator.

- After replacement make sure that there are no errors with the new Digital Indicator.
- When a Digital Indicator is being returned for repair, attach a sheet of paper detailing the problem and return the Digital Indicator to your OMRON dealer.
- If there is a faulty contact, try wiping the contact with a clean, lint-free cloth dampened with alcohol.

**Note** Before replacing a Digital Indicator, always stop Network communications and turn OFF the power to all the nodes in the Network.

# dditional Informa ion for DeviceNet

# **SECTION 8 Additional Information for DeviceNet**

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8-2	Mounted Objects	10-3
8-3	DeviceNet Connection Hardware	10-7
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# Additional Information

# 8-1 Detailed DeviceNet Specifications

# **Data Size and Connection Types**

If the connection type can be set when another company's configurator is being used, select a connection supported by the DeviceNet Communications Unit.

The following table shows the connection types and data sizes for OMRON DeviceNet Communications Units.

Model	Supported connections				Data size (bytes)	
	Poll	Bit strobe	Change of state (COS)	Cyclic	IN	OUT
K3HB-DRT	Yes	Yes	Yes	Yes	1 to 120 (See note.)	1 to 58 (See note.)

Note The size of the IN/OUT Areas depends on the setting.

DeviceNet I/O communications support the following types of connections.

Connection type	Details	Remarks
Poll	Used to exchange data between the master and individual slaves by sending and receiving commands and responses. (Output data is allocated for commands and input data is allocated for responses).	
Bit strobe	Used to broadcast commands from the master and receive input responses from multiple slaves.	By using one command only, the communications cycle time is short, but bit strobe connections can be used only with slaves with 8 or less input points.
Change of state (COS)	Normally, input and output data are sent by master and slaves at regular cycles, but with a COS connection, data is sent to the master or slave when the master or slave data changes.	By setting a long cycle interval, the Network will not be loaded with communications for minor data changes, thereby improving the overall effi- ciency of the Network.
Cyclic	Masters and slaves send output or input data at regular cycles.	

### **Device Profiles**

The following device profiles contain more detailed DeviceNet specifications for DeviceNet communications if more information needs to be registered in the scan list.

General data	Compatible DeviceNet Specifications	Volume I - Release 2.0		
		Volume II - Release 2.0		
	Vendor name	OMRON Corporation	Vendor ID = 47	
	Device profile name	Slaves: Generic Device	Profile number = 0	
	Manufacturer catalog number	N129		
	Manufacturer revision	1.01		
Physical conformance	Network current consumption	50 mA max.		
data	Connector type	Open plug		
	Physical layer insulation	No		
	Supported indicators	Module, Network		
	MAC ID setting	Software switch		
	Default MAC ID	1		
	Baud rate setting	Automatic recognition		
	Supported baud rates	125 kbps, 250 kbps, and	500 kbps	
Communications data	Predefined Master/Slave connection set	Group 2 only server		
	Dynamic connection support (UCMM)	No		
	Explicit message fragmentation support	Yes		

# 8-2 Mounted Objects

# **Identity Object (0x01)**

Object class	Attribute	Not supported
	Service	Not supported

Object	Attribute	ID	Contents	Get (read)	Set (write)	Value	
instance		1	Vendor	No	No	47	
		2	Device type	Yes	No	0	
		3	Product code	Yes	No	505	
		4	Revision	Yes	No	1.1	
		5	Status (bits supported)	Yes	No	Bit 00 only	
		6	Serial number	Yes	No	Unique for each Unit	
		7	Product name	Yes	No	K3HB-DRT	
		8	State	No	No		
	Service		DeviceNet service	Parameter option			
		05	Reset	No			
		0E	Get_Attribute_Single	No			

# **Message Router Object (0x02)**

Object class	Attribute	Not supported
	Service	Not supported
Object instance	Attribute	Not supported
	Service	Not supported
Vendor specifica- tion addition		None

# **DeviceNet Object (0x03)**

Object class	Attribute	Not supported
	Service	Not supported

Object	Attribute	ID Contents		Get (read)	Set (write)	Value
instance		1	MAC ID	No	No	
	2		Baud rate	Yes	No	
		3	BOI	Yes	No	00 (hexadecimal)
		4	Bus Off counter	No	No	
		5	Allocation information	Yes	No	
	Service		DeviceNet service		Parameter option	on
		0E	Get_Attribute_Single	None		
		4B	Allocate_Master/ Slave_Connection_Set	None		
		4C	Release_Master/ Slave_Connection_Set	None		

# **Assembly Object (0x04)**

Object class	Attribute	Not supported
	Service	Not supported

Object instance	Attribute	ID	Contents	Get (read)	Set (write)	Value
100: IN Area 1		1	Number of members in list	No	No	
101: IN Area 2		2	Member list	No	No	
110: OUT Area 1		3	Data	Yes	No	
	Service		DeviceNet service		Parameter option	
		0E	Get_Attribute_Single	None		

# **Connection Object (0x05)**

Object class	Attribute	Not supported
	Service	Not supported
	Maximum number of active connections	1

Object	Section		Information	Max	ximum number	of instances
nstance 1	Instance type	Explicit Message		1		
	Production trigger	Cyclic				
-	Transport type	Server				
	Transport class	3				
	Attribute	ID	Contents	Get (read)	Set (write)	Value
		1	State	Yes	No	
		2	Instance type	Yes	No	00 (hexadecimal)
		3	Transport class trigger	Yes	No	83 (hexadecimal)
		4	Produced connection ID	Yes	No	
		5	Consumed connection ID	Yes	No	
		6	Initial comm. characteristics	Yes	No	21 (hexadecimal)
		7	Produced connection size	Yes	No	0176 (hexadecimal)
		8	Consumed connection size	Yes	No	
		9	Expected packet rate	Yes	Yes	01 (hexadecimal)
		12	Watchdog time-out action	Yes	No	01 (hexadecimal)
		13	Produced connection path length	Yes	No	00 (hexadecimal)
		14	Produced connection path	Yes	No	
		15	Consumed connection path	Yes	No	00 (hexadecimal)
	Service		DeviceNet service	Parameter option		
		05	Reset	None		
		0E	Get_Attribute_Single	None		
		10	Set_Attribute_Single	None		

Object	Section		Information	Max	ximum number	of instances
instance 2	Instance type	Polled	I/O	1		
	Production trigger	Cyclic				
	Transport type	Server				
	Transport class	2				
	Attribute	ID	Contents	Get (read)	Set (write)	Value
		1	State	Yes	No	
		2	Instance type	Yes	No	01 (hexadecimal)
		3	Transport class trigger	Yes	No	82 (hexadecimal)
		4	Produced connection ID	Yes	No	
		5	Consumed connection ID	Yes	No	
		6	Initial comm. characteristics	Yes	No	01 (hexadecimal)
		7	Produced connection size	Yes	No	
		8	Consumed connection size	Yes	No	
		9	Expected packet rate	Yes	Yes	
		12	Watchdog time-out action	Yes	No	00 (hexadecimal)
		13	Produced connection path length	Yes	No	06 (hexadecimal)
		14	Produced connection path	Yes	No	See note 1.
		15	Consumed connection path length			06 (hexadecimal)
		16	Consumed connection path	Yes	No	See note 2.
		17	Production inhibit time	Yes	No	0000 (hexadecimal)
	Service		DeviceNet service		Parameter of	ption
		05	Reset	None		
		0E	Get_Attribute_Single	None		
		10	Set_Attribute_Single	None		

1. Produced Connection Paths

IN Area 1: 20\_04\_24\_64\_30\_03 IN Area 2: 20\_04\_24\_65\_30\_03

2. Consumed Connection Paths OUT Area: 20\_04\_24\_6E\_30\_03

Object	Section		Information	Max	imum numbe	r of instances	
instance 4	Instance type	COS C	Cyclic	1			
	Production trigger	Cyclic					
	Transport type	Server					
	Transport class	2					
	Attribute	ID	Contents	Get (read)	Set (write)	Value	
		1	State	Yes	No		
		2	Instance type	Yes	No	01 (hexadecimal)	
		3	Transport class trigger	Yes	No	12 (hexadecimal)	
		4	Produced connection ID	Yes	No		
		5	Consumed connection ID	Yes	No		
		6	Initial comm. characteristics	Yes	No	01 (hexadecimal)	
		7	Produced connection size	Yes	No		
		8	Consumed connection size	Yes	No	0800 (hexadecimal)	
		9	Expected packet rate	Yes	Yes		
		12	Watchdog time-out action	Yes	No	00 (hexadecimal)	
		13	Produced connection path length	Yes	No	06 (hexadecimal)	
		14	Produced connection path	Yes	No	See note.	
		15	Consumed connection path length			04 (hexadecimal)	
		16	Consumed connection path	Yes	No	202B2401	
		17	Production inhibit time	Yes	Yes	0000 (hexadecimal)	
	Service		DeviceNet service		Parameter option		
		05	Reset	None			
		0E	Get_Attribute_Single	None			
		10	Set_Attribute_Single	None			

Note Produced Connection Paths

IN Area 1: 20\_04\_24\_64\_30\_03 IN Area 2: 20\_04\_24\_65\_30\_03

# 8-3 DeviceNet Connection Hardware

# **DeviceNet Communications Cables**

Model	Specifications	Manufacturer
DCA1-5C10	Thin Cable: 5 wires, 100 m	OMRON
DVN24-10G	Thin Cable: 5 wires, 10 m	Nihon Wire & Cable (See note 1.)
DVN24-30G	Thin Cable: 5 wires, 30 m	Nihon Wire & Cable (See note 1.)
DVN24-50G	Thin Cable: 5 wires, 50 m	Nihon Wire & Cable (See note 1.)
DVN24-100G	Thin Cable: 5 wires, 100 m	Nihon Wire & Cable (See note 1.)
DVN24-300G	Thin Cable: 5 wires, 300 m	Nihon Wire & Cable (See note 1.)

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Model	Specifications	Manufacturer
DVN24-500G	Thin Cable: 5 wires, 500 m	Nihon Wire & Cable (See note 1.)
1485C-P1-C150	Thin Cable: 5 wires, 150 m	Allen-Bradley (See note 2.)
DCA1-5CN□□W1	Cable with shielded micro-size (M12) connectors on both ends (female socket and male plug)	OMRON
	Cable length: 0.5 m, 1 m, 2 m, 3 m, 5 m, and 10 m	
DCA1-5CN□□F1	Cable with shielded micro-size (M12) connector (female socket) on one end	OMRON
	Cable length: 0.5 m, 1 m, 2 m, 3 m, 5 m, and 10 m	
DCA1-5CN□□H1	Cable with shielded micro-size (M12) connector (male plug) on one end	OMRON
	Cable length: 0.5 m, 1 m, 2 m, 3 m, 5 m, and 10 m	
DCA1-5CN□□W5	Cable with shielded connector on both ends (male plug on mini-size end, female socket on micro-size end)	OMRON
	Cable length: 1 m, 2 m, 5 m, and 10 m	

#### Note

- 1. The product specifications of these cables are identical to the OMRON cable specifications.
- 2. The cables made by Allen-Bradley are stiffer than the cables made by OM-RON and Nihon Wire & Cable Company Ltd., so do not bend the Allen-Bradley cables as much as the others.

Other DeviceNet communications cables are available from the following manufacturers. For details, refer to the product catalogs on the ODVA web site (http://www.odva.astem.or.jp/) or contact the manufacturer directly.

### **DeviceNet Connector**

Model	Specifications	Manufacturer
HR31-5.08P-5SC (01)	For node connection	Hirose Electric
	Includes connector set screws	

# **Crimp Terminals for DeviceNet Communications Cables**

Model	Manufacturer
HR31-SC-121: For Thin Cables	Hirose Electric
HR31-SC-111: For Thick Cables	

# **Terminating Resistors for DeviceNet Network**

Model	Specifications	Manufacturer
DRS1-T	Terminal-block Terminating Resistor, 121 $\Omega$ ±1% 1/4 W	OMRON
DRS2-1	Shielded Terminating Resistor (male plug), micro-size (M12)	
DRS2-2	Shielded Terminating Resistor (female socket), micro-size (M12)	
DRS3-1	Shielded Terminating Resistor (male plug), mini-size	

A Terminating Resistor can also be connected to a T-branch Tap or a one-branch Power Supply Tap.

# Additional Information for DeviceNe

# **T-branch Taps**

# **One-branch Taps**

Model	Specifications	Manufacturer
DCN1-1C	Includes three XW4B-05C1-H1-D parallel connectors with screws (When used on a trunk line, one branch line can be connected.)	OMRON
	Connector insertion direction: Horizontal	
	A Terminating Resistor (included as standard) can be connected.	
DCN1-2C	Includes three XW4B-05C1-H1-D parallel connectors with screws (When used on a trunk line, one branch line can be connected.)	OMRON
	Connector insertion direction: Vertical	
	A Terminating Resistor (included as standard) can be connected.	
DCN1-2R	Includes three XW4B-05C1-VIR-D orthogonal connectors with screws (When used on a trunk line, one branch line can be connected.)	OMRON
	Connector insertion direction: Vertical	
	A Terminating Resistor (included as standard) can be connected.	

# **Three-branch Taps**

Model	Specifications	Manufacturer
DCN1-3C	Includes five XW4B-05C1-H1-D parallel connectors with screws (When used on a trunk line, three branch lines can be connected.)	OMRON
	Connector insertion direction: Horizontal	
	A Terminating Resistor (included as standard) can be connected.	
DCN1-4C	Includes five XW4B-05C1-H1-D parallel connectors with screws (When used on a trunk line, three branch lines can be connected.)	OMRON
	Connector insertion direction: Vertical	
	A Terminating Resistor (included as standard) can be connected.	
DCN1-4R	Includes five XW4B-05C1-VIR-D orthogonal connectors with screws	OMRON
	(When used on a trunk line, three branch lines can be connected.)	
	Connector insertion direction: Vertical	
	A Terminating Resistor (included as standard) can be connected.	

# **Shielded T-branch Connectors**

Model	Specifications	Manufacturer
DCN2-1	One-branch shielded T-branch connectors, three micro-size (M12) connectors	OMRON
DCN3-11	One-branch shielded T-branch connectors, three mini-size connectors	
DCN3-12	One-branch shielded T-branch connectors, two mini-size connectors and one micro-size (M12) connector	

# **One-branch Power Supply Tap**

Model	Specifications	Manufacturer
DCN1-1P	One-branch tap for power supply. Use this tap when connecting a communications power supply.  Includes two XW4B-05C1-H1-D parallel connectors with screws and two fuses as standard.	OMRON
	A Terminating Resistor (included as standard) can be connected.	

# 8-4 Glossary

The following table provides a list of commonly used DeviceNet terms.

Term	Explanation
Bus OFF	Indicates that the error rate in the network is extremely high. Errors are detected when a fixed threshold is exceeded by the internal error counter. (the internal error counter is cleared when the Master Unit is started or restarted.)
CAN	CAN is short for Controller Area Network. It is a communications protocol developed as a LAN for use in automobiles. DeviceNet employs CAN technology.
Configurator	A device for setting the system settings. The Configurator can read ID information, read and write parameters, and display the network configuration.
	OMRON's DeviceNet Configurator is designed for use with an OMRON Master Unit.
Consumed Connection Size	Indicates the data size (byte length) received via the connection.
ODVA	ODVA is short for Open DeviceNet Vendor Association, Inc. It is a non-profit organization formed by machine vendors with the aim to administer and popularize the DeviceNet specification.
Produced Connection Size	Indicates the data size (byte length) sent via the connection.
Connection	This is a logical communication channel for facilitating communications between nodes. Communications are maintained and managed between the master and slaves.
Device Profile	Standardizes the configuration and behavior (the smallest data configuration and operation that must be supported by the device) of devices of the same type (equipment, etc.). Provides mutual exchangeability between devices of the same type. Also known as a device model. Devices for which device profiles are currently being investigated include sensors, valves, display units, and encoders.
Master/Slave	A node can be either a master, which collects and distributes data, or a slave, which outputs and inputs data according to the instructions received from the master. OMRON's DeviceNet products are already provided with either master or slave functions in a predefined master/slave connection set.

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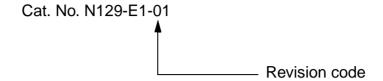
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# **Revision History**

A manual revision code appears as a suffix to the catalog number on the front cover of the manual.



The following table outlines the changes made to the manual during each revision. Page numbers refer to the previous version.

Revision code	Date	Revised content	
01	February 2004	Original production	